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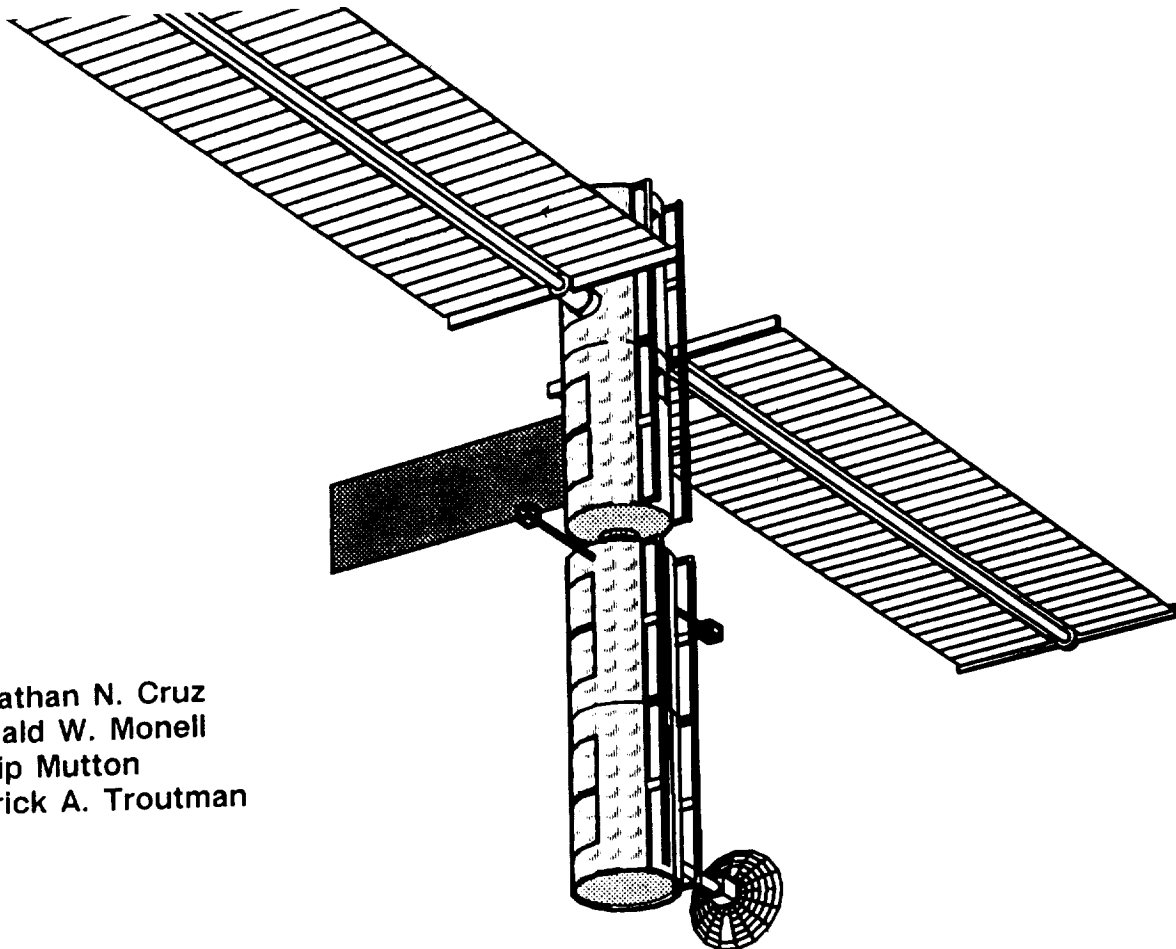
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Pre-Integrated Structures for Space Station Freedom

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Table of Contents

Introduction	1
Pre-integrated Truss Structural Description	7
Packaging and Mechanisms	35
Packaging options	37
Station assembly mechanisms and attachment methods	49
Subsystem mounting concepts	67
Structural Analysis	115
Thermal Analysis	137
Integrated Assembly	161
Summary and Recommendations	271
Acknowledgments	274

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Introduction

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Introduction

The assembly of Space Station Freedom has always presented a significant challenge to its design engineers. Never before had a spacecraft the size of Freedom been required to be delivered to orbit in such a comparably small launch vehicle (the space shuttle). This size difference dictated numerous shuttle launches and on-orbit assembly. In 1986, one half of Freedom's transverse boom along with a pressurized node was manifested on the shuttle as the first assembly flight. This included 18.75 KW of power, ten bays of erectable five meter truss and its assembly equipment, RCS and fuel, full communications and avionics. By the time the program reached the PDR stage in 1990, the items manifested on the first assembly flight were reduced to one 18.75 Kw PV unit, a few bays of truss and associated assembly devices.

The reduction of station hardware on the first assembly flight is due to many factors. Shuttle performance decreases, station system and support hardware mass increases, a more conservative understanding of shuttle packaging and C.G. constraints, increases in flight support equipment (FSE) and large increases in EVA estimates have made it increasingly difficult to launch and assemble the station with a limited number of shuttle flights. At PDR it took four shuttle flights to launch and assemble what was manifested on the first flight in 1986. The prime benefit on an erectable space structure - the ability to construct a large spacecraft from a small launch package - was no longer being realized for Freedom assembly.

The shuttle with its 60 foot cargo bay is capable of delivering to orbit long pre-integrated sections of truss using only a limited amount of FSE since there would be only one large cargo element in the cargo bay. Based on length alone, three shuttle flights can bring up one half of the transverse boom in pre-integrated sections with the added benefits of ground integration, ground verification and a substantial reduction in EVA as compared to using erectable truss. In July of 1990 the LaRC Space Station Freedom Office (SSFO) began to study the technical feasibility of using pre-integrated structure in the assembly of Freedom with the objective being to maximize ground integration and minimize on-orbit integration/verification functions. The concept was based on utilizing an isogrid tube as part of the pre-integrated structure. The feasibility of the structural concept was evaluated with respect to system/structural interfaces, dynamic and thermal loads, assembly manifesting/operations and station orbital characteristics.

Ground Rules/Assumptions

The study was based on a given isogrid form which is described in the following section, "Pre-integrated Truss Structural Description." Baseline data were used for the subsystems definitions (number, size, etc. of ORU's) and the STS launch capability. Weights used for manifesting were provided by Level II to be more compatible with the current design status, and a margin of 15% was added to allow for uncertainties.

Ground Rules/Assumptions

- Erectable truss replaced with isogrid tube structure with 22-inch node spacing
- Assume baseline STS capability
- Baseline subsystems requirements will not change
- Utilize Level II –provided weights
 - add 15% structural margin

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Pre-Integrated Truss Structural Descriptions

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Isogrid Structural Features

Isogrid is a lattice of stiffening ribs which intersect to form an array of equilateral triangles. This arrangement creates a structure which exhibits isotropic behavior and has a Poisson's ratio of $1/3$. This design is efficient in carrying compression and bending loads, acting similar to a beam-column.

There are several advantages to using isogrid in structural applications. It is easily analyzed by virtue of its isotropic behavior. The method of manufacturing isogrid allows for optimization for a wide range of loading intensities. Isogrid provides a standard pattern (every 22 inches in this case) for attachment. These attachment nodes allow for a wide variety of equipment to be mounted to the structure with minimum impact to the basic isogrid structure. The method of manufacturing and the attachment nodes allow for reinforcement at concentrated load points and around cutouts. Isogrid also provides redundant load paths.

Isogrid Structural Features

- A lattice of intersecting ribs forming an array of equilateral triangles
- **Characteristics:**
 - Isotropic (no directions of instability or weakness)
 - Efficient in compression and bending
- **Advantages:**
 - Easily analyzed
 - Can be optimized for wide range of loading intensities
 - Standard pattern for attachment (nodes accommodate equipment mounting without change)
 - Readily reinforced for concentrated loads and cutouts
 - Redundant load paths

Integrated Structure Dimension Drivers

The length and diameter of the isogrid structure were driven by numerous factors. The orbiter imposes the most requirements that impact the structure's dimensions. A length of 44 feet was chosen to provide sufficient clearance between the isogrid structure, the aft bulkhead camera and the orbiter to station docking module. This length also allowed the structure to stay within the orbiter C.G. constraints and lift capability. Increasing the length of the structure would improve overall assembly efficiency by reducing the total number of flights. This may require exceeding some orbiter constraints and thus was not considered for this feasibility study. The diameter of the isogrid truss was also driven by orbiter packaging requirements. A maximum diameter of 14.5 feet is allowed in the orbiter bay. A slightly diameter (13.3 feet) was chosen for the isogrid structure so that some external packaging of elements (mobile transporter rails, berthing mechanisms, etc.) was possible.

Integrated Structure Dimension Drivers

Length – Transverse boom clearances, number of assembly flights, orbiter C.G. constraints, orbiter clearances, RMS reach limits, packaging requirements, EVA access and weight.

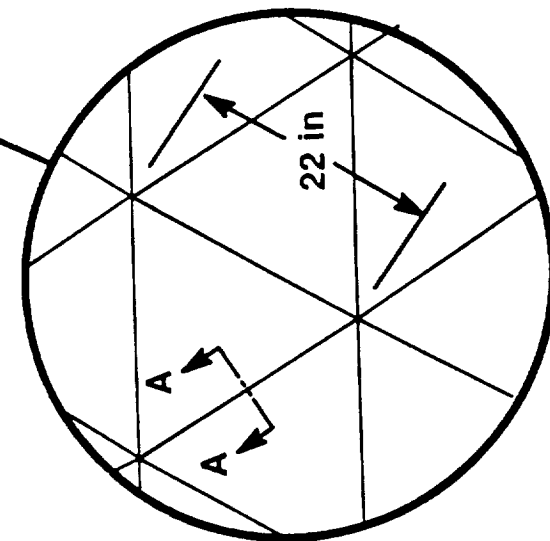
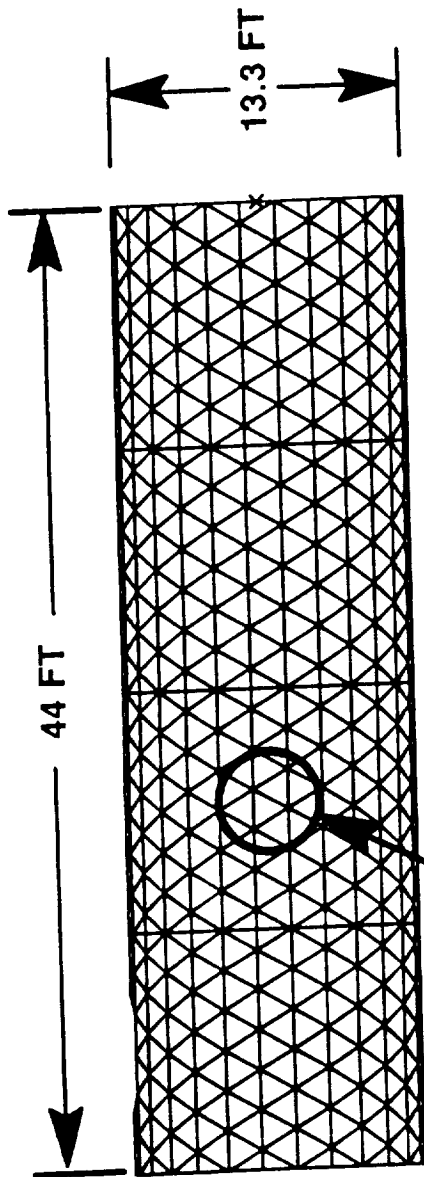
Diameter – Orbiter clearances, internal vs external packaging of some elements, EVA access and weight.

Isogrid Configuration

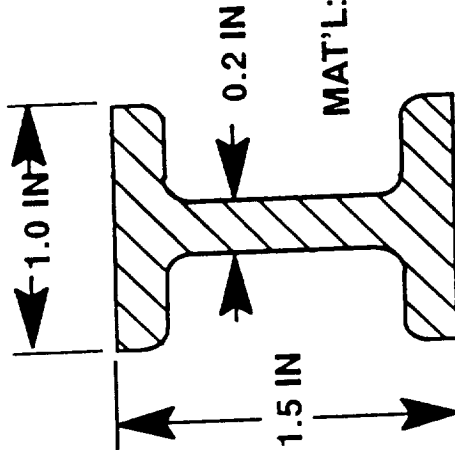
The cylindrical structure is constructed in the form of an aluminum isogrid, which is fabricated by using several machined segments welded together along the longeron members. Each grid has a dimension of 22 inches between adjacent nodes.

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Isogrid Configuration



CLOSEUP VIEW OF ISOGRID



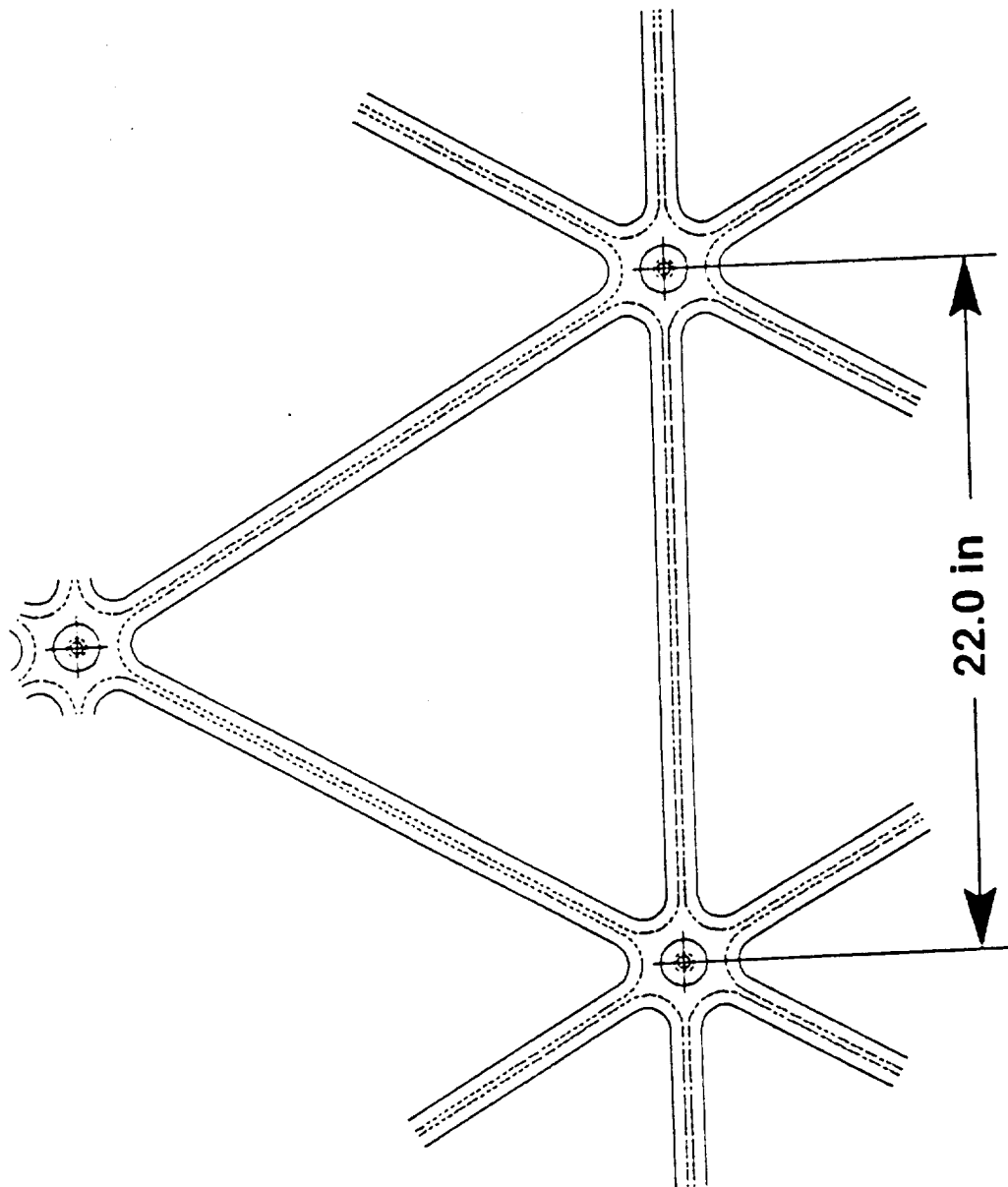
SECTION A-A

Typical Segment of Isogrid

In a single segment of isogrid the structure can be seen to be very open, hence its light weight. The incorporation of attachment points at each node provides flexibility for the location of system hardware, and shielding materials.



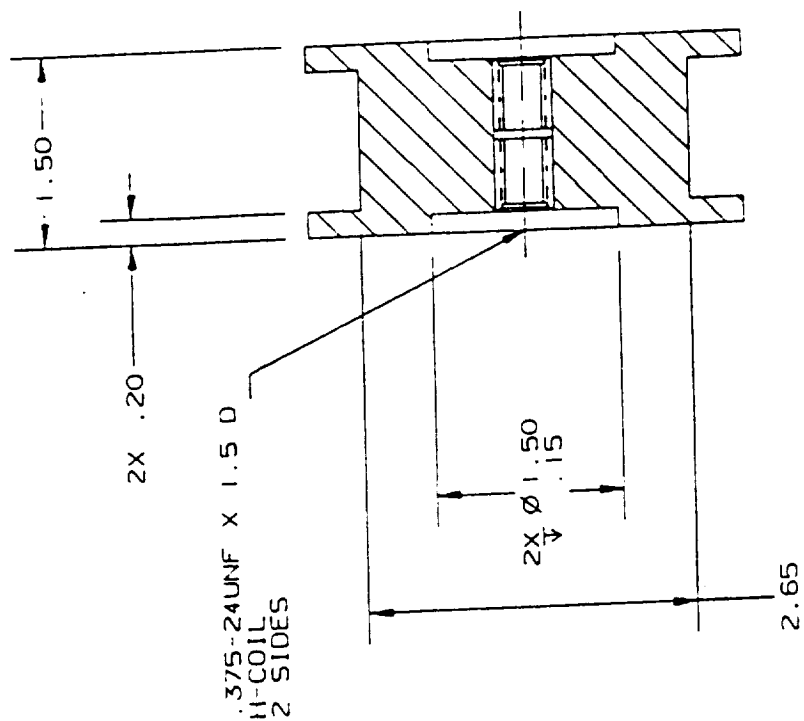
Typical Segment of Isogrid



Isogrid Node With Insert(s)

At each node, a threaded insert facilitates attachment of subsystems, utilities, payloads, etc., on either the inside or the outside of the structure. Extremely flexible as systems change or grow.

Isogrid Node With Inserts



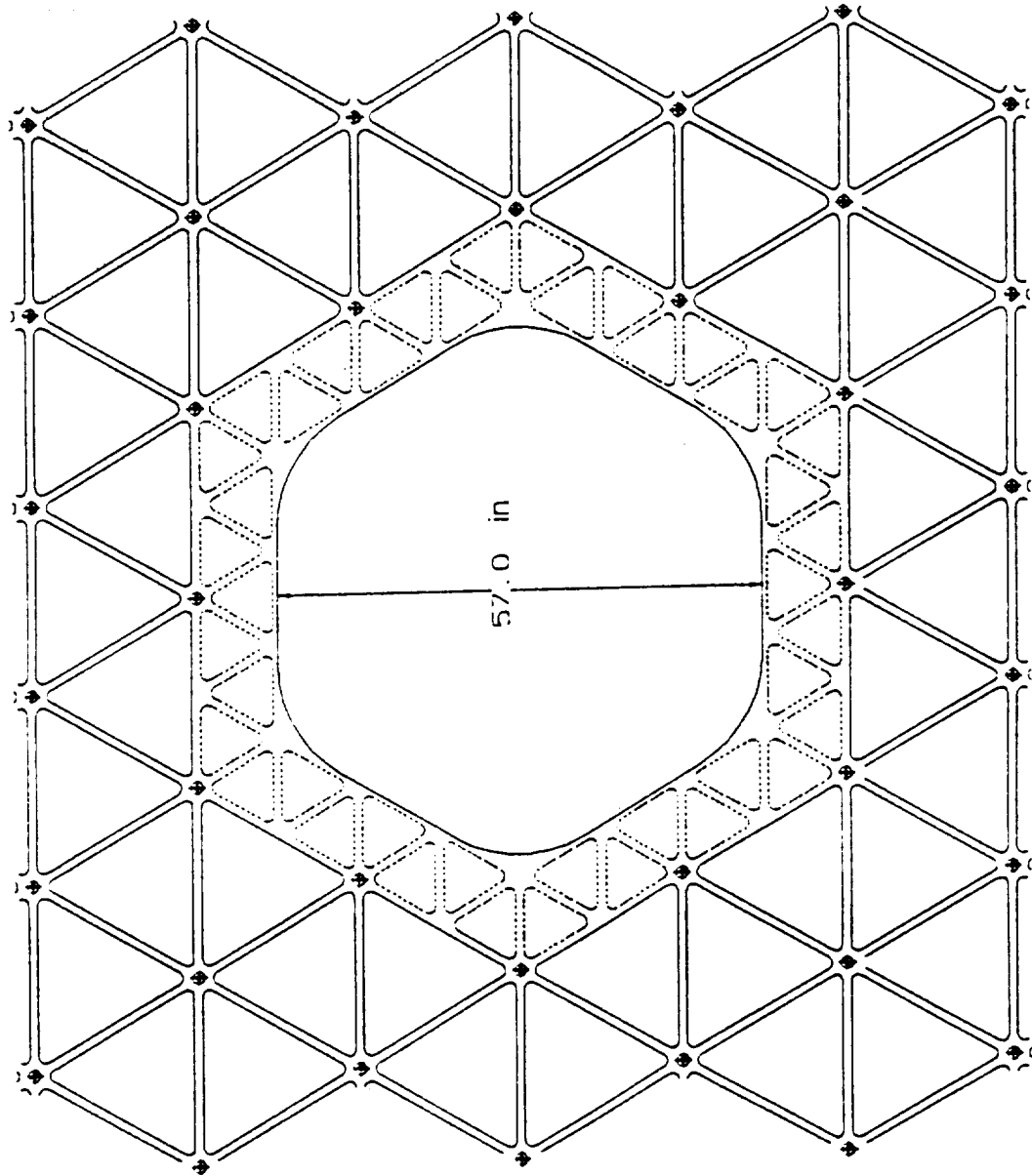
EVA Access Hole

The access apertures required for EVA and other automated maintenance activities may be reinforced by using longerons on each side of the hole, and/or by locally adding structure as shown.

A similar approach may be used for subsystems/payloads having elements which pass through to the outside and require an aperture greater than a single isogrid element (such as beta joints). The concept shown may be modified for the various apertures sizes required.



EVA Access Hole



Shielding Options

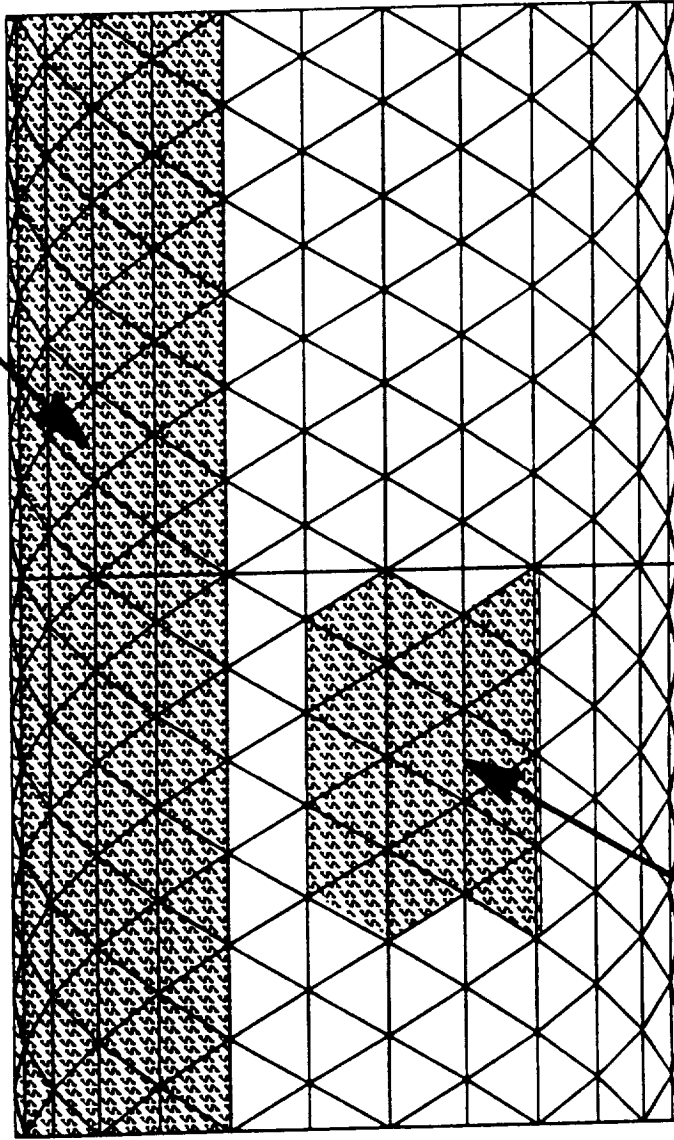
Isogrid lends itself to incorporating shielding for debris and micrometeoroid protection.

Large areas can be covered as may be necessary for utility protection, and smaller areas can be selectively shielded for subsystem/payload protection. In addition, shielding may be attached to, or incorporated in, the utility support rail structure.

The isogrid may be fabricated with integral shielding at selected grids, or by attaching separate shielding elements at any of the nodes.

Shielding Options

Utility Shielding

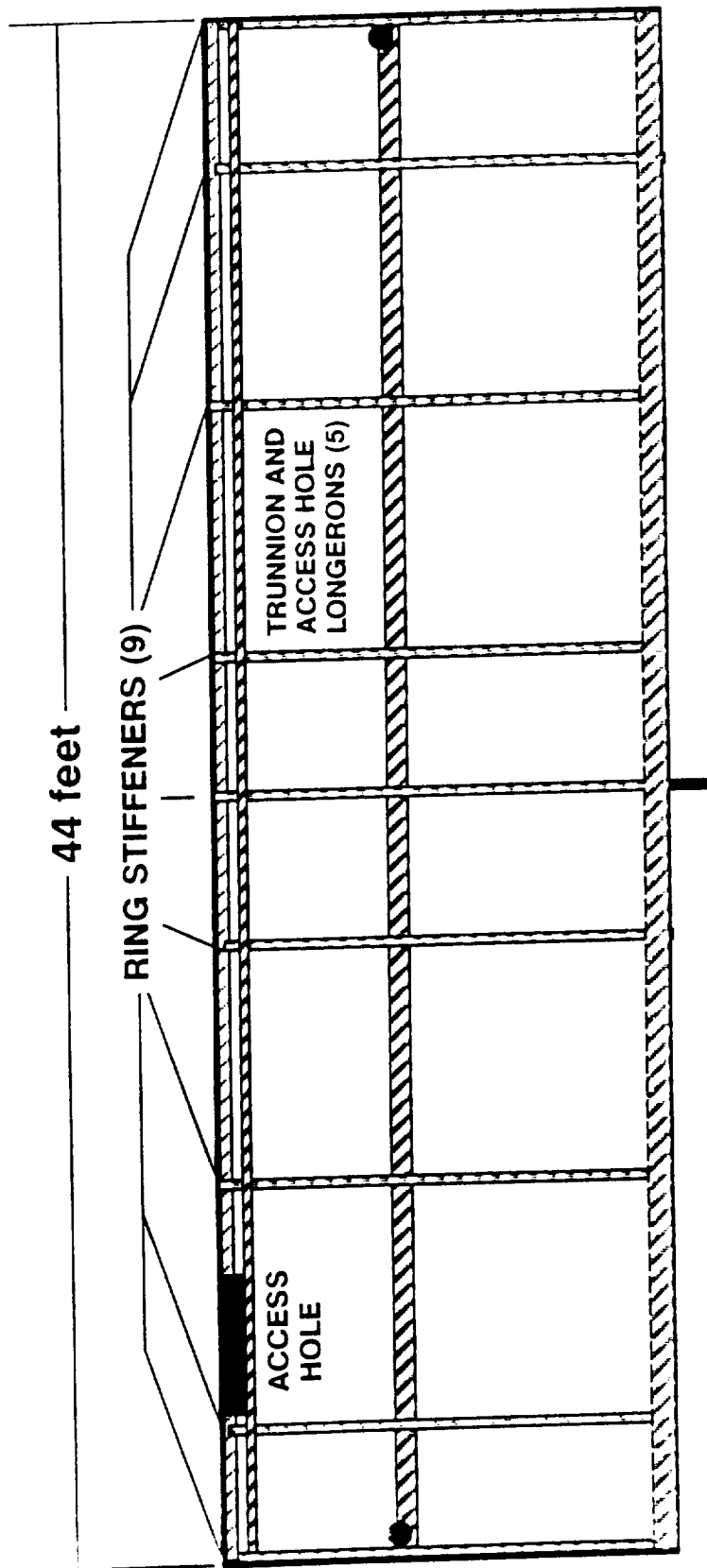


Selective Subsystem Shielding

Pre-Integrated Structure Isogrid Skin and Added Support

Hybrid section showing longerons and structural rings as used in the structural analysis.

Pre-Integrated Structure Isogrid Skin and Added Support



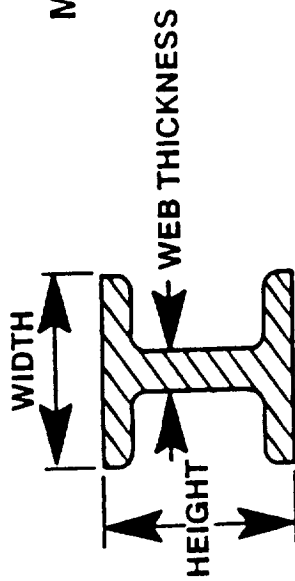
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SIDESTRUCTURE

Dimensions of Structural Elements

The cross-sectional dimensions of the isogrid and stiffening structure members are tabulated in the following chart. The material used was aluminum 2219-T87. Both I-beam and C-channel sections were used- the type used is indicated in the chart.

Dimensions of Structural Elements



MAT'L: AL 2219-T87

Isogrid Element	Height (in)	Width (in)	Web Thickness (in)
Keel Longeron	1.5	1.0	0.200
Trunnion Longeron	6.0	6.0	0.313
Top Longeron	5.0	3.0	0.125
Top Longeron (C)	5.0	2.0	0.156
Ring Stiffeners			
Primary	5.0	2.5	0.125
Secondary (C)	5.0	4.0	0.125
End Ring (C)	5.0	4.0	0.125
Container Edge Stiffener (C)	5.0	4.0	0.125

NOTE: (C) indicates C-Channel; all others are I-Beams

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Orbiter Interfaces

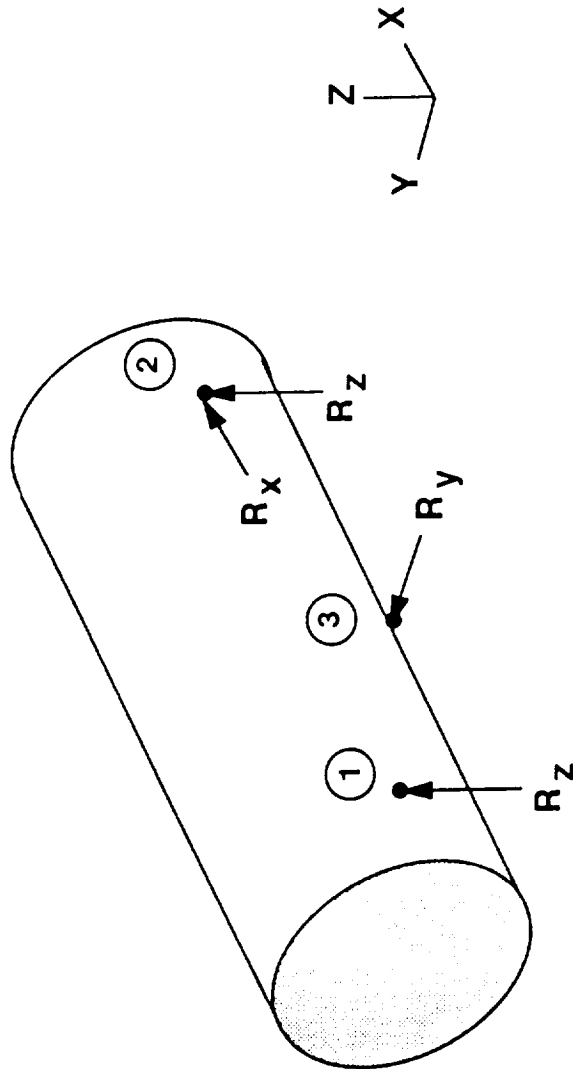
- Four Trunnion Fittings:
 - Forward pair react Z-axis loads only
 - Aft pair react both X-axis and Z-axis loads
- One Keel Fitting:
 - Reacts Y-axis loads only

Orbiter Interface Design Loads

The maximum reaction loads at the orbiter interface points are summarized below. The load cases from which these were obtained are presented in the Structural Analysis section of this paper.



Orbiter Interface Design Loads



Attach Point	R_x (lbf)	R_y (lbf)	R_z (lbf)
1 - Stabilizing	—	—	-27500
2 - Primary	41200	—	-100000
3 - Keel	—	-50000	—

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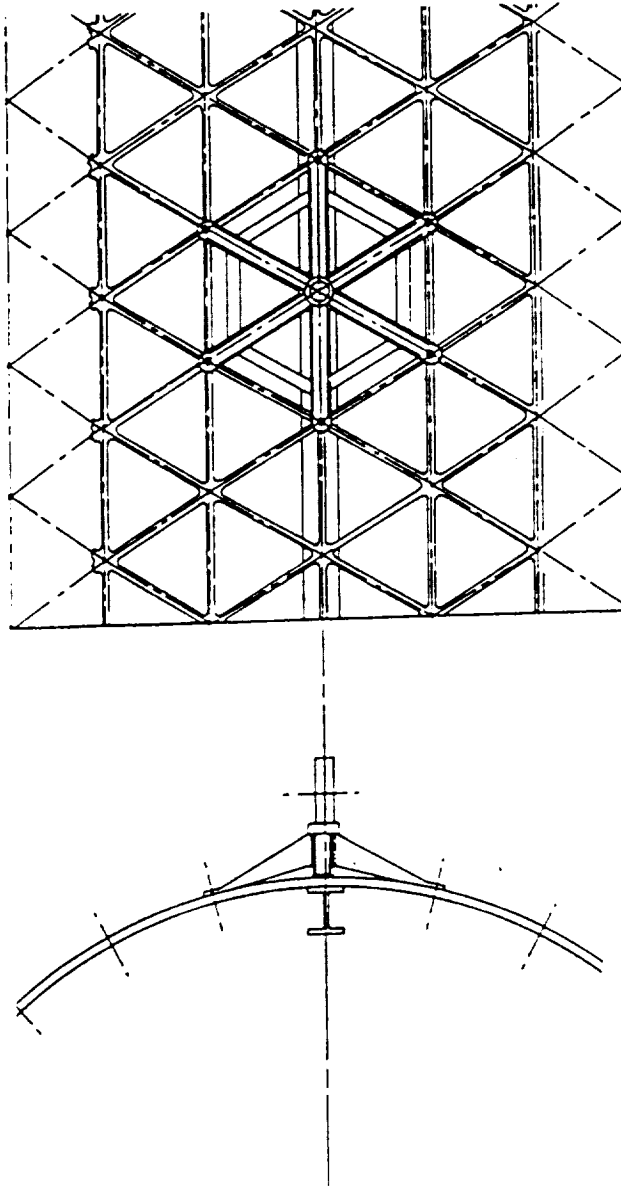
Trunnion Fitting

Four trunnion fittings support the integrated truss elements in the STS cargo bay. The aft (primary) pair of trunnions provide support in the X and Z axes, and the forward (stabilizing) pair provide support in the Z axis only.

Each trunnion spreads the load through seven nodes of the isogrid, as well as directly into the major longerons. The aft trunnions weigh 100 lbs. each, and the forward trunnions weigh 80 lbs. each.



Trunnion Fitting

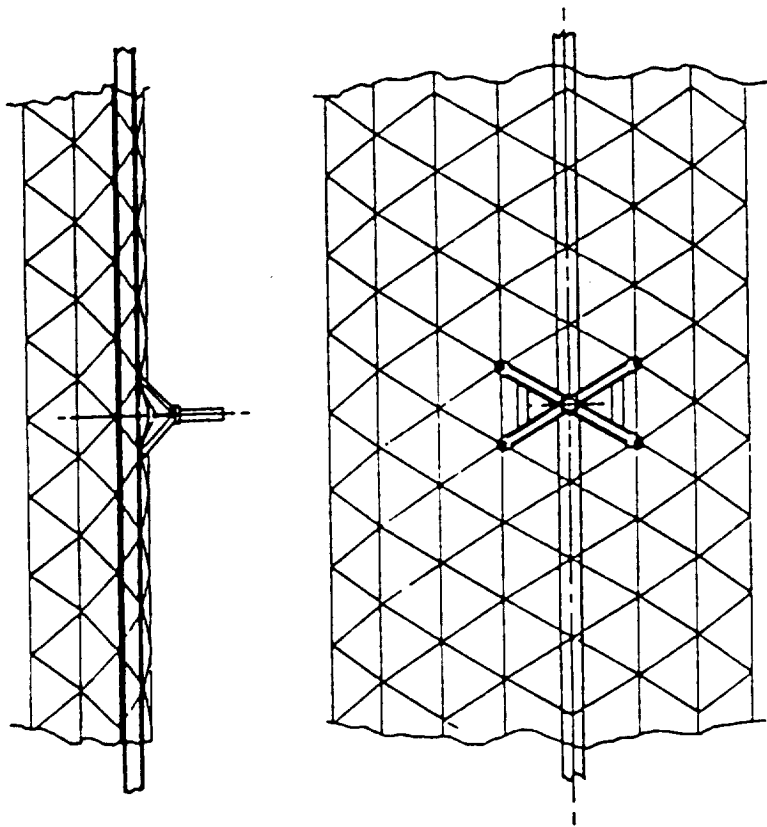


Keel Fitting

The keel fitting provides lateral support and distributes the load through five isogrid nodes, and into the keel longeron. This fitting weighs 80 lbs.



Keel Fitting



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Packaging and Mechanisms

Packaging Options

Several approaches can be taken with respect to packaging of the subsystems in the integrated structure. One approach could be to package the systems on the exterior of the structure. This approach enhances accessibility but requires some systems to be attached to the structure while on orbit which reduces the amount of pre-integration and increases the amount of EVA required. The systems that need attachment on orbit (RCS tanks, N2O2 carriers, etc.) take up valuable payload volume in the orbiter that could be used for additional structure length thus leading to an increase in the number of assembly flights. Another approach is to package all the systems in the interior of the structure. This approach would require all ORUs to be removed through small access holes in the structure via small containerized systems. Breaking up the systems into small units requires more interfaces and volume leading to additional weight and increased EVA requirements. An approach to get around these problems is to put the major subsystems in large removable sections of the structure. This approach requires additional structural weight to reinforce areas of the structure where the container sections can be removed but the advantage of having major subsystems located in one removable section (less distribution, less EVA and SSRMS accessibility) compensates for the weight penalty. The packaging approach used for this study is a hybrid of all of the above. Some equipment such as docking mechanisms and mobile transporter guide rails are mounted on the outside of the structure. Appendages such as thrusters, solar arrays, radiators and antennas are brought up stowed inside of the structure then EVA attached on orbit. Some subsystems, such as data processors and communications electronics, are packaged in small modular containers that are removed through access holes in the structure. Larger subsystems, such as RCS tanks and mechanical joints, are packaged in large removable structural sections.

Packaging Options

External Packaging

Major ORUs and some systems mounted outside of structure.

- Increases number of assembly flights.
- Requires EVA assembly and on orbit integration.

Internal Packaging

All ORUs and systems mounted inside of structure.

- Requires all ORUs to be removed through small access holes resulting in increased EVA, weight, volume and additional interfaces.
- Limits SSRMS accessibility.

Internal Packaging with Removable Container Sections

Major ORUs mounted inside of removable structural sections.

- Requires additional structural weight to reinforce areas of structure where container sections can be removed.
- Allows SSRMS access of major ORUs (such as hydrazine tanks) without requiring them to be mounted external to the structure.

The selected packaging concept is a hybrid of all three options.

Pre-Integrated Hybrid Isogrid Structure Packaging (Large Container Section)

An end view of the integrated structure is shown. The diameter of the structure is 13.33 feet which allows room for the externally mounted rails and docking mechanisms. The bottom half of the structure is a removable container section for housing large subsystems. The upper half of the structure is used as an EVA access corridor and includes utility lines, a CETA device and access holes. Minor ORU access to the subsystem container is done via the EVA corridor.

Pre-Integrated Hybrid Isogrid Structure Packaging

(LARGE CONTAINER SECTION)

MECHANICAL DOCKING LATCH

TUBE DIAMETER
13.33' OUTER
13' INNER

DEPLOYABLE MOBILE
TRANSPORTER RAILS

TRUNNION FITTING

ACCESS
HOLE

CETA

ELECTRICAL
LINES

FLUID
LINES

EVA ACCESS & MINOR
ORU CHANGE OUT

MAJOR ORUs HOUSED
IN HALF CIRCULAR
CONTAINERS

KEEL FITTING

SHUTTLE CARGO
BAY DIAMETER

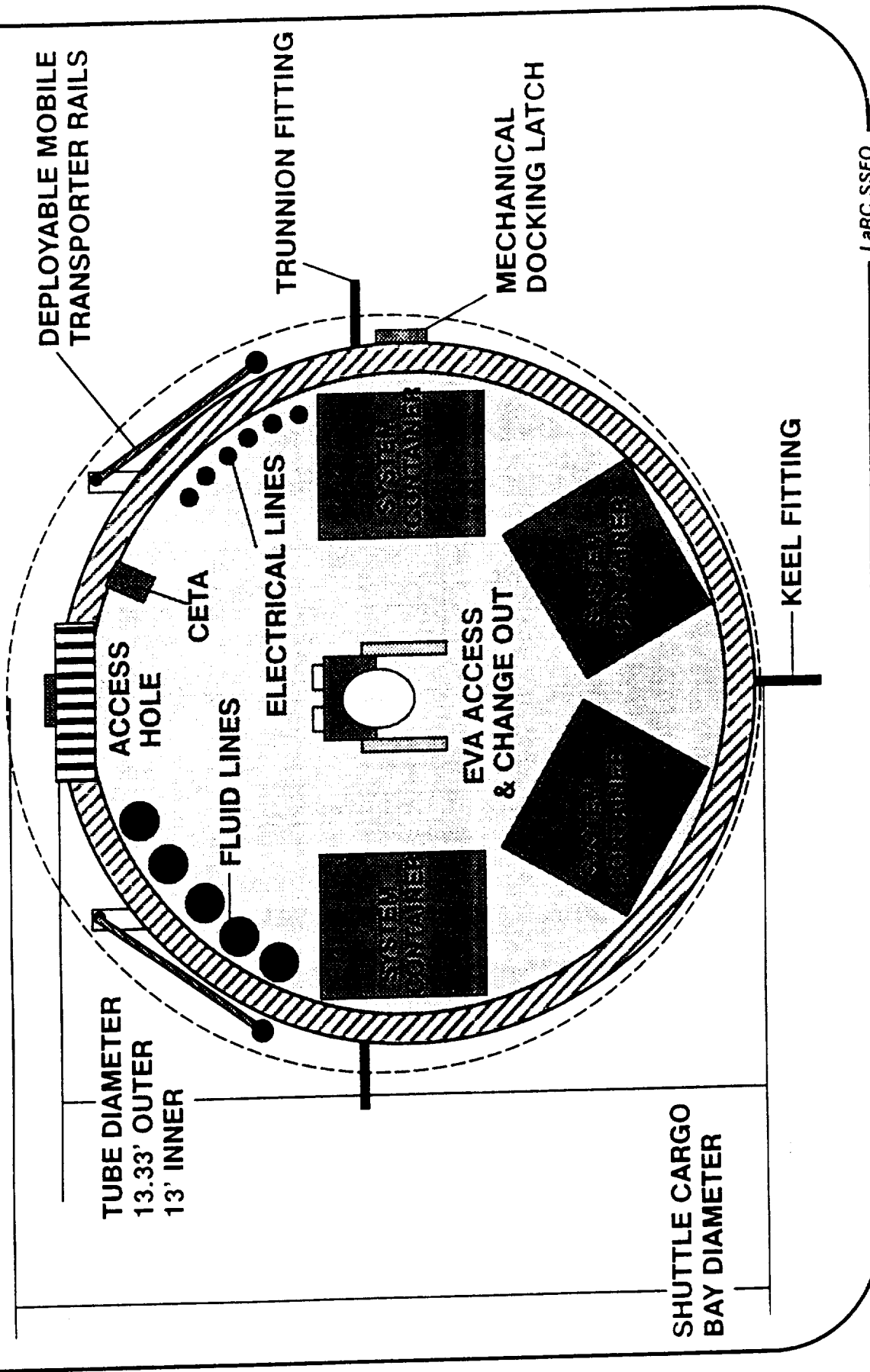
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Pre-Integrated Hybrid Isogrid Structure Packaging (Radial Container Section)

An end view of the integrated structure is shown. The diameter of the structure is 13.33 feet which allows room for the externally mounted rails and docking mechanisms. The bottom half of the structure contains radial system containers that can be removed through the access hole in the upper part of the structure. The upper half of the structure is used as an EVA access corridor and includes utility lines and a CETA device.

Pre-Integrated Hybrid Isogrid Structure Packaging

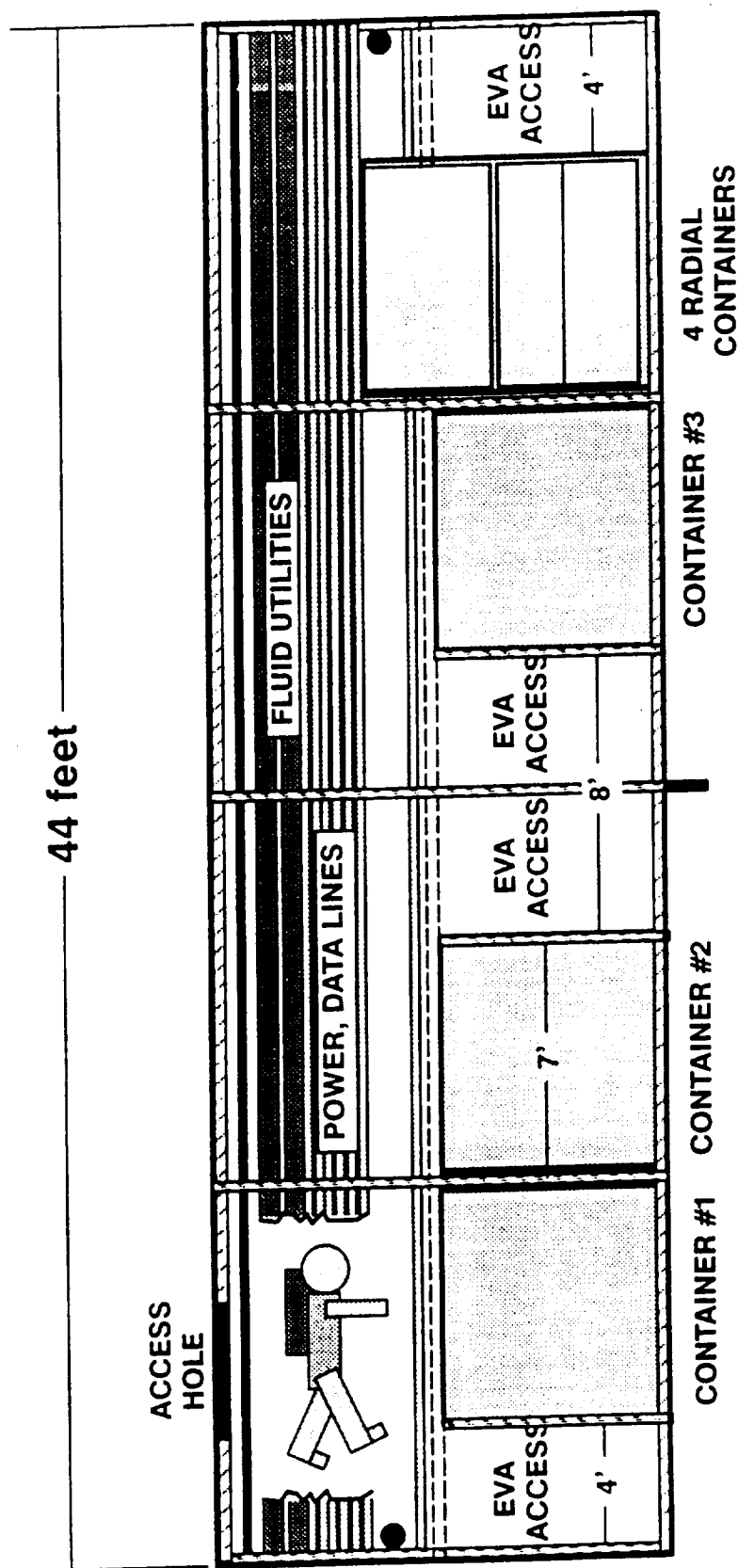
(RADIAL CONTAINER SECTION)



Pre-Integrated Hybrid Isogrid Structure Packaging (SIDE VIEW)

A side view of the integrated structure is shown. The length of the structure is 44 feet which maintains orbiter clearance and center of gravity requirements. A typical section would have several removable container sections and one radial container section. Each section is 7 feet long with 4 feet of EVA access/utility interface space available on one side. The upper half of the structure is used as an EVA access corridor and includes utility lines, a CETA device and an access hole.

Pre-Integrated Hybrid Isogrid Structure Packaging



Additional longerons, ring stiffeners and container structure have been added to the Isogrid skin for added strength.

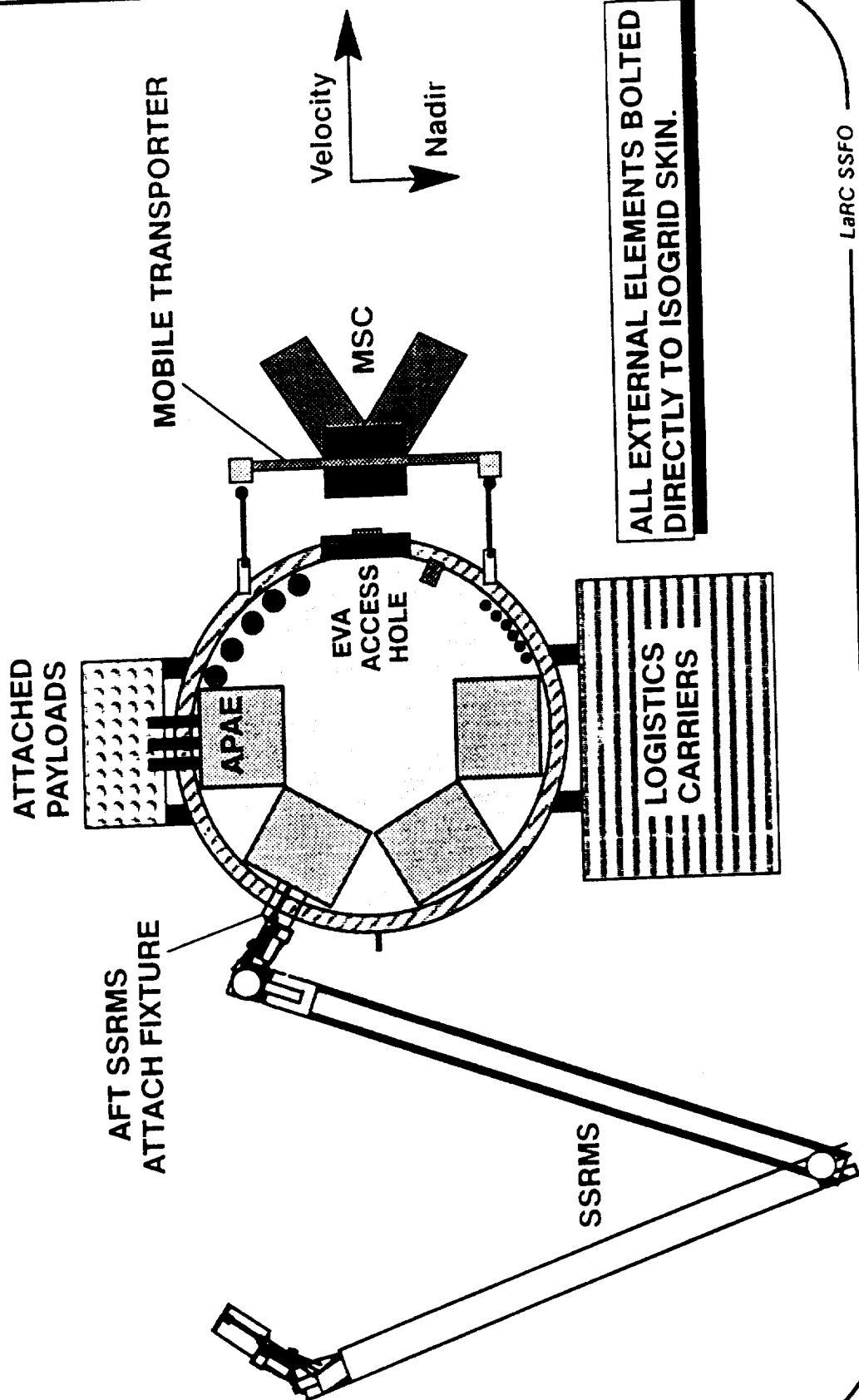
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SIDE PACKAGE

External Attachment Capability

The methods for attaching external elements are shown. The isogrid skin provides a large number of attach points due to the pre-drilled holes located at the intersections of the beam members. Attached payloads can be mounted directly to the isogrid with utility interfaces running through the open triangular sections into the structure. The MSC rails and additional logistics carriers can be mounted in a similar fashion. An aft SSRMS attach fixture will be required on some sections of the station to accommodate reach requirements for items such as radiators and the JEM module

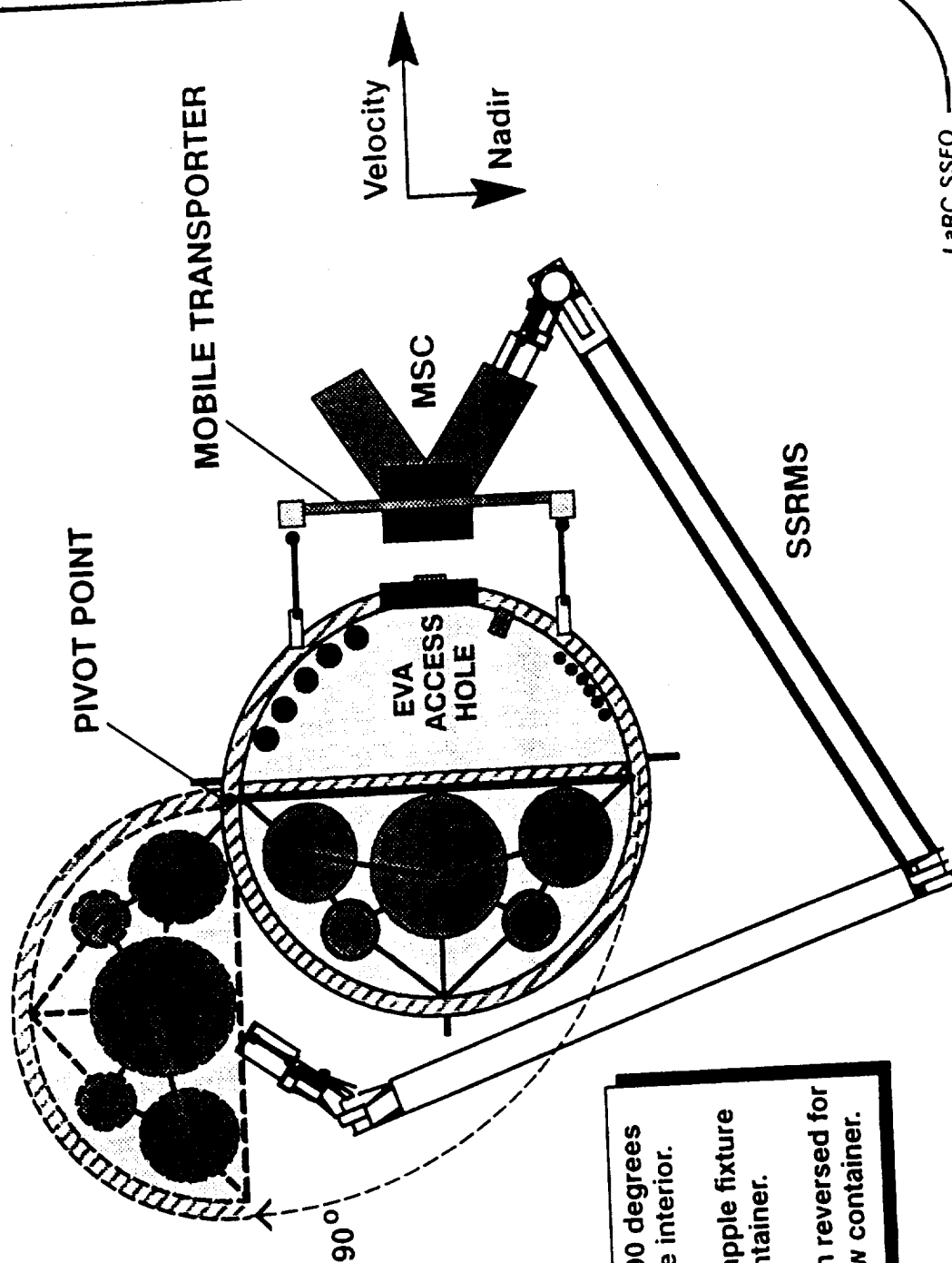
External Attachment Capability



Major ORU Container Replacement

Major subsystem ORUs are accessed through the use of removable container sections. The structural container section is rotated 90 degrees outward to expose the interior. The SSRMS grabs a grapple fixture, lifts the section away from the station, then places the section in the orbiter cargo bay. The procedure is reversed with a replacement section (RCS tanks for example). For some applications, removal of the container section may not be necessary since the SSRMS may be able to remove specific subcomponents from container section while in the rotated position.

Major ORU Container Replacement



Rotate container 90 degrees outward to expose interior.

SSRMS grabs grapple fixture then removes container.

Procedure is then reversed for installation of new container.

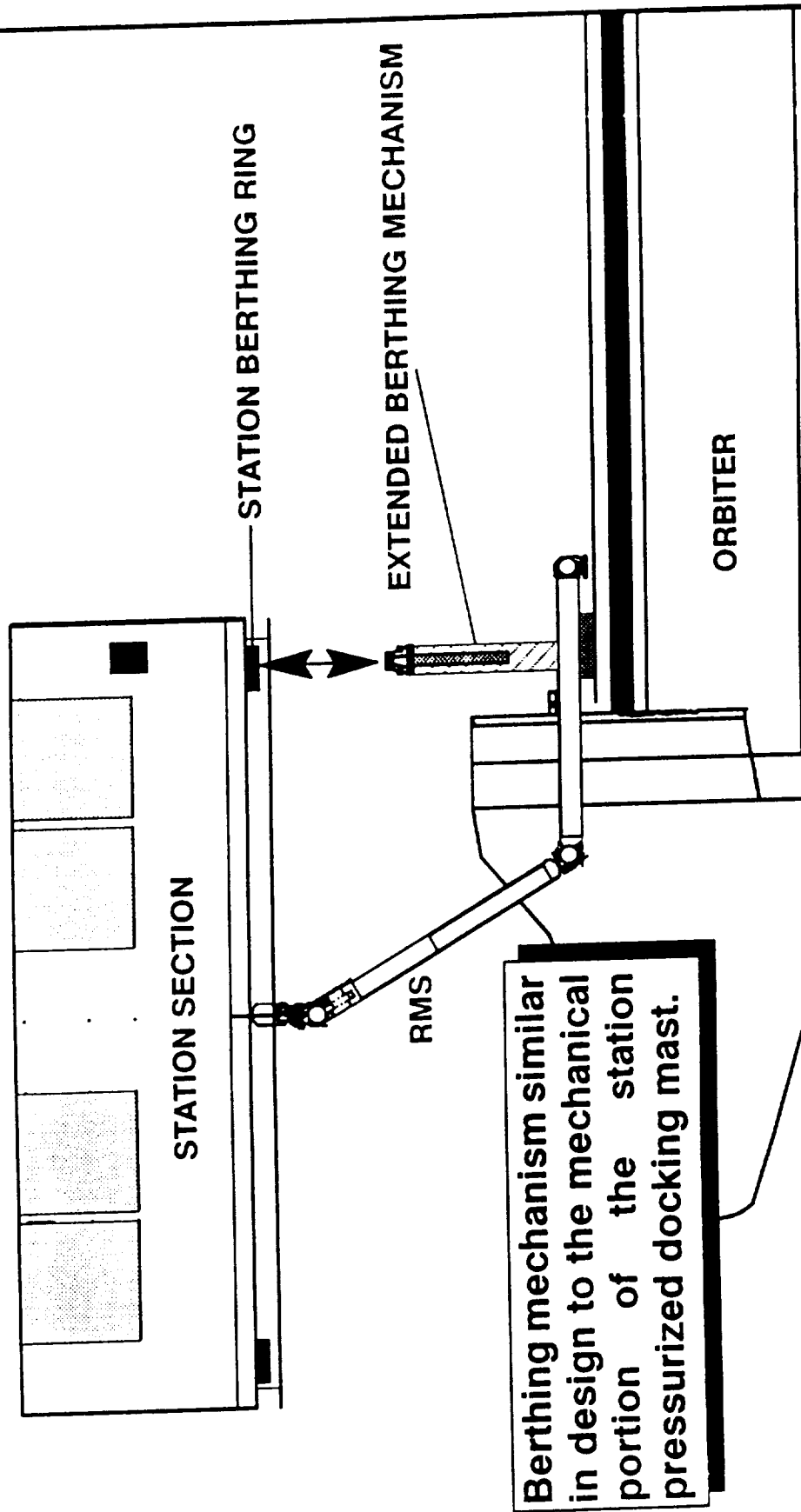
Station Assembly Mechanisms and Attachment Methods

Each tubular section is assembled to the next by manipulating it with the arm on the STS until it is aligned.

The two sections are brought together, and three guide pins provide the final alignment and accept shear loads across the joint. The first pin to engage is longer than the other two. This allows initial engagement followed by rotation of the tube for final alignment and docking.

At each guide pin location, there is also a latch which automatically secures the two sections together axially in a soft docked condition. After it has been established that this connection is secure, two mechanisms are simultaneously operated (EVA) to provide final alignment and docking. Once final docking is complete, the bolts around the interface are secured (EVA) to accept operational loading.

Station Assembly Mechanisms and Attachment Methods



Mechanisms and Attachment Methods

Mechanisms are incorporated in the end of each truss section to assist in the alignment during assembly. Initial engagement of the two sections is made by automatic latches to provide a secure condition (soft docking) prior to EVA.

Final docking is established when the two sections are pulled fully together, and the final attachment is made with bolts to provide structural integrity of the assembled truss.

Once the mechanical assembly is complete the utilities, which are integrated within the tube section are connected to the adjoining tube with quick disconnect (QD) fittings. The pre-integration of the utilities in the tube permits the use of rigid sections of fluid lines with flexible segments at the QD interfaces.

Mechanisms and Attachment Methods

- **Isogrid Section Interface:**
 - Alignment and soft docking
 - Final docking (EVA)
 - Final attachment (EVA)
- **Utilities:**
 - Quick disconnects (EVA)
 - Use of flexible and rigid sections possible
 - Flexibility in choice of support locations
 - Individual and group retainer system to optimize maintenance procedures

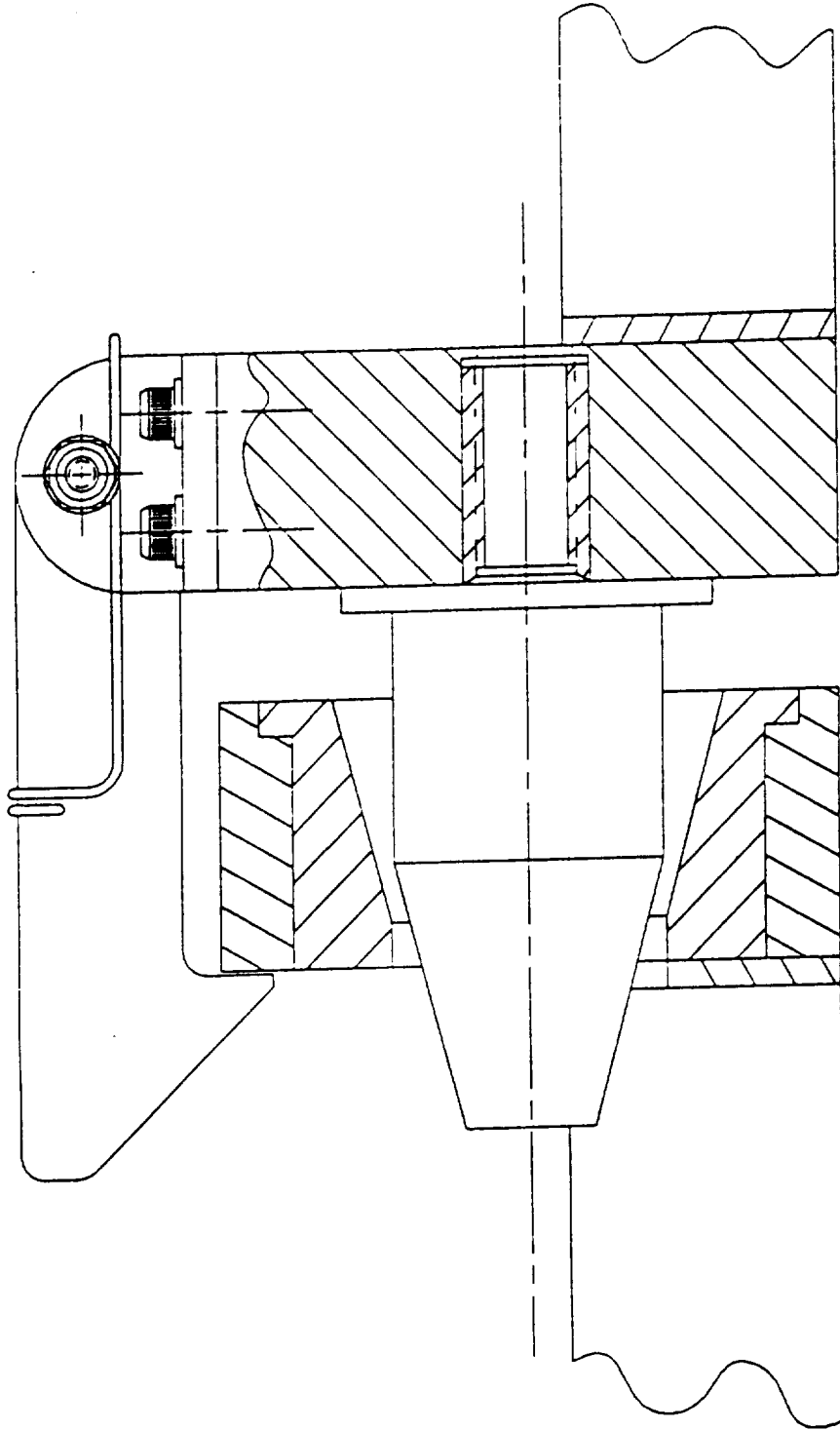
Soft Docking Alignment Pin and Latch

Docking alignment is facilitated by the tapered section of the pins.

The latch is designed with free play along the axis of the tube section during initial engagement to ensure operation of all three latches.



Soft Docking Alignment Pin and Latch



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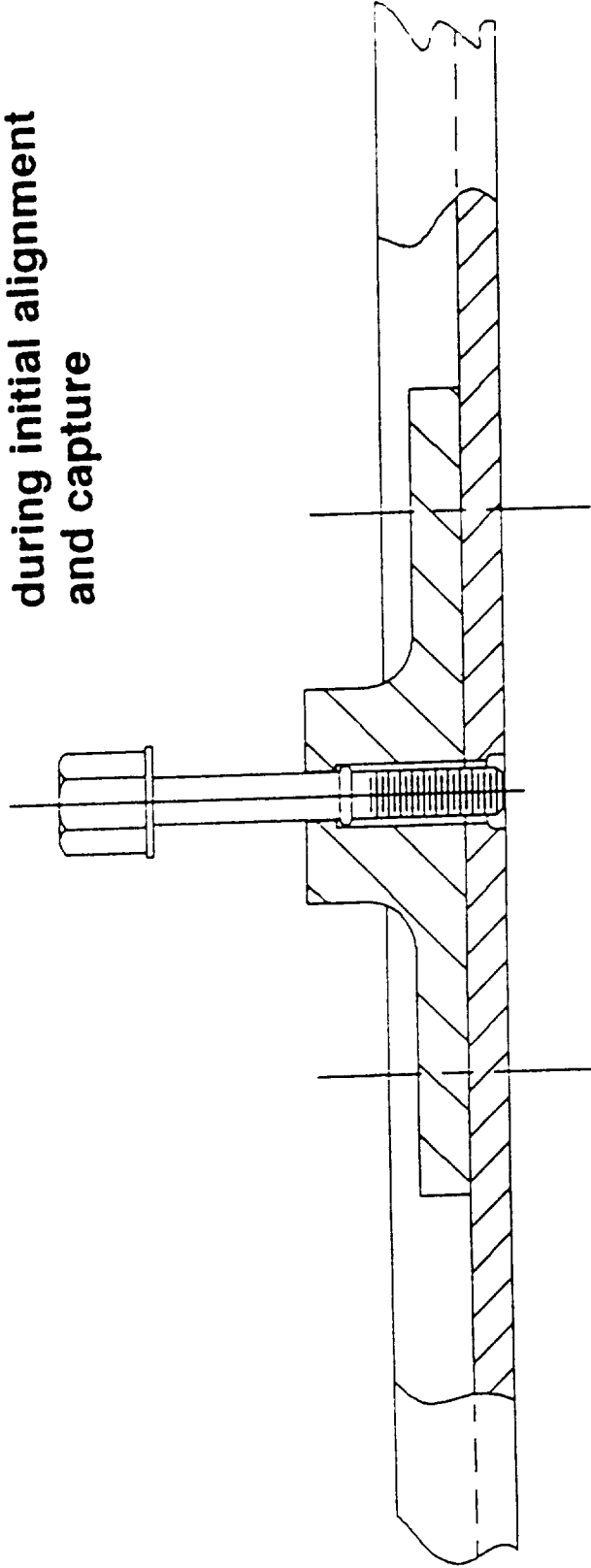
Attachment Bolt Detail

During the docking/latching sequence, the bolts are retracted to prevent interference. Once latched securely, the bolts are inserted into the adjacent isogrid section and tightened.



Attachment Bolt Detail

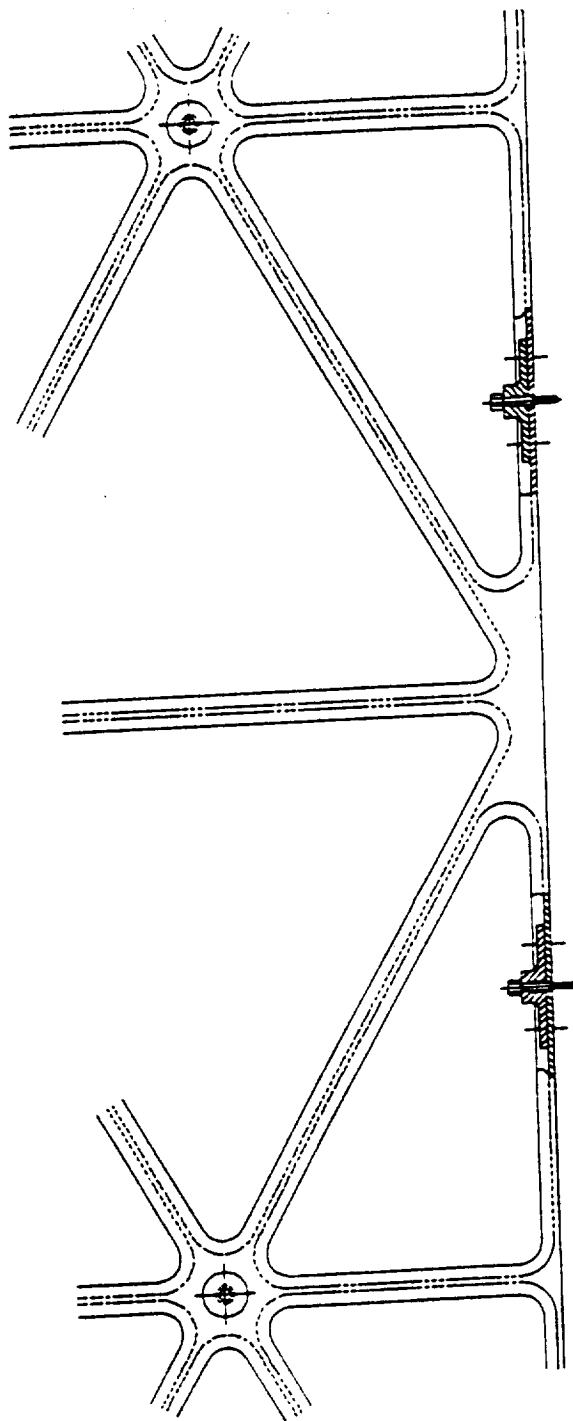
Bolt is retracted
during initial alignment
and capture



Tube/Tube Attachment Bolt

Final attachment of each tube section is made using retained bolts through the ends of the isogrid.

Tube/Tube Attachment Bolts

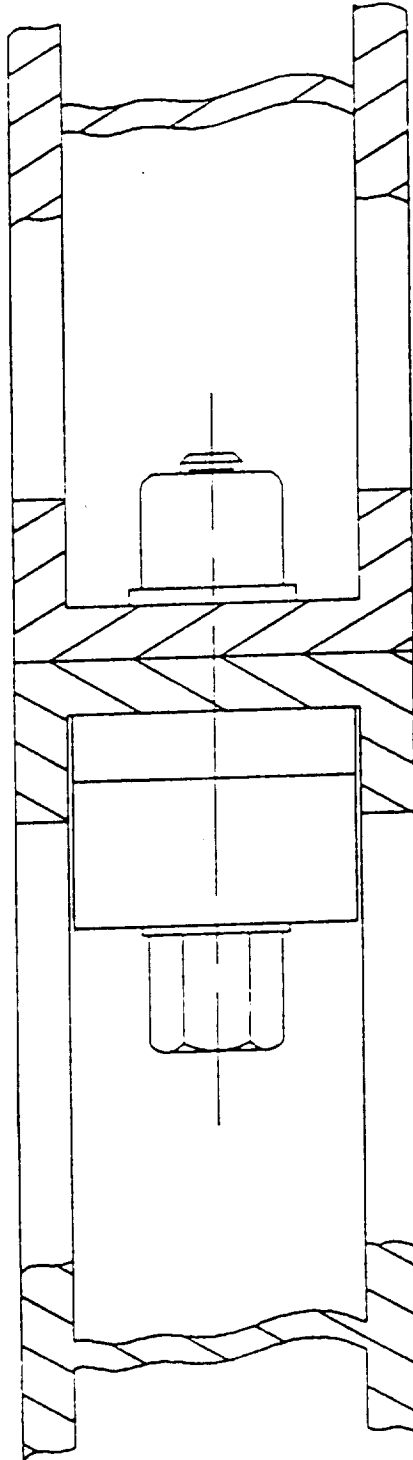


Final Position of Attachment Bolt for Two Mated Sections (Typical)

The bolts are shown within the thickness of the isogrid.



Final Position of Attachment Bolt For Two Mated Sections (Typical)



Utility Interconnection

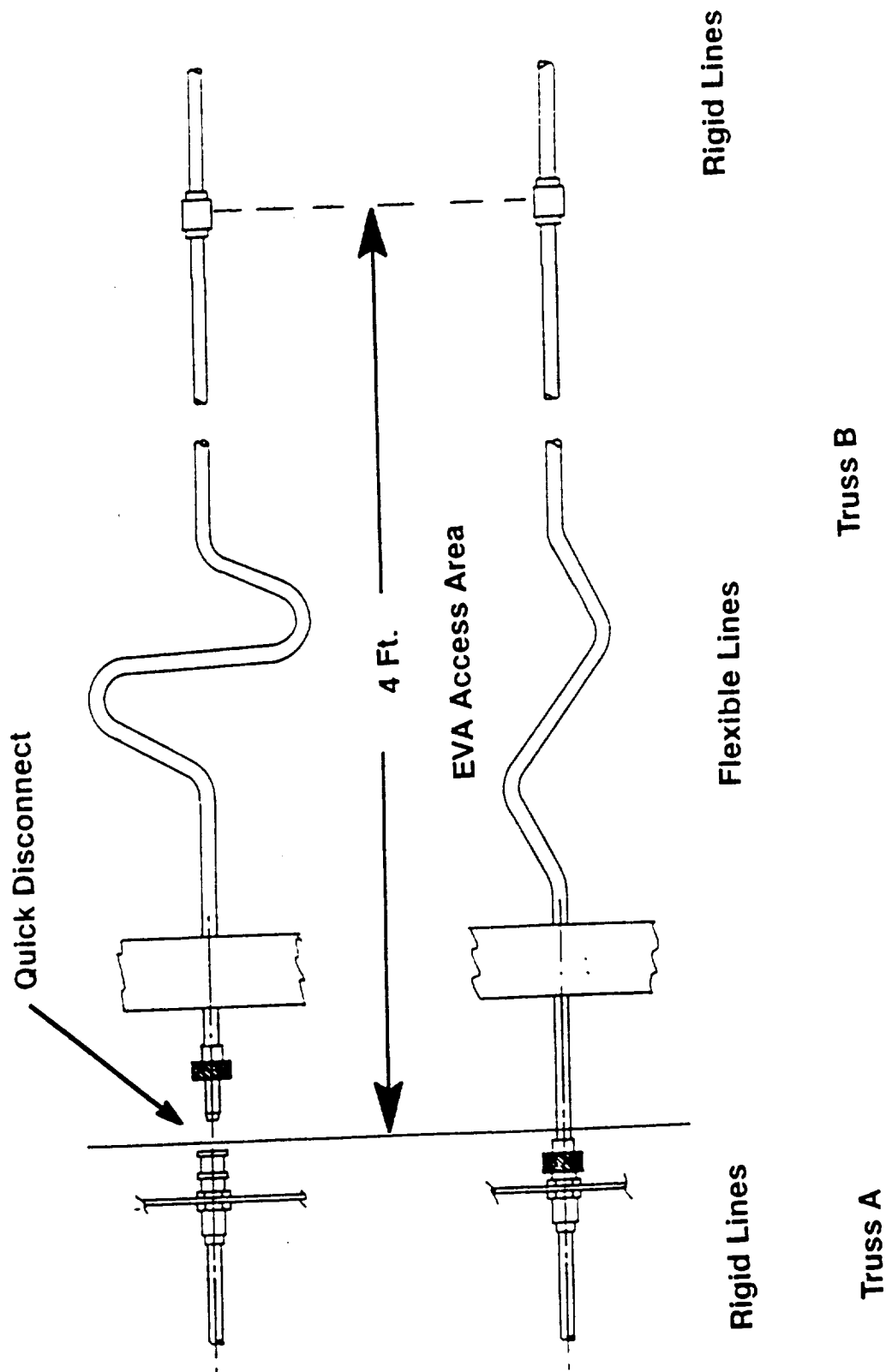
Within the isogrid, utility lines can be rigid or semirigid, to the extent that service replacement will allow.

A section at one end of each truss element will be flexible to allow the lines to be retracted during launch, and extended to connect to the rigid lines in the adjacent truss element during assembly.

The extendable section of the lines can be achieved in several ways including methods/materials used in the current baseline. Each line is equipped with a quick disconnect for ease of assembly. Electrical lines use the same mounting concept.



Utility Interconnection

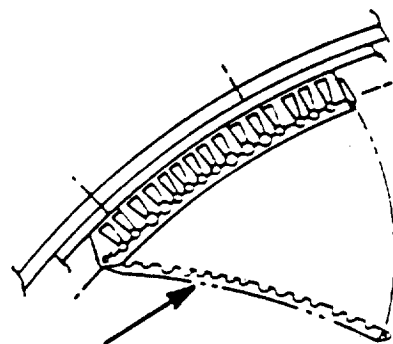


Utility Line Attachment

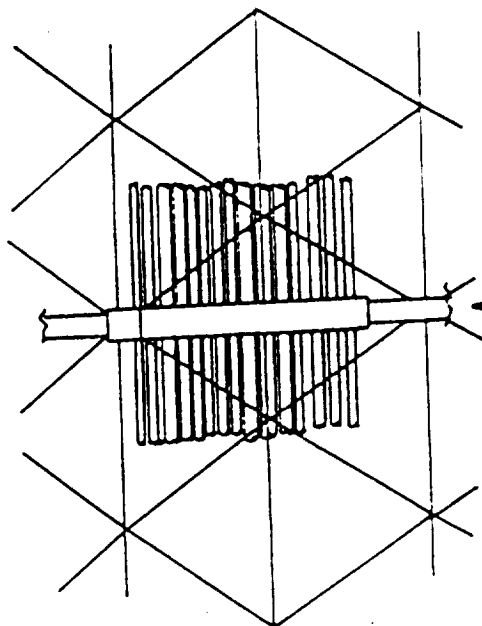
Attachment may be with hard clamps applied to each line individually, or with soft clamps with a retainer providing security for a group of lines or cables. The retainer locks the soft clamps and provides structural support during launch loads.



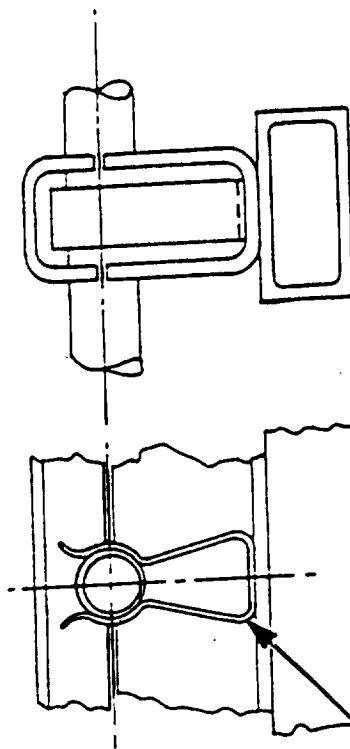
Utility Line Attachment



Hinged Retainer



Support Ring



Soft Clamp

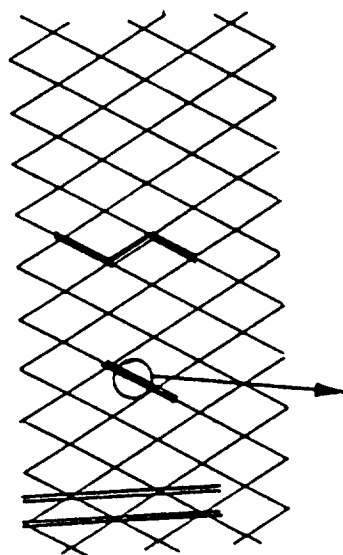
Utility Support Locations

Utilities are supported on rails which offer numerous options for attachment to the isogrid.

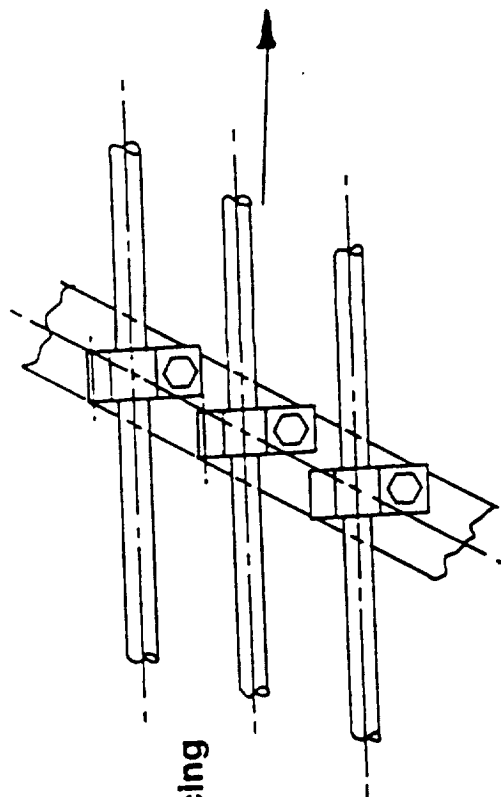
A circumferential ring (or partial) can be situated at 11 inch increments, or diagonal rails can be mounted following the contours of the isogrid members. The latter may permit closer spacing of the utility lines, while allowing access to the clamps for maintenance.



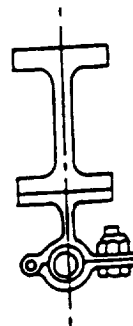
Utility Support Locations



Support rail mounting
options bolted at
isogrid nodes



Reduced spacing
possible with
angled rail



Subsystem Mounting Concepts

Internally mounted ORUs may be pre-integrated. Externally mounted ORUs must be stowed inside during launch, and assembled on the exterior of the truss on orbit.

Larger ORUs (such as an RCS tank farm) are in the form of removable semicircular segments of the isogrid structure. Smaller ORUs are mounted on trays and may be removed from the tray and transported through an EVA access hole during service operations. Each type of mounting method may be used exclusively within a particular section of truss, or a combination of both types may be used as required.

External attachments to the isogrid may be single point attachments to an individual node for small items such as UHF antennas, or using a "foot" to distribute the load over several nodes as would be required for a large antenna assembly. Attached payloads may be secured directly to the nodes with similar "feet", or mounted on struts as required. PV arrays and radiators are mounted on beta joints, which are accessible through enlarged openings in the isogrid.

Subsystem Mounting Concepts

- **Internal Attachments:**

- Major ORU container replaceable as a unit or serviceable for subsystem element replacements (tanks, etc.)
- Container is retained as an integral part of the structure during launch and operation
- Smaller subsystems on trays inside a contiguous tube section

- **External attachments:**

- Single point attachments to nodes
- Attached payloads to nodes via struts or load spreading brackets
- Antennas/radiators to similar mounts or through isogrid to subsystem

Subsystem Integration Approach

The First Element Launch (FEL) is used as a representative truss section since it was found to be one of the heaviest launch payloads. It also has a relatively small margin for the location of the center of gravity with respect to the orbiter payload requirements.

The configuration of the system/subsystem hardware in this flight is varied in that it incorporates several types of mounting requirements. These include large ORUs in removable containers, smaller ORUs mounted on trays, and some directly mounted to the isogrid, as well as fixed and movable external system elements.

Subsystem Integration Approach

Use First Element Launch (FEL) as representative example.

- FEL is one of the more critical flights with regard to:
 - a) Total mass to orbit
 - b) Center of gravity location within the STS cargo bay
- FEL feature:
 - a) Mounting of large and small ORU's in containers, on trays, and directly on isogrid
 - b) Attachment of external ORU's

First Element Launch – Flight TR1 Assembled Configuration

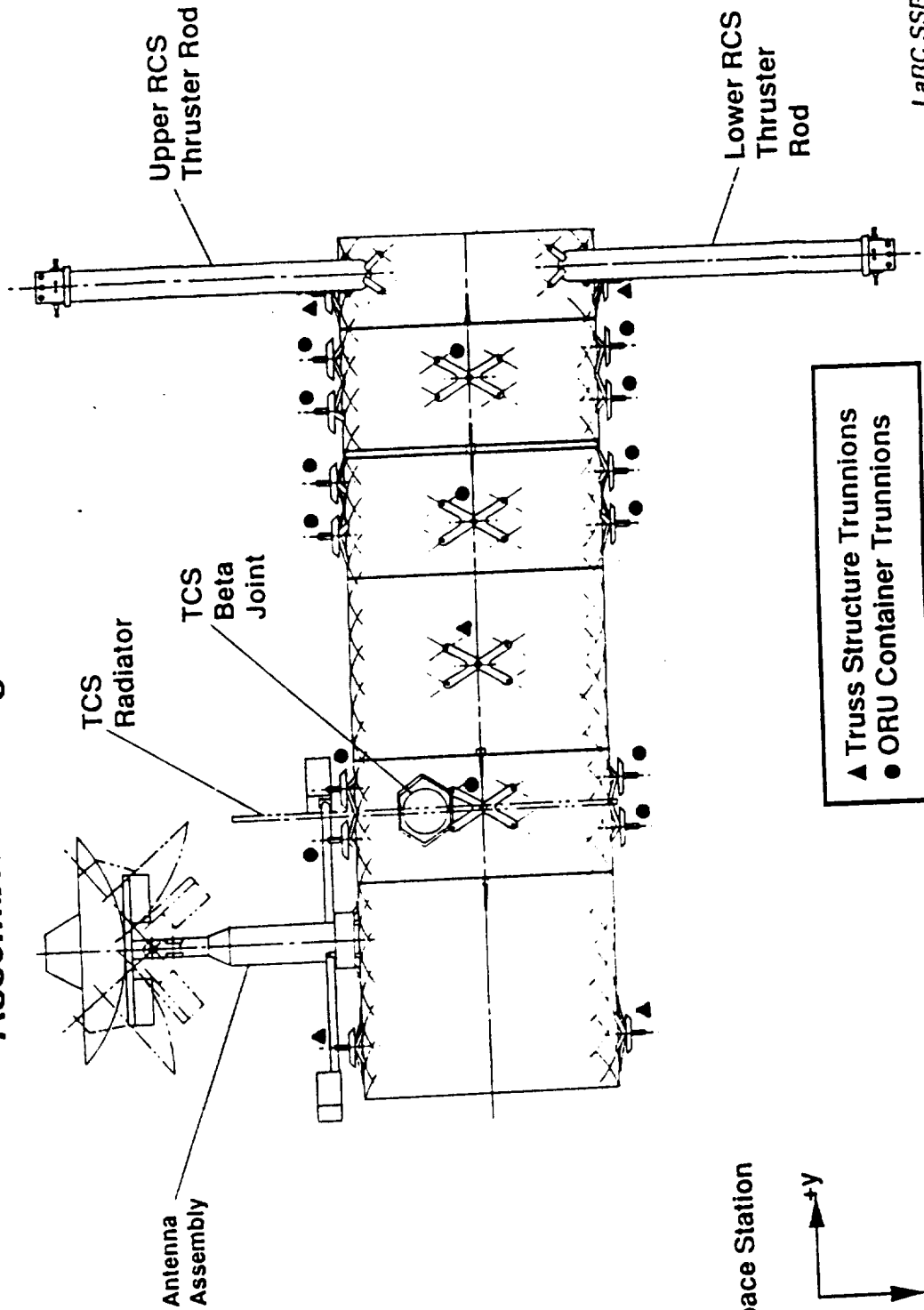
The first element launch was selected for a more detailed evaluation of the structures and mechanisms used in the reinforcement of the isogrid and the mounting of the subsystem elements. This flight was studied because: 1.) It contains both large removable containers (RCS and TCS and smaller ORUs (C&T, DMS, and EPS elements); 2.) The need for mounting external elements is addressed in the case of RCS thruster pods, TCS radiator, and C&T antenna assemblies; 3.) This is one of the more critical flights in regard to payload mass and center of gravity requirements for the NSTS launch vehicle.

The standard cargo interface trunnions are shown for attaching the 44' integrated truss section within the orbiter cargo bay. In addition a set of trunnions is shown on each of the removable containers. These may be in place during initial launch of the integrated section if clearances permit, or attached on orbit in preparation for returning the container to earth. Replacement containers will have trunnions permanently attached for use when launching/returning the container as an independent cargo element.



First Element Launch - Flight TRI

Assembled Configuration



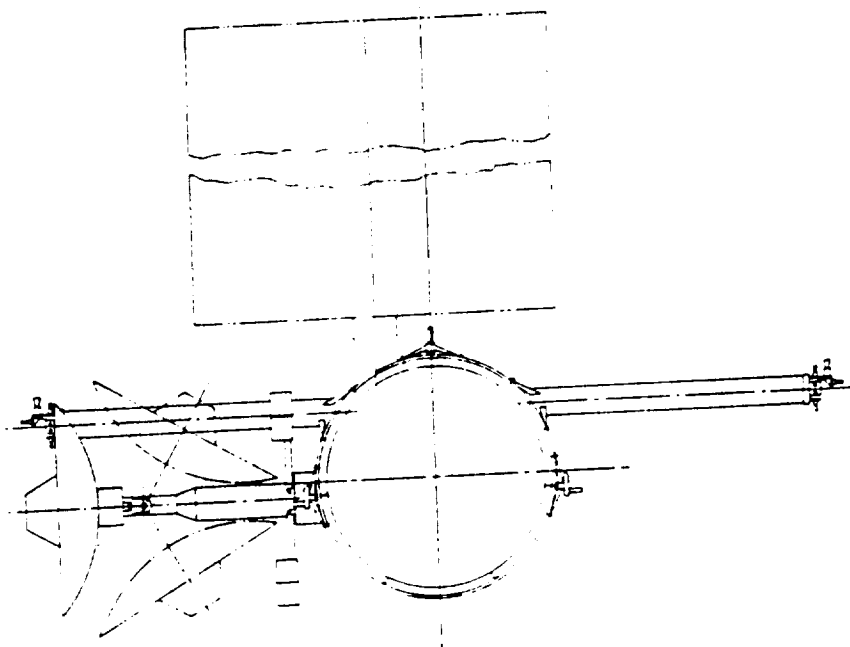
First Element Launch – Flight TR1 Assembled Configuration – End View

In this end view the relative locations of the antenna assembly, RCS thrusters, and TCS beta joint can be seen.

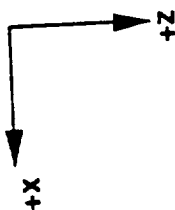


First Element Launch - Flight TRI

Assembled Configuration - end view



Space Station



Packaging – First Element Launch

As far as possible systems are integrated prior to launch. Exceptions to this are externally mounted items which are stowed inside the tube section for launch, and assembled on the exterior of the isogrid during EVA, or by using robotics capabilities.

Packaging—First Element Launch

Integrated Items

- RCS Tank Farms
- GN&C Star Trackers & ISA's
- TCS-baseline pallet mounted ORU's
- C&T-baseline pallet mounted ORU's for C&T, DMS, and EPS systems
- Temporary Power System

Items Stowed for Launch

- RCS Thruster Assemblies
- SGS Ku-Band Antenna and Support Structure
- Antenna mounted C&T ORU's

First Element Launch – Flight TR1 Launch Configuration

In the launch configuration, the integrated systems hardware is located in containers (RCS and TCS system elements), directly on the isogrid (GN&C elements and utilities), ORU trays (C&T, DMS and EPS system elements and the temporary power system).

The temporary power system and its associated PV array are also pre-integrated. The electronics and batteries are on an ORU mounting tray, and the solar panel blanket is directly “wrapped” around an available area of the main isogrid tube such as the central EVA access section.

The stowed items are the RCS thruster pods and the Ku-Band antenna with its support structure. Some antenna mounted C&T system elements are also stowed on one of the mounting trays.

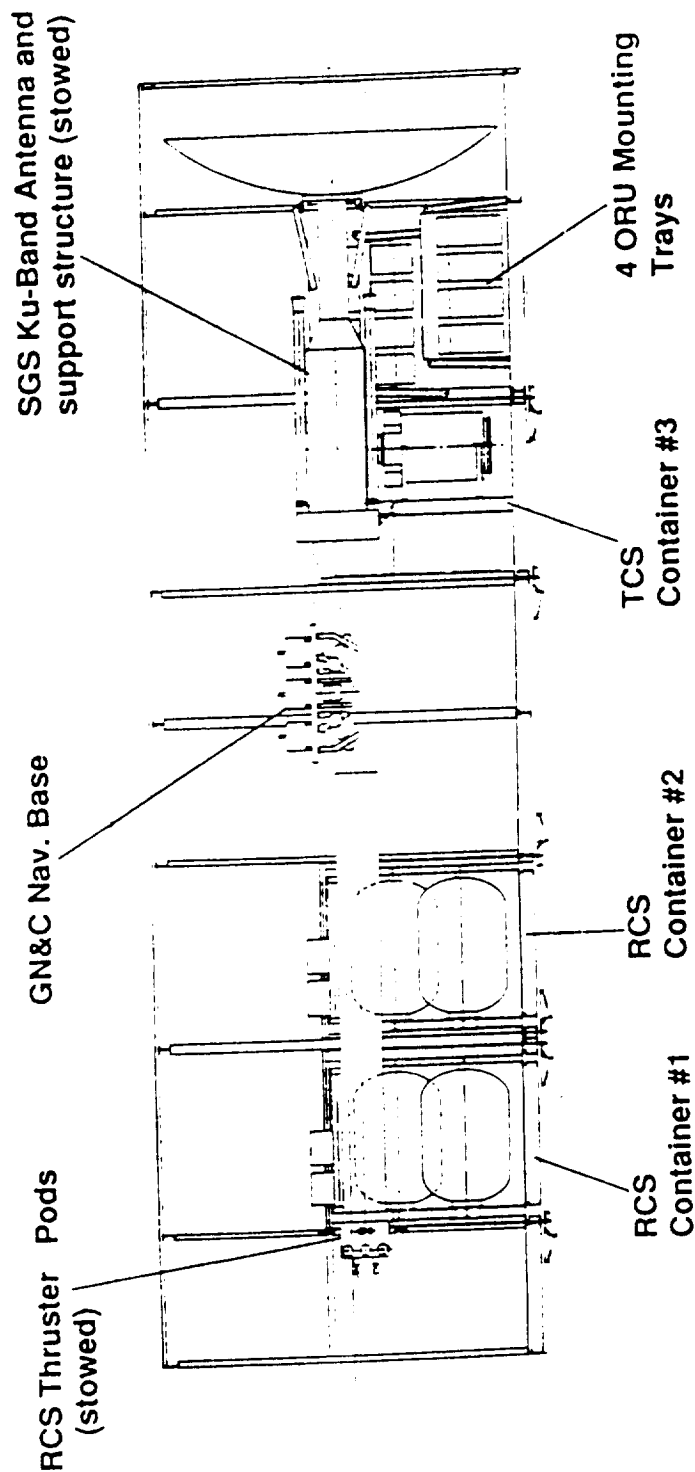
The propulsion system conceived for this structural configuration features a tank farm assembly in each removable RCS container. The thruster pod assemblies are on extended booms to provide the necessary reaction torque moments. There are four tanks (type V075) in each RCS container providing a total capacity of 4255 lbs of fuel per container. The RCS tank containers are ORUs for the purpose of refueling, and maintenance, and may be configured as either: One container serving both thruster pods. The other set of tanks is to be used when the first is being replaced/refueled, or one container serving to each of the upper and lower thruster assemblies, as in the baseline station.

A special consideration for these configurations is that the fuel lines between the tanks and the thrusters must be connected and disconnected on orbit. Quick disconnect technology (Fairchild poppet valve type) has been developed for on-orbit refueling of the GRO spacecraft, and this may be applied to this concept. Alternatively a ball valve type (Moog design – tested, but not yet qualified) may offer the increased flow rates which may be necessary for this application.



First Element Launch - Flight TRI

Launch Configuration

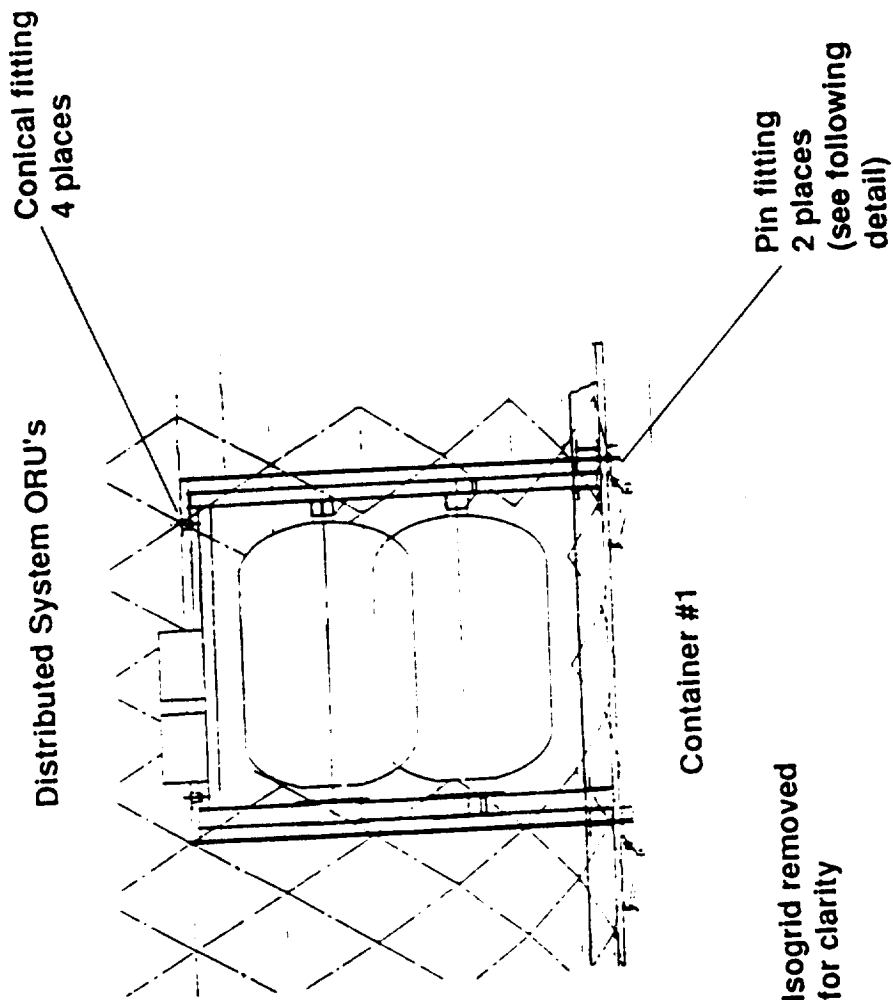


RCS Container – Side View

This view shows the location of the attachment fittings which retain the container. The keel fittings between the two containers are retractable pin and latch mechanisms which are tapered for alignment purposes, and are capable of reacting loads in the orbiter Y and Z axes. On orbit, the reduced load requirements may permit replacement containers to be secured by a subset of the six attachment fittings described, the balance to be used for alignment purposes only.



RCS Container - Side View



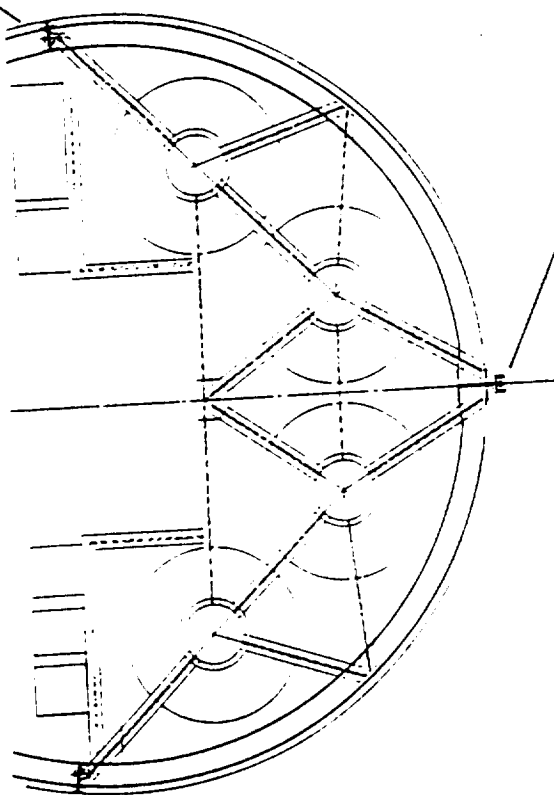
RCS Container – End View

The fuel tanks are mounted between two end frames in a manner similar to that used in the baseline. The aft frame (launch orientation) provides primary support in three axes, while the forward, somewhat lighter, frame provides secondary support in the Y and Z axes only. The upper extension of these end frames forms a support for a platform used to mount the electronic components.



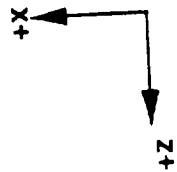
RCS Container - End View

Conical Fitting
4 places
(see following
detail)



pin fitting
2 places

Space Station



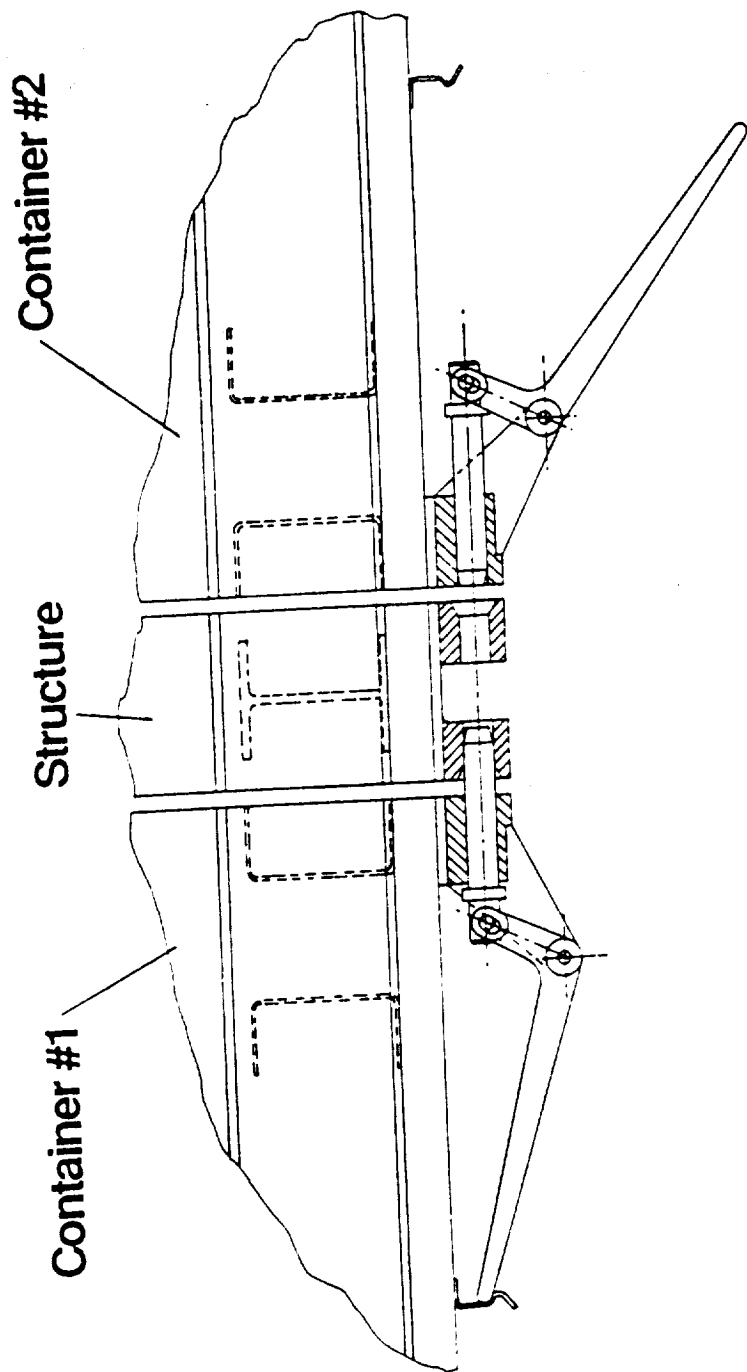
Container Attachment Fittings at Keel

The two pin fittings at the keel are operated by a cam/lever mechanism. They can react loads in the Y and Z axes, and alone are sufficient to react the reboost loads in these directions.



Container Attachment Fittings at Keel

Pin Type



Retracted

Secured

Container Attachment Fittings

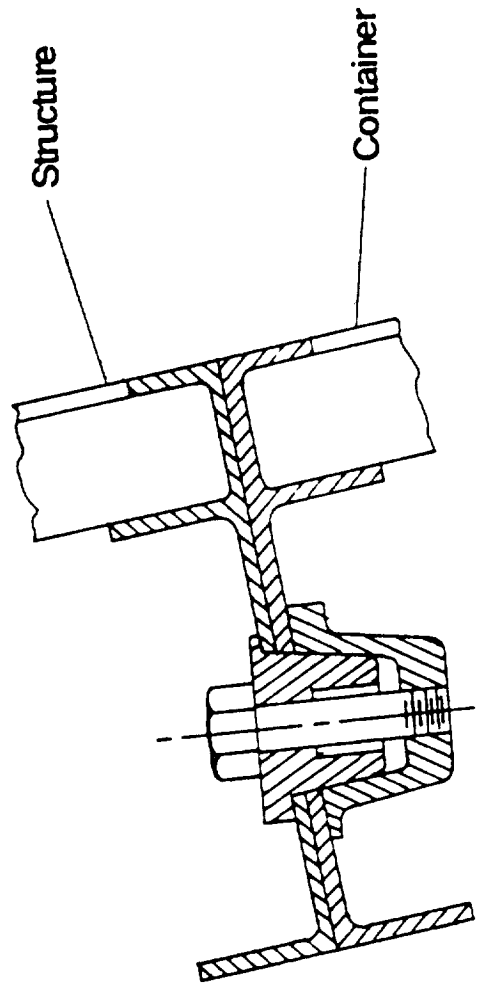
Conical

The four conical fittings provide alignment and attachment of the container into the main tube structure. These are designed to react loads in the orbiter X and Y axes through the main longerons to the orbiter attachment trunnions. The bolts provide the mechanism for pulling the container fully into the load carrying attachment as well as carrying Z axis loads in tension. The bolts may not be required for the lighter on-orbit loads, and may be left undone after the first service replacement of the container. A simple (light) latch may be attached to the exterior to facilitate installation of replacement containers. Further study is required to determine the feasibility of these details, and the specifics of connecting the fuel lines feeding the thrusters.



Container Attachment Fittings

Conical



Alternate Propulsion System Configuration

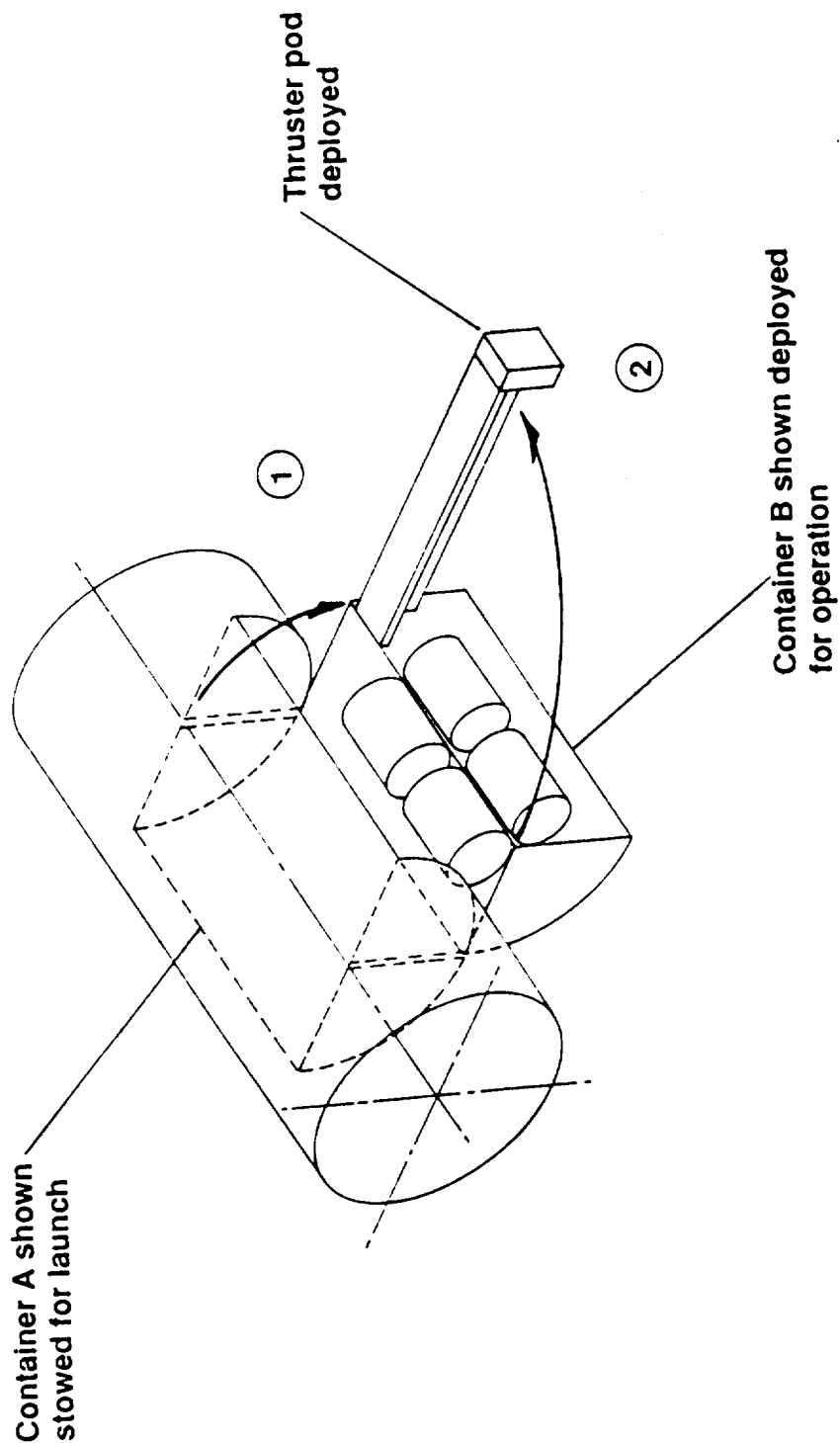
Alternate configurations have been considered to eliminate the on orbit hypergolic connections. However, no detailed study has yet been made of the structures and mechanisms for these options. In this scheme, the complete propulsion system is a single ORU (as in the baseline). The container in this case is a quarter section of isogrid and is twice the length of the semicircular containers. It is hinged at the keel, and stabilized by struts between it and the main isogrid structure. The thruster pod assemblies fold out from the container after it has been rotated outward to its operating position. A structural feature of this scheme is that the integrity of the keel longeron can be retained between the two RCS containers.



FREEDOM

NASA

Alternate Propulsion System Configuration



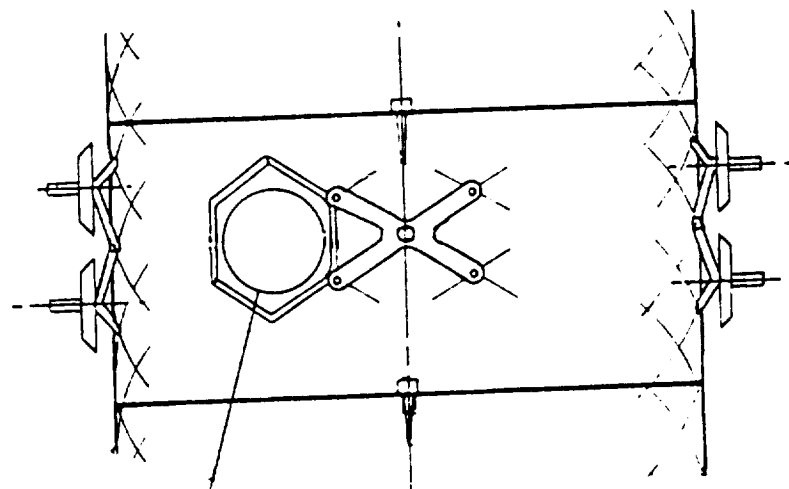
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TCS Container – Side View

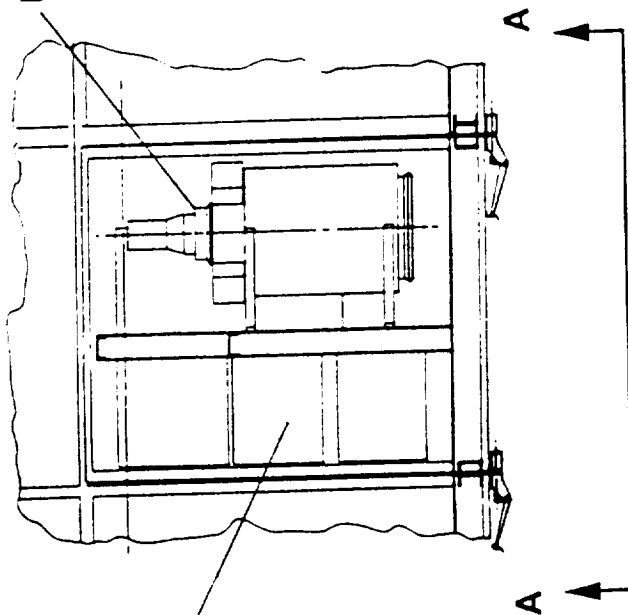
The Beta joint is located with its axis coincident with an isogrid node point. The isogrid node itself and adjacent members are removed and the opening reinforced in a similar manner to that used for the EVA access aperture (view A-A). Other TCS and distributed systems ORUs are mounted on both sides of the central framework, which also supports the beta joint. The radiator is delivered to the station, installed, and deployed on a subsequent flight.



TCS Container - Side View



Beta Joint



ORU's

Space Station

+x

+y

View A - A

LaRC SSFO

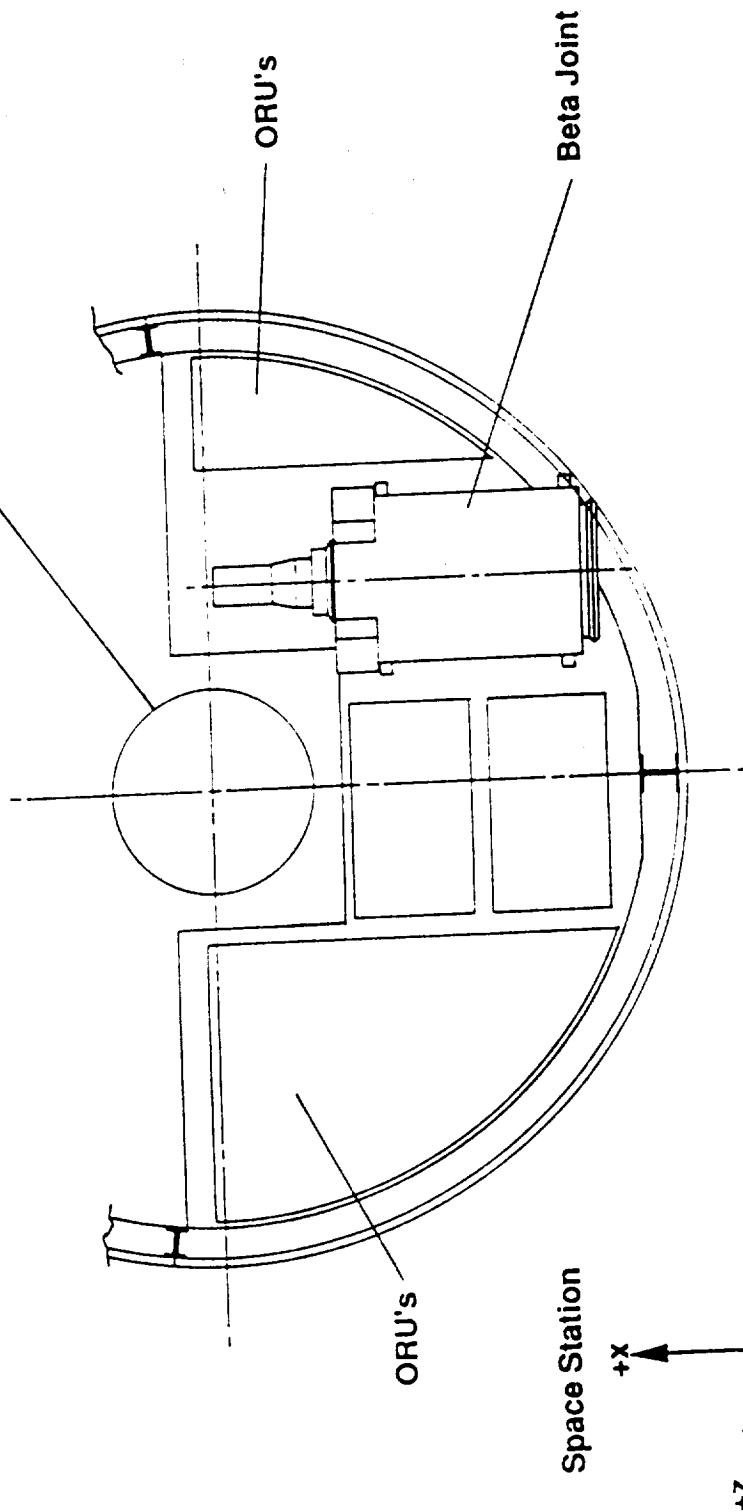
TCS Container – End View

The Beta joint and other ORUs are mounted on a pallet-like framework, which is integral to the container. The aft end (launch orientation) of the antenna support structure is attached to this framework when it is in the stowed position.



TCS Container - End View

Location of stowed
antenna support structure

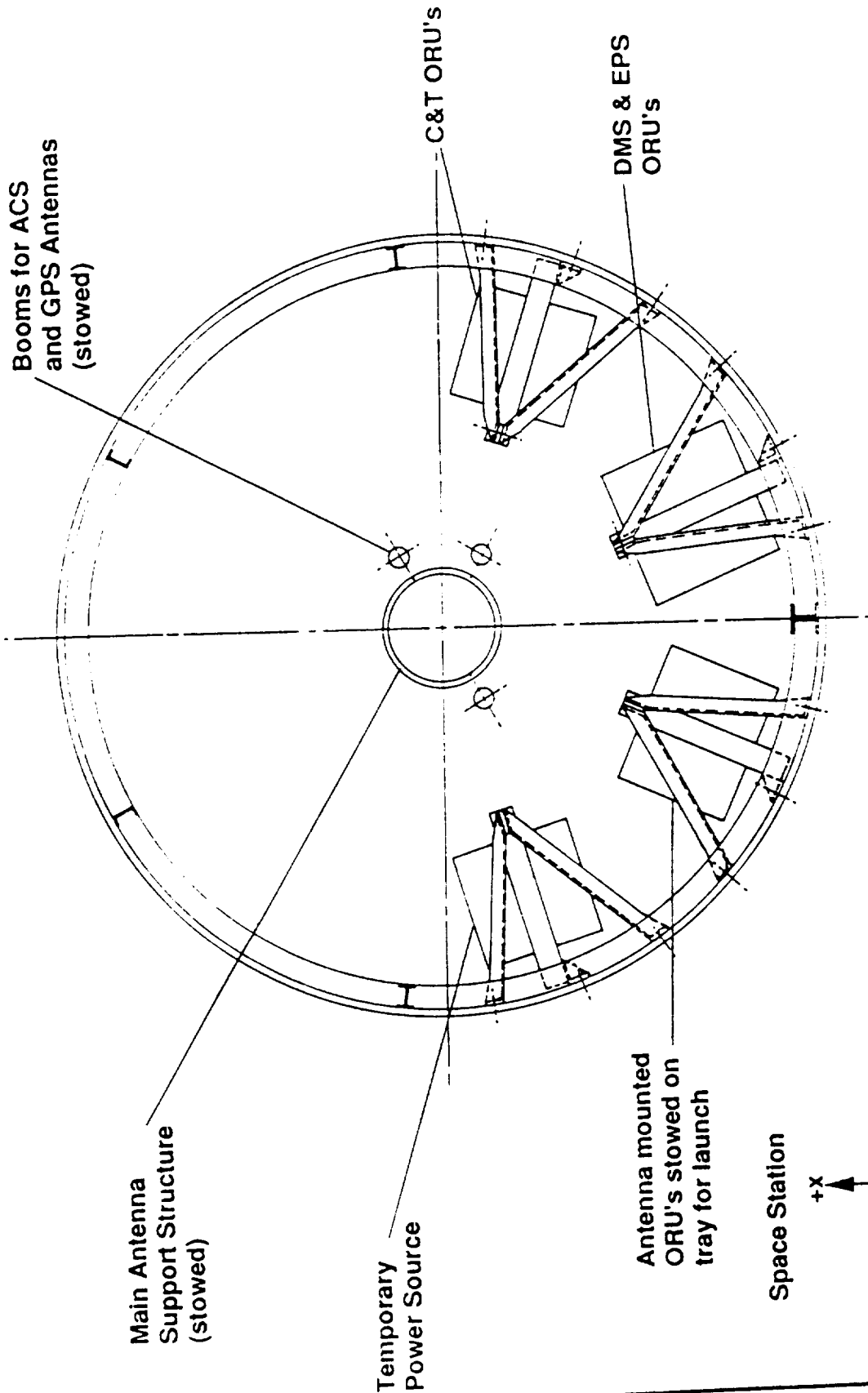


Subsystem Trays

Smaller subsystems and/or ORUs are mounted on both sides of trays which are positioned radially in a non-removable section of the tube structure. The subsystem elements which were on the baseline C&T pallet are located on two of the trays (except for the antenna mounted and GN&C components). The first tray, immediately below the antenna assembly, contains the C&T system elements. The second, adjacent to the first contains distributed system elements of the DMS and EPS systems.



Subsystem Trays

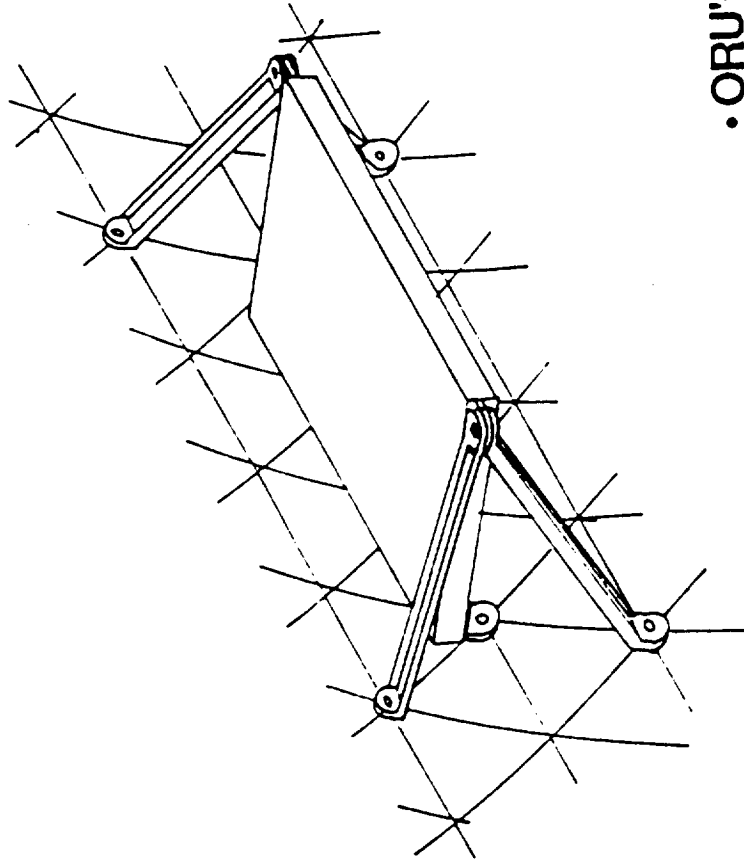


Subsystem Tray Attachment

Tray mounting brackets and support struts are attached directly to the isogrid nodes. The tray may be fixed, or utilize sliding and/or hinged rails to orient the ORUs for easier access for servicing.



Subsystem Tray Attachment



- ORU's mount on both sides of tray

Alternate Subsystem Mounting Assembly

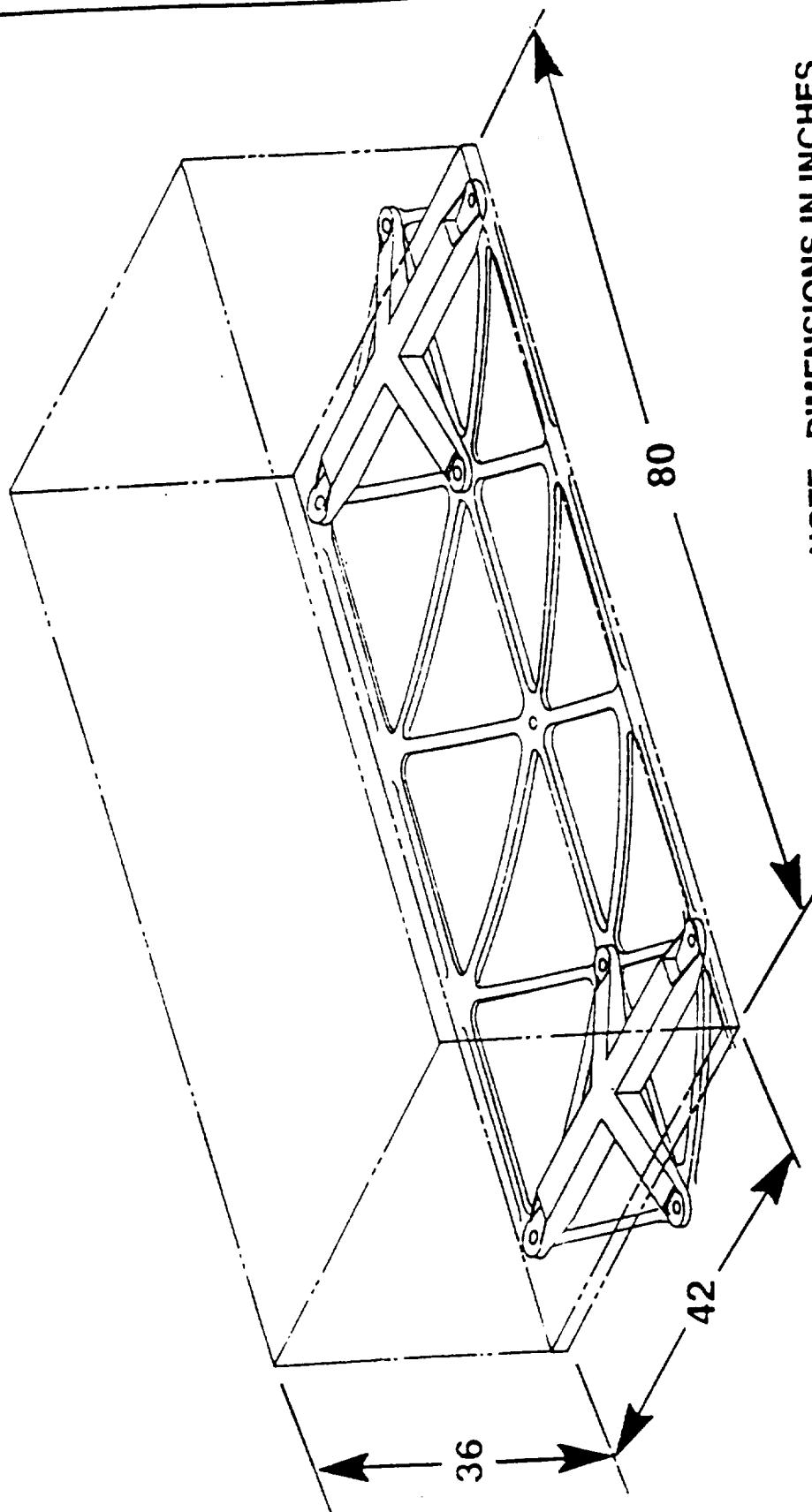
ORU's which are too large for the previous subsystem tray mounting method, but not large enough to require a complete container, may be mounted on this type of tray. It is suitable for system elements up to 80"x36"x41.5" and weighing up to 1000 lbs.

The system element is mounted on a tray (depending on specific requirements), which is supported on the isogrid via a pair of mounting brackets. The load is thereby distributed over eight isogrid nodes. The mounting assembly weighs 65 lbs.



FREEDOM

Alternate Subsystem Mounting Assembly



NOTE: DIMENSIONS IN INCHES

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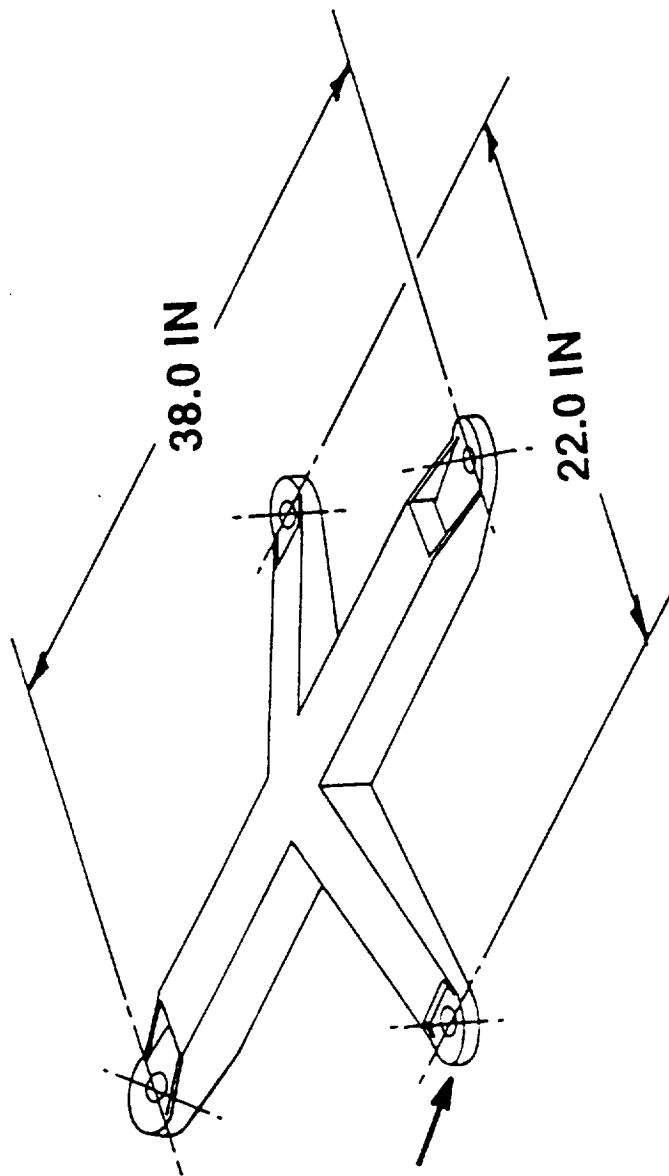
NASA

Subsystem Mounting Bracket

A typical mounting bracket to support the alternate subsystem tray spans 22" (between adjacent node points) by 38" (twice the height of a single isogrid segment) to spread its load over four nodes.



Subsystem Mounting Bracket



Attaches to isogrid
nodes at 4 points

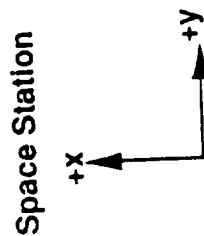
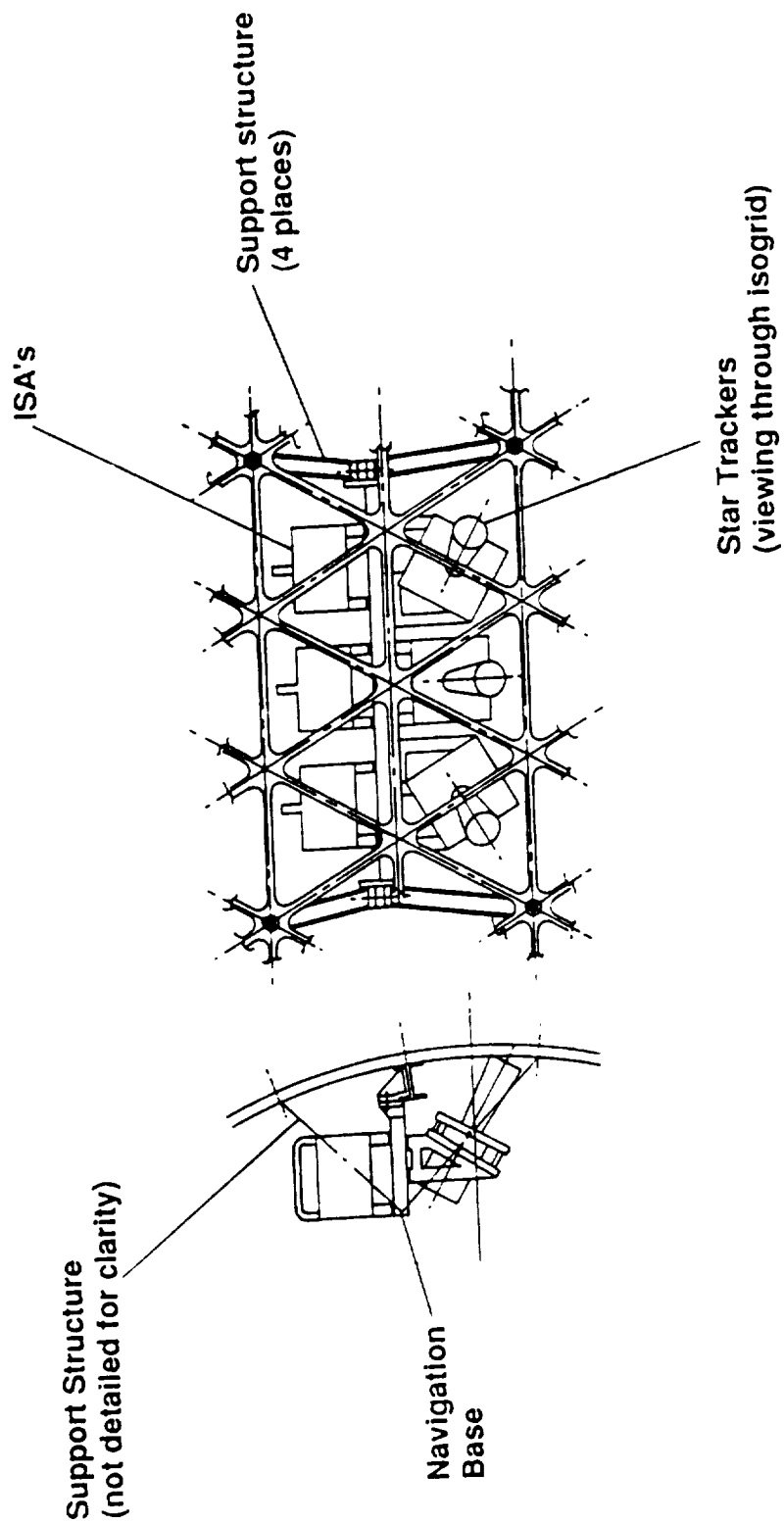
2 per subsystem (typical)

GN&C ORUS

The navigation base is attached to the isogrid within the central EVA access area. This location permits viewing angles which avoid obstruction by the Ku-Band antenna. The star tracker's view is through the isogrid openings. The collocation of star trackers and ISAs on a single navigation base is retained, but they are mounted on opposite sides for ease of replacement and to minimize incursion into the EVA access volume.



GN&C ORU S



First Element Launch – Flight TR1

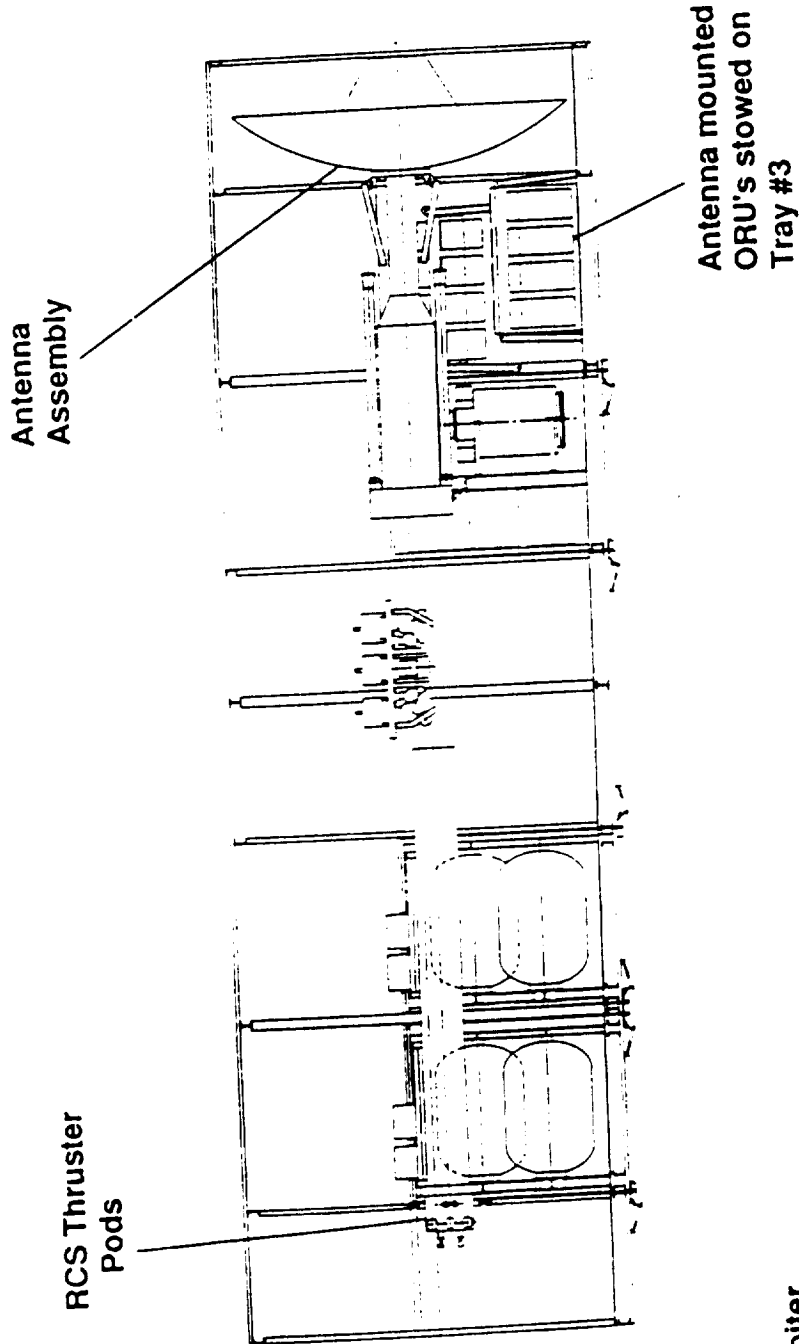
Stowed Items

The RCS thruster pods are stowed on top of the RCS containers one on each side of the center line of the main tube structure. The thrusters themselves, being within the EVA access area placing their mass toward the aft end of the orbiter payload. The Ku-Band antenna assembly is mounted axially within the tube at the forward end with the deployable booms folded along its length.

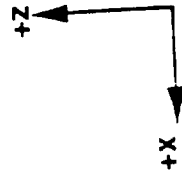


First Element Launch - Flight TRI

Stowed Items



Orbiter



Stowed Items

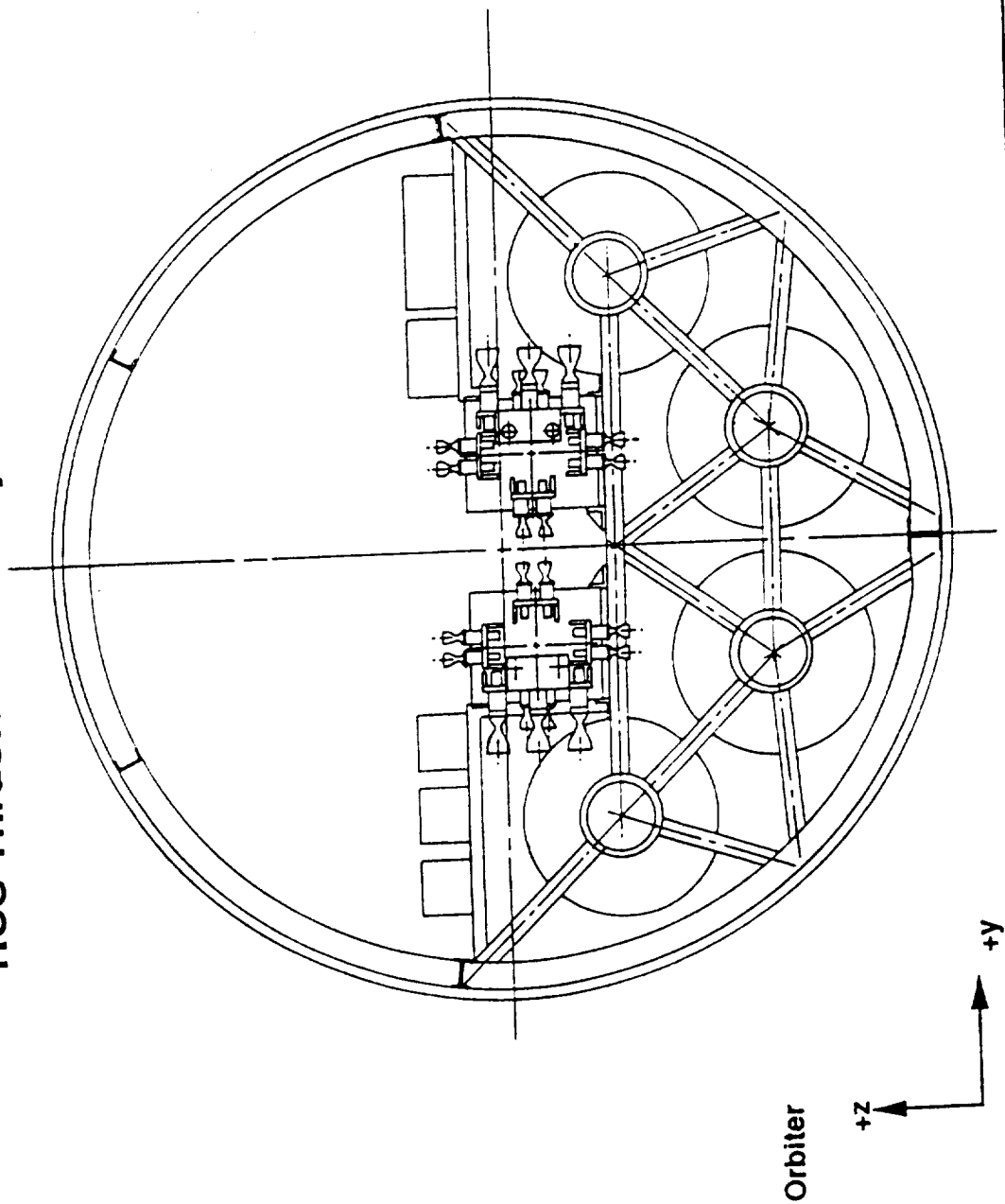
RCS Thruster Assembly – Stowed

This figure shows the thruster assemblies stowed for launch. They are attached to the RCS container tank support structure by means of brackets and latches (FSE). In operation the booms are attached to the outside of the isogrid (after on-orbit assembly), and the thruster pods at the ends of the booms may be separate ORUs.



Stowed Items

RCS Thruster Assembly - Stowed



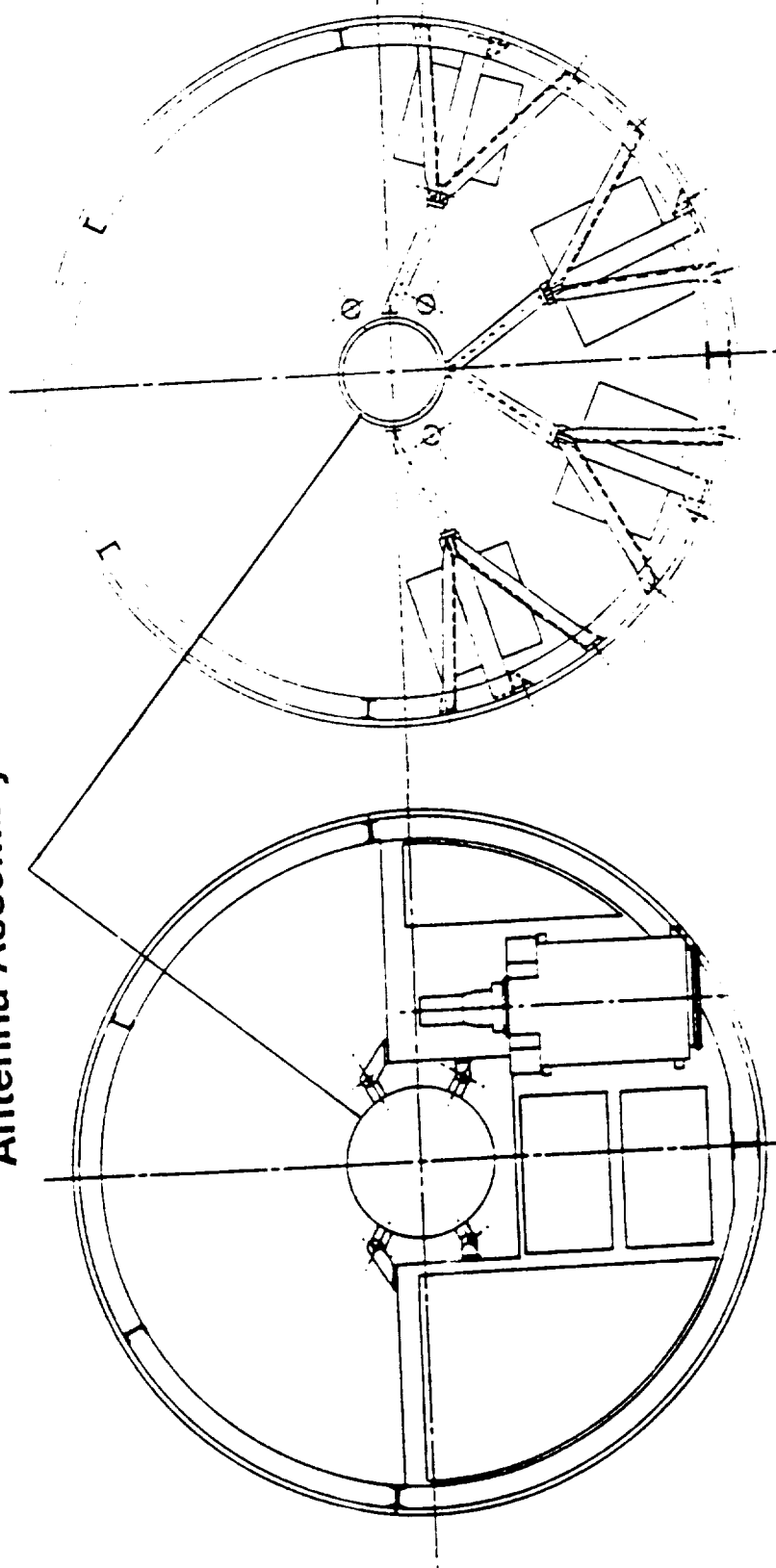
Stowed Items
Antenna Assembly – Stowed

The base of the stowed antenna assembly is secured to central framework of the TCS Container by four brackets brackets and latches (FSE). The forward end is similarly secured on four struts attached to the ORU mounting tray supports.



Stowed Items

Antenna Assembly - Stowed



Orbiter

+z

+y

Forward Attachment to
ORU Mounting Tray supports

APE Attachment
to TCS Container

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Stowed Items

Antenna Assembly – Operational

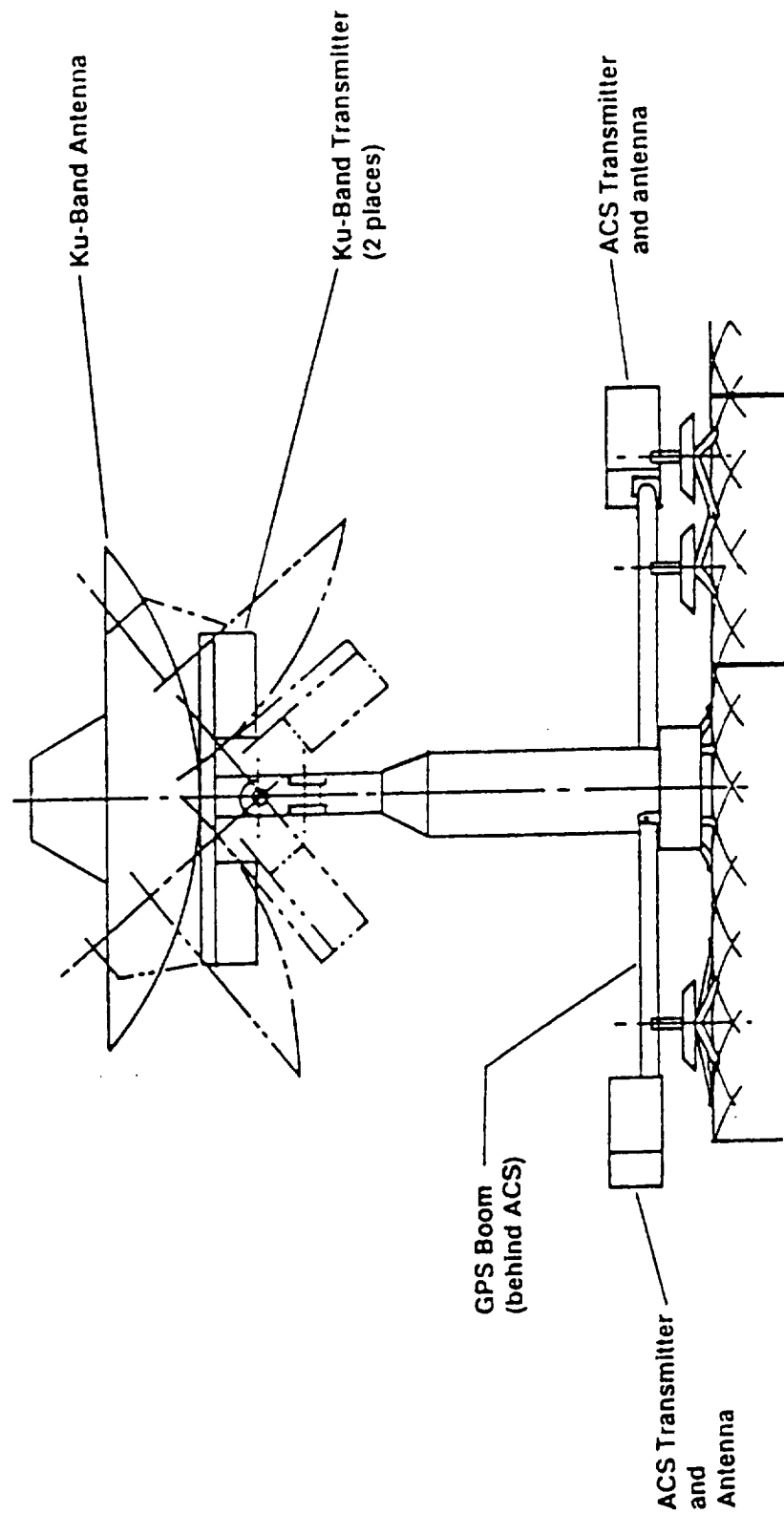
The base of the antenna assembly is attached at six isogrid nodes. The antenna support structure includes a main tubular member (possibly an isogrid structure) to support the Ku-Band parabolic antenna with five deployable booms incorporated in the assembly. The two upper booms accommodate the Ku-Band Space to Ground System (SGS) transmit/receive units. Two of the three lower booms provide attachment points for the S-Band Assembly Contingency System (ACS) transmit/receive units. The third is an accommodation for the Global Positioning System components to be installed on a later flight. Each of the booms is secured and deployed using a system of latches and hinges similar to the baseline system.

The above mentioned antenna mounted ORUs are attached to an unused subsystem tray during the launch phase. These are the same ORUs as are antenna mounted in the baseline station with one exception. The SGS antenna controllers are mounted on the antenna structure in the baseline, but in this design, are integrated on a subsystem tray located at the base of the antenna support structure along with the other C&T ORUs.



Stowed Items

Antenna Assembly - Operational



Packaging Mechanisms for FEL Summary

This study of system configurations and mounting methods demonstrates the following advantages and disadvantages.

Advantages:

- i) Many options exist for methods of mounting system hardware.
- ii) A degree of modularity is possible for the mounting methods creating the opportunity to design common elements.
- iii) The numerous attachment points (one at every isogrid node), permit flexibility in the location of subsystem hardware.
- iv) Micrometeoroid/debris shielding may readily be attached over the isogrid, or integrated into the structure itself.

Disadvantages:

- i) The precise location of attachment points is fixed at the grid nodes. Optimization of the grid size and reinforcing structure could minimize this effect.
- ii) The system hardware generally appears as concentrated loads, which during launch (the highest load condition), are reacted at the fixed orbiter attachment points. The distribution of these loads requires significant reinforcement of the isogrid structure.

Packaging Mechanisms for FEL

Summary

Advantages

- Flexibility of attachment methods
- Numerous attachment points
- Ease of attaching micrometeoroid/debris shielding

Disadvantages

- Isogrid restricts precise location of attachment points for subsystems to predefined nodes
- Relies heavily on reinforcement rings and longerons to distribute concentrated launch loads

Comments

- Further studies are required to fully optimize this concept, particularly the grid size relative to the various ORU's, trunnion locations, etc.
- A "strongback" truss structure is also worthy of further study

Further Study

Isogrid Optimization

The isogrid structure offers flexibility of attachment methods, which may be applied to many types of ORUs and/or payloads. It provides numerous attachment points for subsystem elements, although the fixed spacing of the isogrid does predefine the precise attachment locations.

The optimum isogrid spacing may be other than 22 inches, and may result in better load distribution and/or improved ORU attachments. For example, it may be advantageous for the isogrid used for the container shells to be a different grid size than that of the main truss section, or for the section above the main longerons to be other than that for the sections between the longerons and the keel.

Strongback Approach

This study has focused on the isogrid as a primary structure, and has shown that significant reinforcement is required to handle launch loads, which are concentrated at the orbiter attachment trunnions. A strongback truss structure comprised of longerons at the trunnion locations may provide the basis of an optimal structure for reacting launch loads, as well as more readily utilizing existing hardware mounting configurations.

The isogrid may be viewed as a secondary structure, and incorporated as required to provide torsional rigidity and to carry distributed loads. This approach may result in a lighter isogrid form, which could be applied in selected areas. These areas would benefit from the addition of a torsional stiffening structure, and/or from the positive attributes of the isogrid for mounting items such as utilities and micrometeoroid shielding.



Further Study

- Optimization of grid size relative to the various ORU's, trunnion locations, etc.
- A "strongback" truss structure is also worthy of further study.

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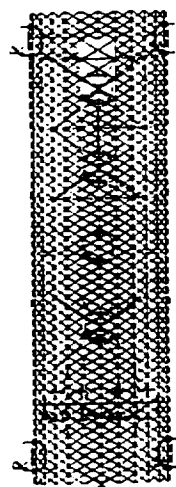
Structural Analysis

Isogrid Truss Finite Element Model

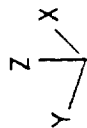
Here are three orthographic views and an isometric view of the finite element model created to represent the analysis case. The model contains 919 nodes and 2489 beam elements and rigid body elements. All internal subsystems are included as rigid body elements, but are connected to the structure with flexible beam elements. The TCS and RCS systems are included in removable containers that will simplify changeout on-orbit. The container attachments to the rest of the truss are modeled here by rigid body elements that are constrained only in selected directions to simulate the actual attachment devices that are presented in the Packing and Mechanisms section of this addendum. Utilities are included as non-structural mass, so they provide no structural rigidity to the model though their mass effects are included. Trunnion fittings used for the interface with the orbiter are modeled as rigid bodies to simulate a stiff plate used to distribute the loads through several elements of the isogrid.

ISOGRID TRUSS FINITE ELEMENT MODEL

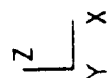
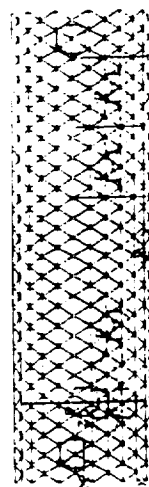
TOP VIEW



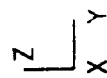
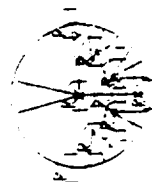
ISOMETRIC VIEW



SIDE VIEW



END VIEW



Primary Structural Mass Breakdown

The total structure required to support the payloads and withstand the expected loads has been divided into two classes - primary structure and secondary structure. The primary structure, which includes the isogrid itself as well as additional major structure needed to stiffen the isogrid, is itemized in the following table.

Primary Structural Mass Breakdown

Isogrid (44 ft section) 2768 (lbm) 2768 (lbm)

Primary Stiffening Structure

Trunnion longeron (2)

208

Keel longeron

382

Top longeron (2)

80

End Ring (2)

181

Isogrid stiffening ring
(adjacent to containers) (4)

362

Center ring (3)

294

EVA access stiffener (4)

13

Isogrid trunnions (5)

440

Connecting hardware

200

Total primary stiffening structure 2160 2160

Total primary structural mass 4928 lbm

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primary mass

Secondary Structural Mass Breakdown

The total structure required to support the payloads and withstand the expected loads has been divided into two classes: primary structure and secondary structure. The secondary structure, which is used to attach the payloads to the isogrid, is itemized in the following table.



Secondary Structural Mass Breakdown

Propulsion System (2 units)

Container stiffener	420
Tank support (fore)	200
Tank support (aft)	100
Trunnions (10)	460

Subtotal 1180 1180

Thermal Control System

Aperture reinforcement	10
Container stiffener	210
ORU support	425
Trunnions (5)	230

Subtotal 875 875

C&T System

Rack structure	180
----------------	-----

Temporary Power System

Rack structure	60
----------------	----

Total secondary structural mass 2295 lbm

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Structural Analysis Summary

Three static load cases and a normal modes analysis were used in the structural analysis. The first two cases shown were obtained from MSFC, and represent the worst case loads they expected for module-sized payloads in the orbiter during liftoff and landing, respectively. A factor of safety of 1.4 was applied to the loads received from MSFC to make them ultimate loads. The third loadcase used was the worst case presented in Attachment 1 (ICD-2-19001) (also known as Volume 14). This worst case load was found in Table 4.1.3-4: Landing of Non-Returnable Cargo. A factor of safety of 1.4 was also applied to this case in order to use ultimate loads. A normal modes analysis was performed to determine the minimum natural frequency of the entire model (this was done to ensure that the requirement that the minimum natural frequency for FEL must be greater than or equal to 8 Hz was met).

Structural Analysis Summary

Loadcase	Load Factors (Ultimate) (g's)			Max Princ Stress (psi)	Max Disp (in)
	Nx	Ny	Nz		
* 1	-6.2	-1.8	-2.7	-24410	1.430
* 2	+4.1	+0.5	+1.4	+11670	0.709
# 3	-1.7	+0.8	+3.0	-12360	0.764

Normal Modes Analysis
(within orbiter PLB) **Min. Freq. = 14.17 Hz**

- Note: The load factors above include a 1.4 factor of safety.

*** MSFC Liftoff/Landing loads**

**# Attachment 1 (ICD-2-19001) Table 4.1.3-4
Landing of Non-Returnable Cargo**

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Deformed Structure– Launch Loads

This is the deformed shape of the structure when it is exposed to the launch loads listed as Case 1 on the previous chart. The deformations have been magnified by a factor of 25 to be able to see them. The actual maximum deflection, which occurs in the isogrid along the stiffening ring between the two removable pallets, is only 1.43 inches. The maximum stress within the structure is –24410 psi, which, when considering an ultimate strength of 69000 psi, provides a factor of safety of 2.8.

DEFORMED STRUCTURE - LAUNCH LOADS

- Ultimate Load Factors:

$$N_x = -6.2 \text{ g}$$

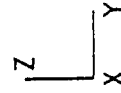
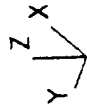
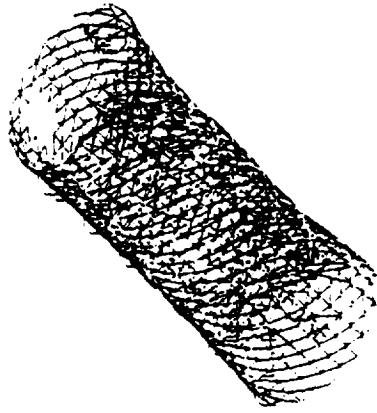
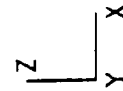
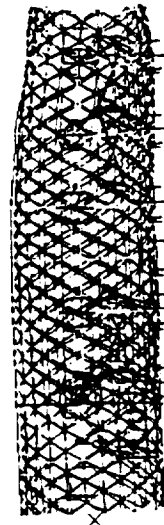
$$N_y = -1.8 \text{ g}$$

$$N_z = -2.7 \text{ g}$$

- Max. Principal Stress = -24410 psi

- Max. Displacement = 1.43 in

- Note: Scale of Deformation = 25:1



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Deformed Structure– Landing Loads

Here is the deformed shape of the structure when the landing loads listed as Case 2 on the summary sheet are applied to it. The deformations have been magnified by a factor of 25 to be able to see them. The actual maximum deflection, which occurs along the keel between the two removable pallets, is only 0.709 inches. The maximum stress within the structure is 11670 psi, which provides a factor of safety of 5.9.

DEFORMED STRUCTURE - LANDING LOADS

- Ultimate Load Factors:

$$N_x = +4.1 \text{ g}$$

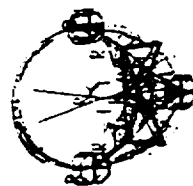
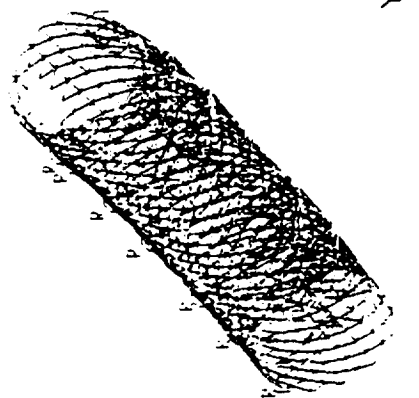
$$N_y = +0.5 \text{ g}$$

$$N_z = +1.4 \text{ g}$$

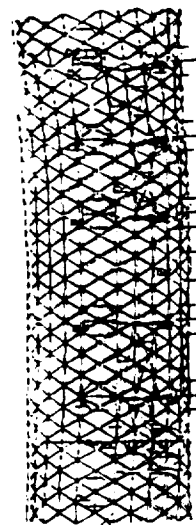
$$\text{- Max. Principal Stress} = +11670 \text{ psi}$$

$$\text{- Max. Displacement} = 0.709 \text{ in}$$

$$\text{- Note: Scale of Deformation} = 25:1$$



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Deformed Structure- Abort Landing Loads

The deformed shape shown here occurs when the loads listed as Case 3 are applied to the structure. The deformation have been magnified by a factor of 25 to be able to see them. The actual maximum deflection, which occurs along the keel between the two removable pallets, is only 0.764 inches. The maximum stress within the structure is 12360 psi, which provides a factor of safety of 5.6.

DEFORMED STRUCTURE - ABORT LANDING LOADS

- Ultimate Load Factors:

$$N_x = -1.7 \text{ g}$$

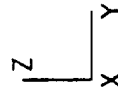
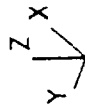
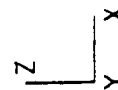
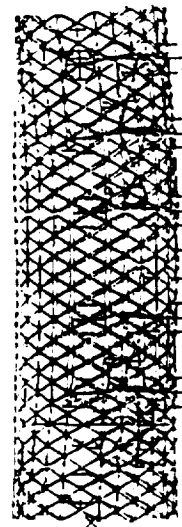
$$N_y = +0.8 \text{ g}$$

$$N_z = +3.0 \text{ g}$$

$$\text{- Max. Principal Stress} = -12360 \text{ psi}$$

$$\text{- Max. Displacement} = 0.764 \text{ in}$$

$$\text{- Note: Scale of Deformation} = 25:1$$



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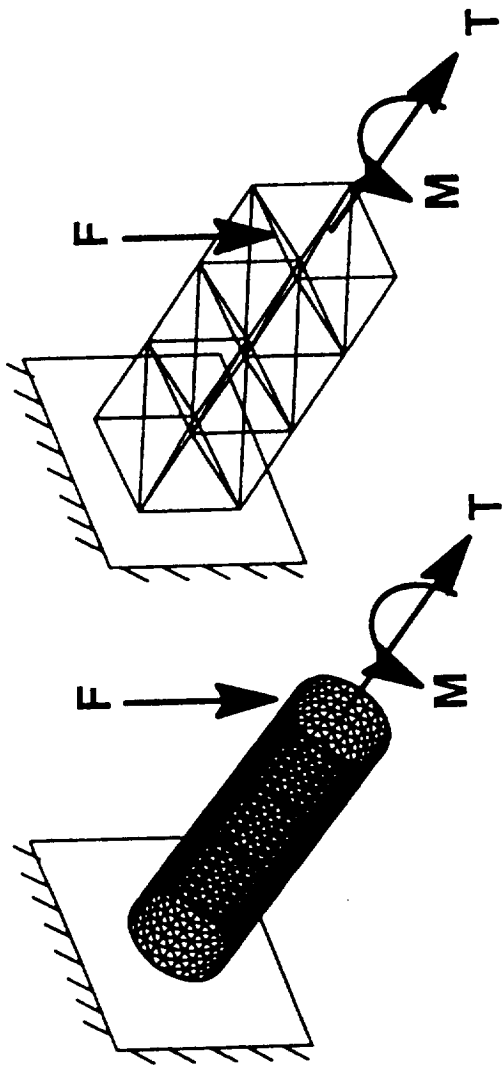
Stiffness of Isogrid vs. SSF Box Truss

A stiffness comparison analysis was performed between the isogrid truss structure and three bays of 5-meter SSF box truss. The lengths were similar– the box truss was slightly longer. Both ends of each truss section were rigidized, and one end was fixed in place to cantilever the truss sections. Three different loads were then separately applied to the free end of each truss section: a tensile force (T), a bending force (F), and a torsional moment (M). The deflections at the ends of the two truss sections were then compared, with the deflections being normalized to the SSF box truss.

The isogrid truss was considerably stiffer in all respects to the SSF box truss. When stiffeners were added to the isogrid truss, overall stiffness was more than doubled when compared to isogrid alone.

The stiffness of the isogrid is, in some respects, less than that of the isogrid in the original study due to the fact that three removable container sections have been created in the model used for the study in this addendum.

Stiffness of Isogrid vs. SSF Box Truss



Ratios of stiffness in:		
Tension (T)	Torsion (M)	Bending (F)

Isogrid only

3.4

2.6

5.0

Isogrid with stiffeners

7.3

5.7

13.2

SSF Box Truss

1

1

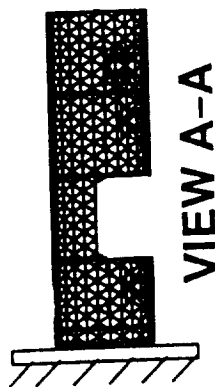
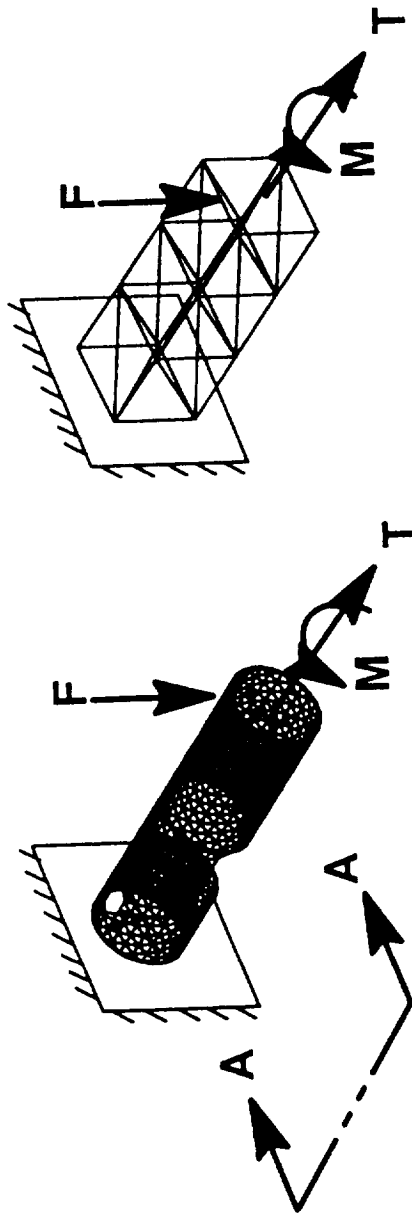
1

Stiffness of Isogrid with Container Section Removed vs. SSF Box Truss

A stiffness comparison analysis was performed between the isogrid truss structure with a container section removed and three bays of 5-meter SSF box truss. The container section removed was seven feet long and slightly over half the cylinder's diameter high.

The end conditions and loadings used were identical to those used on the previous chart with the container section in place. The removal of the container section makes a big difference in the stiffness of the isogrid truss, but it still remains more stiff than the SSF box truss. The model used in the analysis was originally created without the removable container concept in mind, so the strongest stiffener is running along the bottom of the cylinder, which is the part that is removed. If stronger stiffeners are used in areas remaining when the container is removed, the stiffness of the structure should increase.

Stiffness of Isogrid with Container Section Removed vs. SSF Box Truss



VIEW A-A

Ratios of stiffness in:		
Tension (T)	Torsion (M)	Bending (F)

Isogrid with 7 ft.
Container Section
Removed

5.3

1.3

5.6

1

1

1

SSF Box Truss

Structural Analysis Conclusions

From this analysis of the feasibility of using isogrid as the primary truss of the space station, it appears that isogrid with additional stiffening structure would provide a good framework for the space station. The isogrid is stronger, stiffer, and undergoes smaller deflections and stresses under given loads than the current baseline truss.

Structural Analysis Conclusions

- Isogrid has a greater axial, torsional, and bending stiffness than the current baseline truss
- Additional stiffening structure (ie. longerons, ring stiffeners, etc.) is needed to carry launch and abort landing loads
- The load cases analyzed produce small deflections and principal stresses
- Based upon this preliminary analysis, the use of isogrid as truss appears to be a viable option

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FREEDOM



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Thermal Analysis

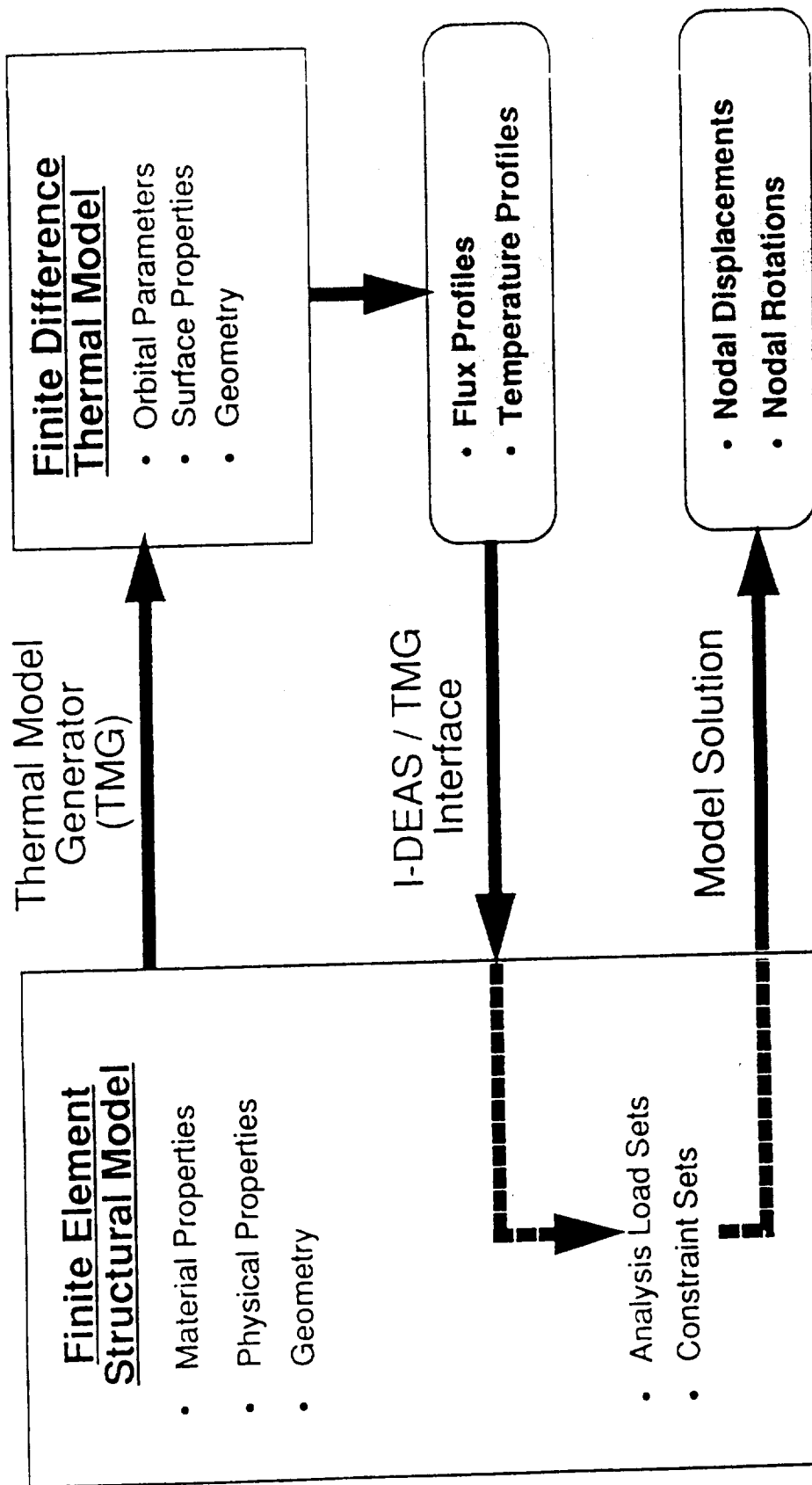
Analysis Approach

The objective was to perform a thermal distortion analysis of the preintegrated truss structure. To do so, the **finite element structural model** (MB1-806), created using the I-DEAS (Interactive Design and Evaluation of Advanced Spacecraft) CAE analysis package, was first converted to a finite-difference thermal model using the **Thermal Model Generator** (TMG) analysis package. Analysis of the thermal model determined the temperature profiles for all of the thermal nodes, which in turn serve as input load sets for the linear-static distortion analysis. The results of the distortion analysis are nodal displacements and rotations. This diagram illustrates the described analysis approach.



Thermal Distortion Analysis Approach

I-DEAS Finite Element Modeller And Analyzer



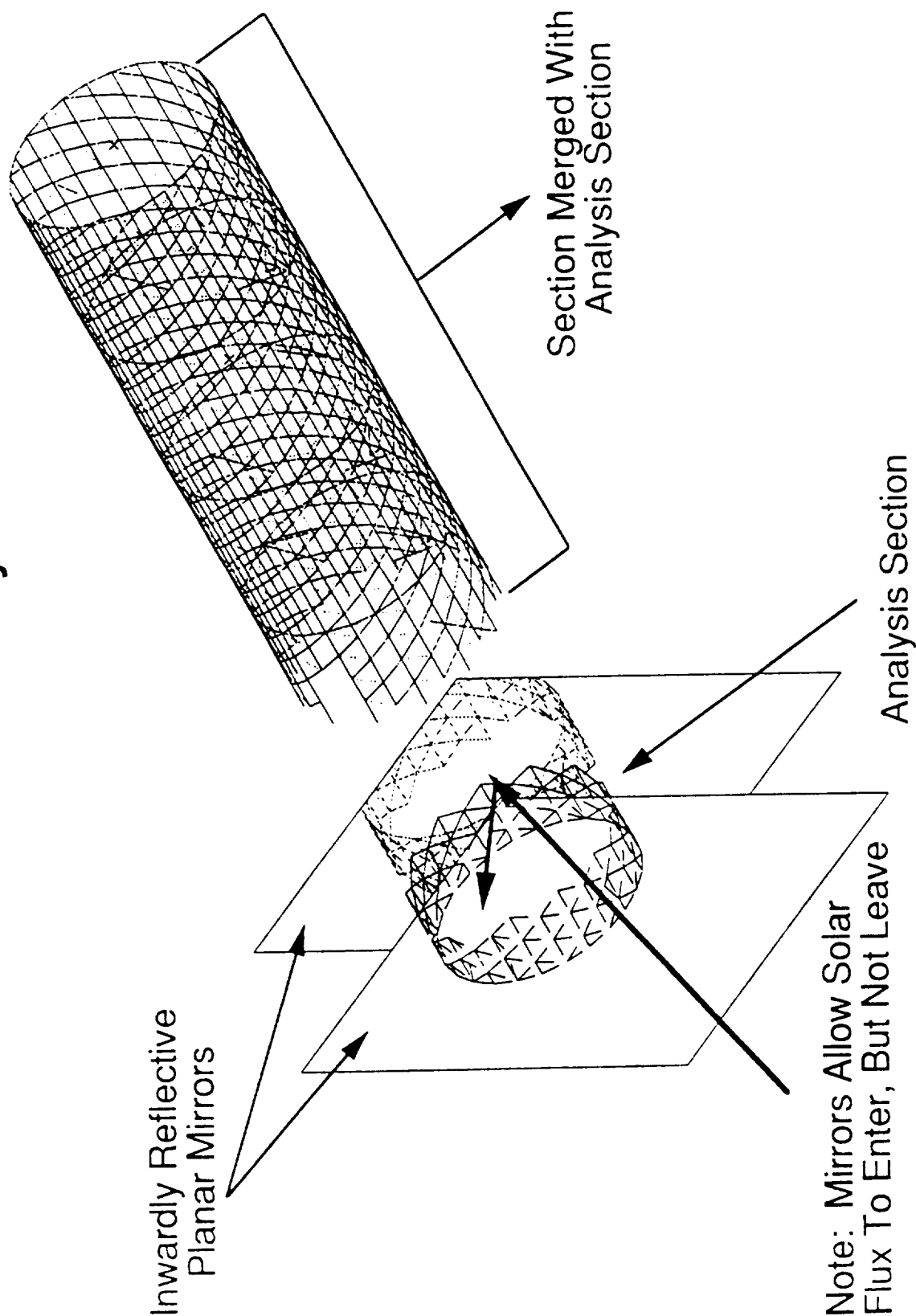
Thermal Analysis Scheme

This exploded view illustrates an analysis scheme driven by the excessive computational times typically required by complex thermal models. This issue dictated an analysis scheme that both simplified the thermal model and exploited the occurrence of symmetry in the structure. The analysis approach chosen selects a small subsection of the complete thermal model and closes it between planar, inward reflecting surfaces. Once an incident flux is reflected at these surfaces, any reflected flux can: (1) impinge on other isogrid members, (2) escape through openings in the side of the structure, or (3) be reflected again by the opposing mirror. This achieves an approximation of an infinite length of the structure.

Performing a thermal analysis on the subsection determines the temperature profiles of all thermal nodes in the subsection. To exploit the symmetry of the truss structure, it is assumed that all identically oriented thermal nodes with identical material and physical properties will have essentially the same net heat flux and temperature profiles. All isogrid members outside of the analyzed subsection are assigned temperature profiles identical to their like-oriented counterpart in the analyzed subsection. The results of the analysis are considered to be worst case for the orbital orientations studied.



Exploded View Of Thermal Model Illustrates Analysis Scheme



Assumptions

Several characteristics representative of the isogrid truss structure and its orbital environment serve as assumptions for the analysis process.



Thermal Analysis Assumptions

- Only the thermal mass in the isogrid members and longerons modelled
- $\alpha_{\text{solar}} / \epsilon_{\text{thermal}} = 0.3/0.2$ with no degradation (LDEF analogy)
- Orbit inclination = 28.5°
- Orbit altitude = 380 km (205-n miles)
- Orbit beta angle = 0°
- Earth declination = 0° (Equinox)
- Earth albedo = 0.35
- No subsystems mounted internal to isogrid section
- Structural members modelled as hexagonal tubes
- At time $t=0$, model is fully deployed and isothermal at 0°C

Orbital Configurations

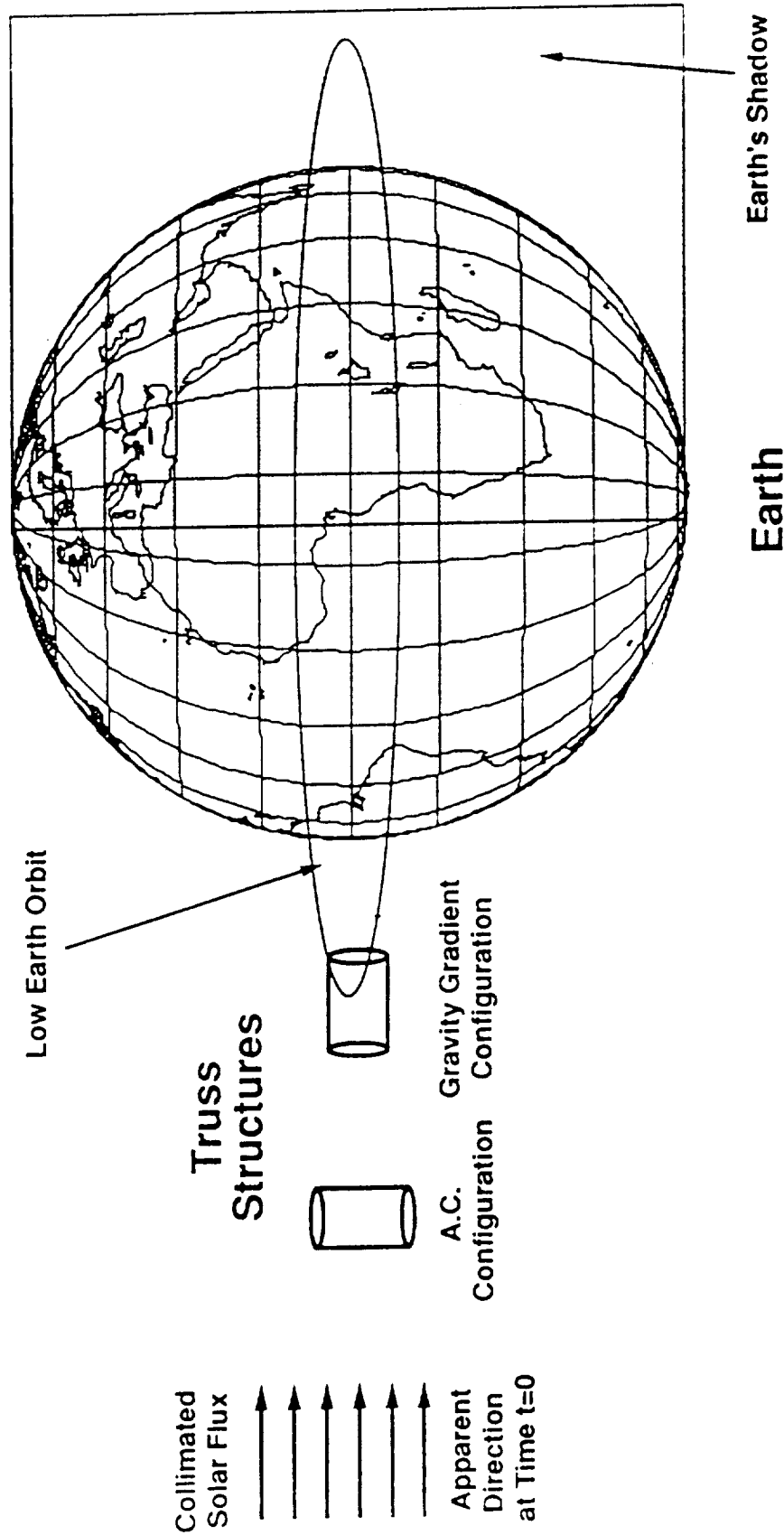
Two orbital configurations were studied. The **Gravity Gradient** configuration is applicable during the early assembly stages, while the **Assembly Complete** orientation represents the LVLH attitude of the structure during later assembly stages through **Assembly Complete**. The analysis results are characterized in three parts:

- (1) Net flux on representative elements,
- (2) Temperature profiles for selected representative elements,
- (3) Maximum thermal distortions for an end ring of the isogrid structure.

These results are presented for both orbital configurations.



Relative Orientation Of Pre-integrated Truss Structure In Two Orbital Configurations



Note: The orientation of the configurations are shown for illustration, and are not shown to scale.
Both orientations were analyzed with identical orbit parameters.

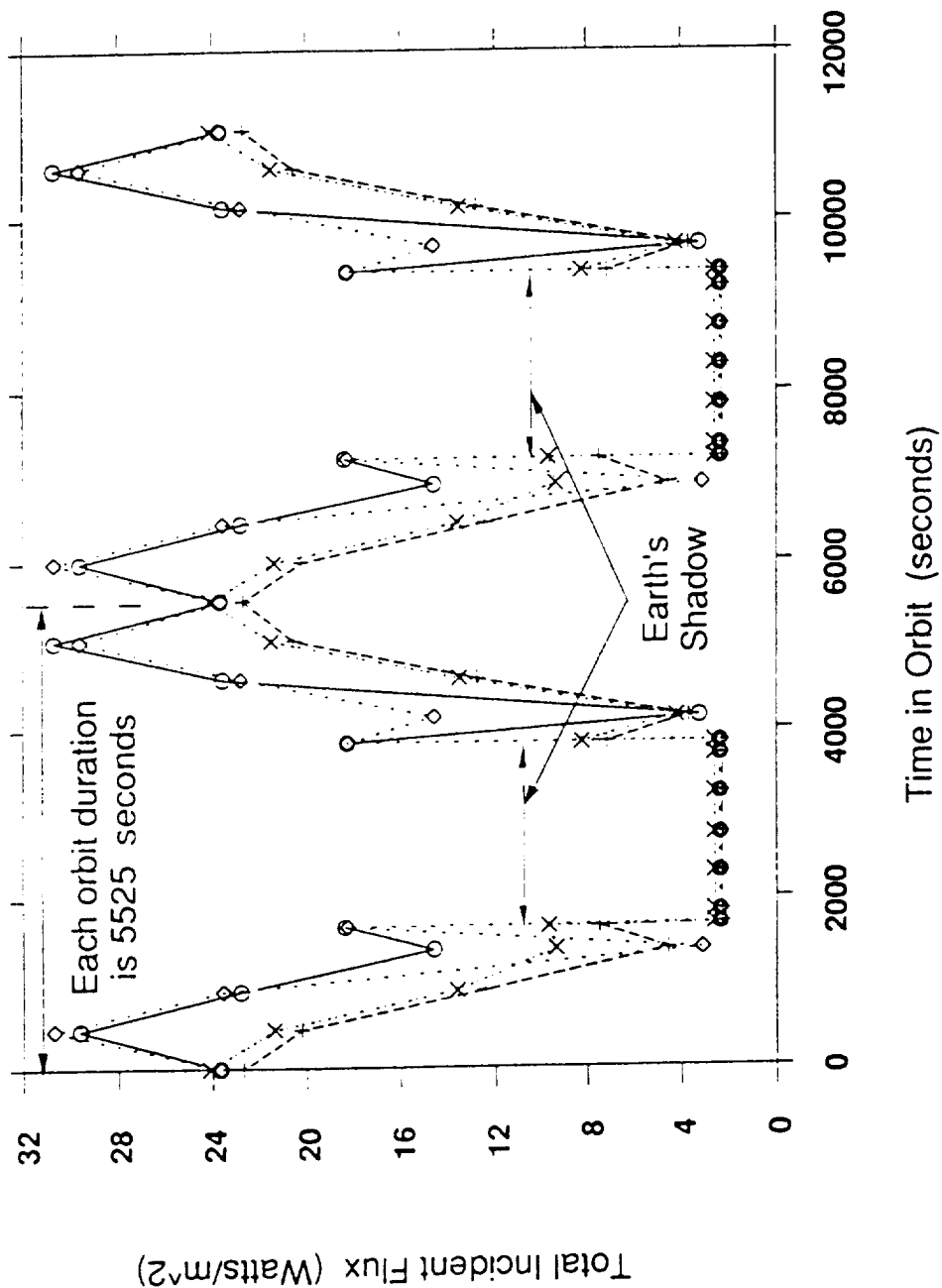
Incident Flux Profiles (GG)

The similar plots illustrated in this and the next chart depict the total incident flux on representative elements as a function of time in orbit. The representative elements were chosen based on their relative orientations, and are spaced approximately 90 degrees apart around the isogrid tube. This chart relates to the **Gravity Gradient** configuration and the next to the **Assembly Complete** configuration.

- (1) Both configurations have constant low flux periods lasting approximately 2000 (2K) seconds. This correlates to the period of time these low earth orbit (LEO) configurations spend traversing Earth's shadow during each orbital period.
- (2) The flux profiles exhibit sharp changes in magnitudes that correlate with points on the orbit where sunward isogrid members cast brief episodes of shadowing on others behind them as orbit-relative solar angles change.
- (3) Flux profiles are symmetrical and repetitive.



Incident Flux Profile Gravity Gradient Configuration

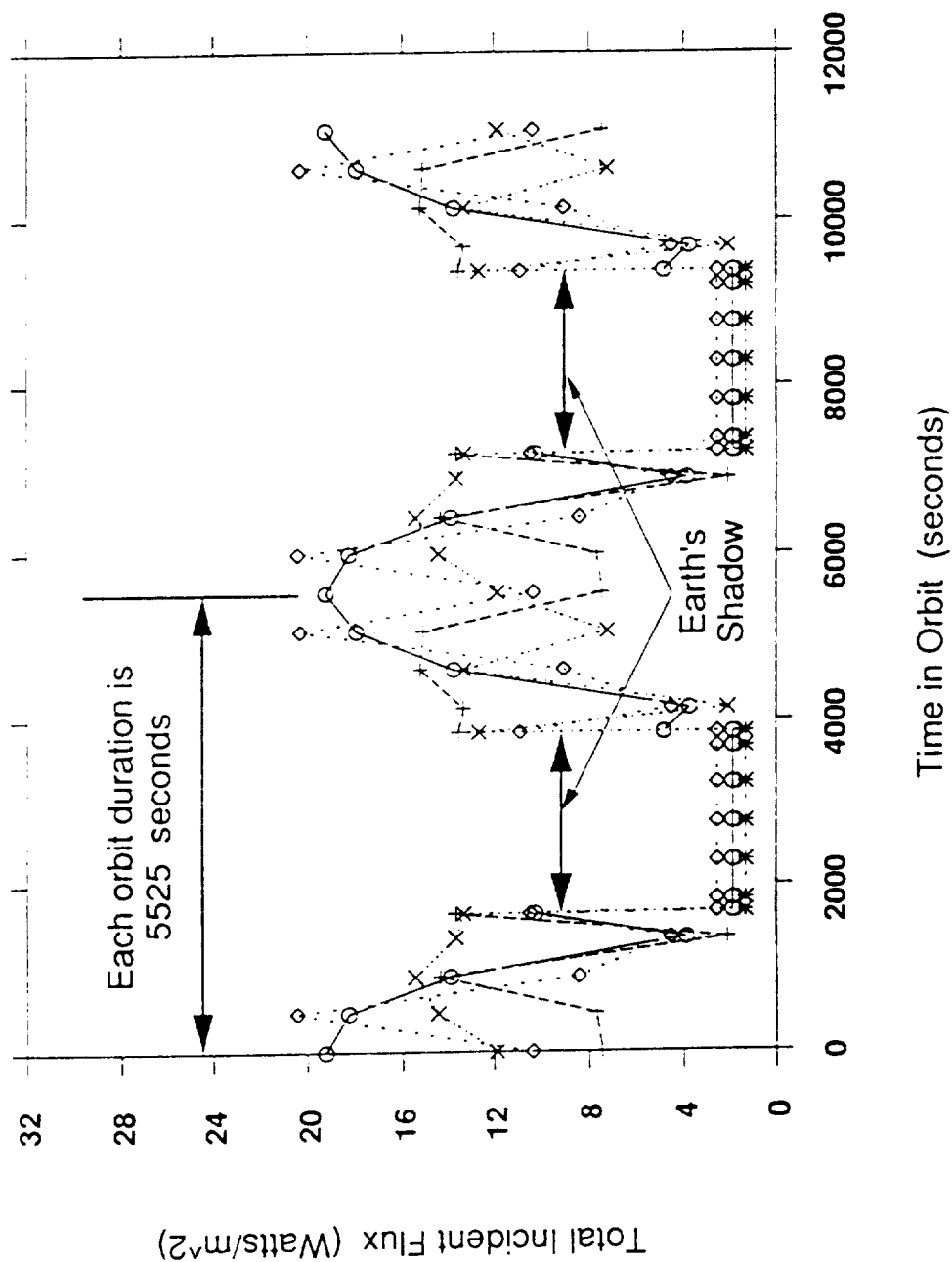


Incident Flux Profiles (AC)

In comparing the two configurations as they are represented in these two charts, it can be seen that incident flux for the **Gravity Gradient** configuration is higher than for the **Assembly Complete** configuration. Orbital flux profiles determine temperature profiles for the analysis section.



Incident Flux Profile Assembly Complete Configuration



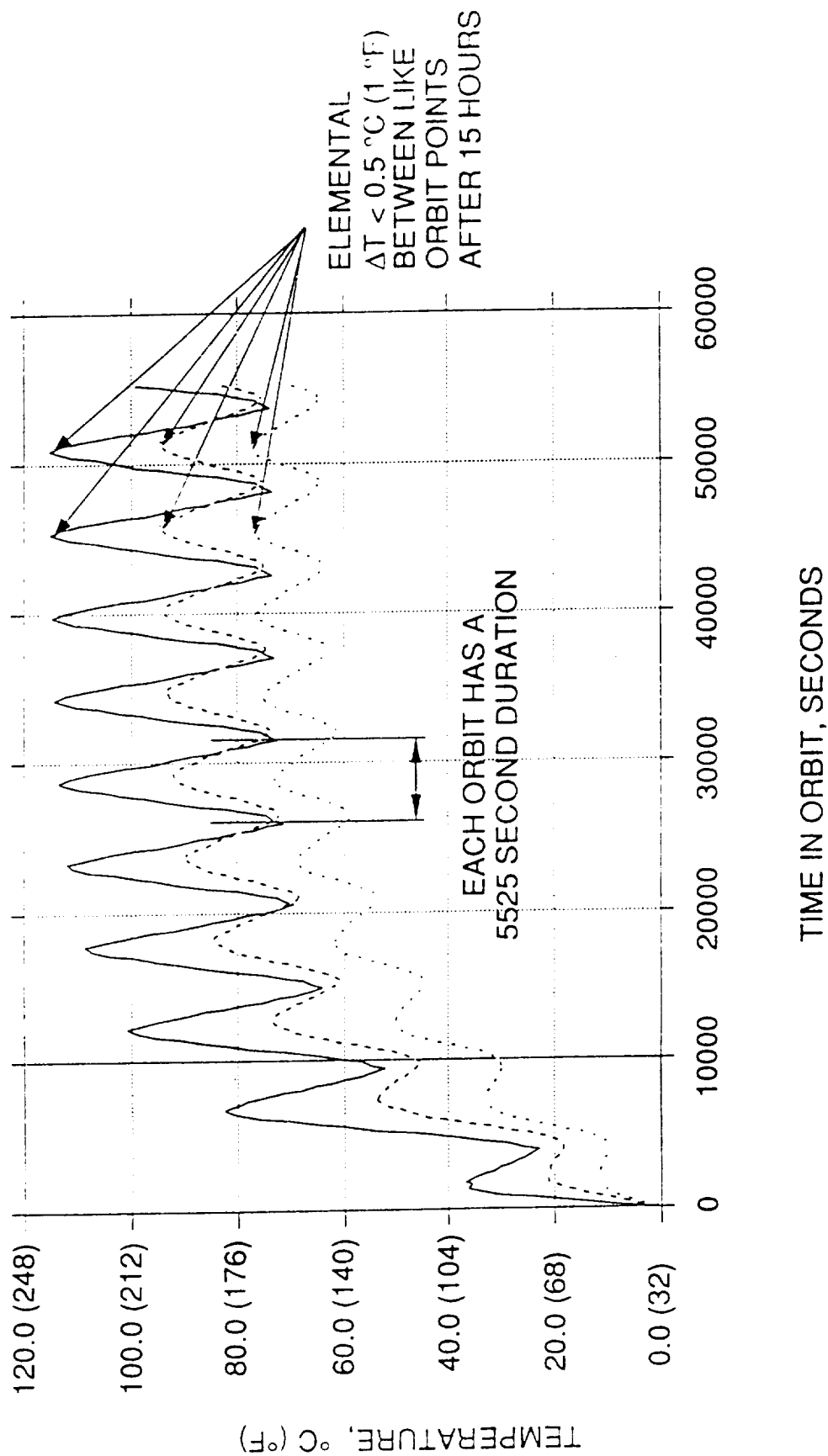
Temperature Profiles (GG)

In this and the next chart, temperature profiles are depicted for three thermal nodes, representing the maximum, intermediate and minimum temperatures of the structure for each of the analyzed configurations. The first presents the profile as given for the **Gravity Gradient** configuration and the second represents the same for the **Assembly Complete** configuration.

Both configurations achieve a steady-state orbital temperature profile in approximately ten (10) orbits, as illustrated by the recurring maxima and minima on the curves. The time required to reach a steady-state profile is within the time frame anticipated for proposed deployment scenarios.



Temperature Profile Gravity Gradient Configuration

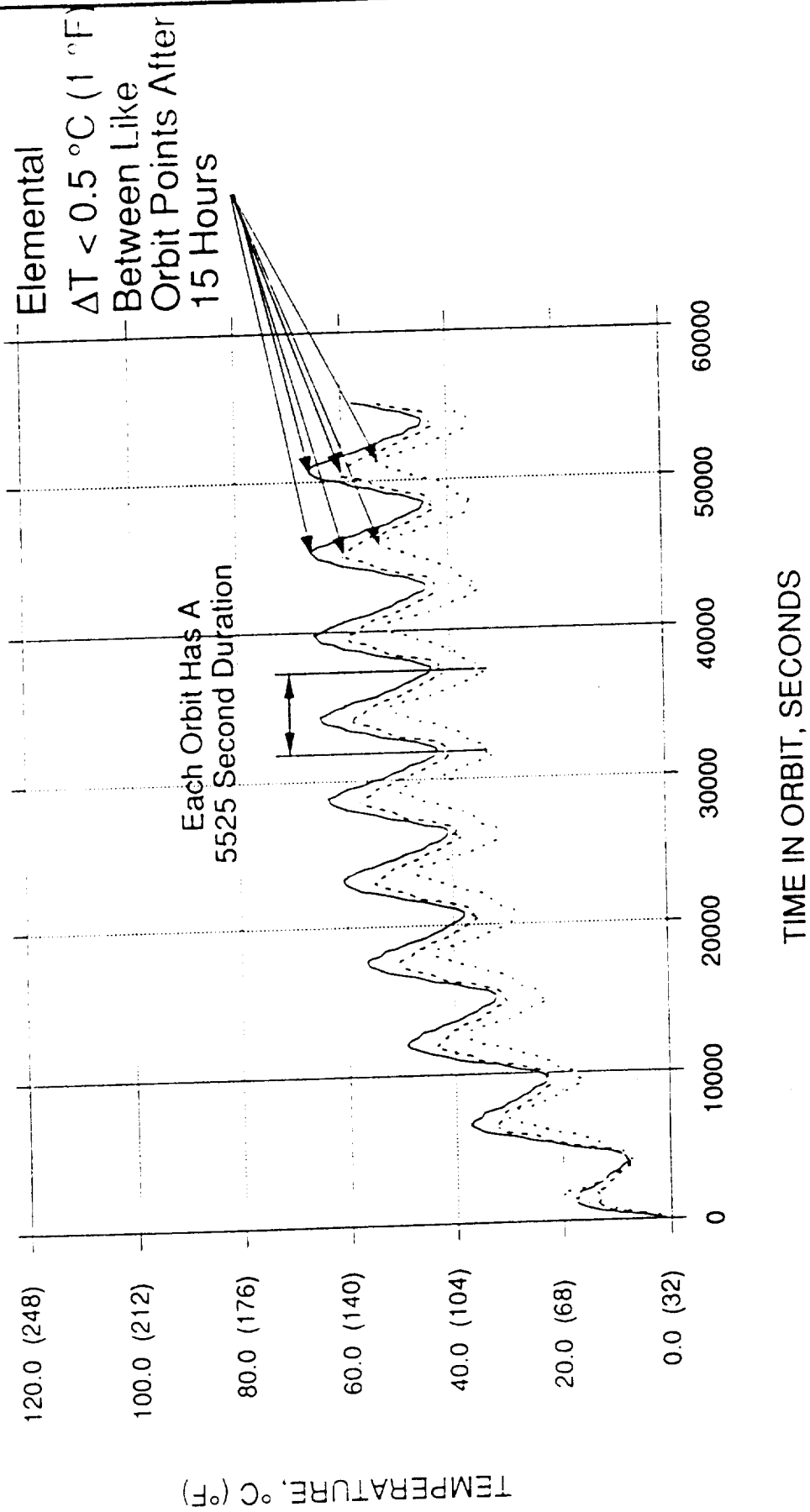


Temperature Profiles (AC)

Note that temperatures for the **Gravity Gradient** configuration are considerably higher than those for the **Assembly Complete** configuration. This corresponds with the higher fluxes noted previously for the **Gravity Gradient** configuration. Temperatures serve as load sets for the linear-static distortion analysis.



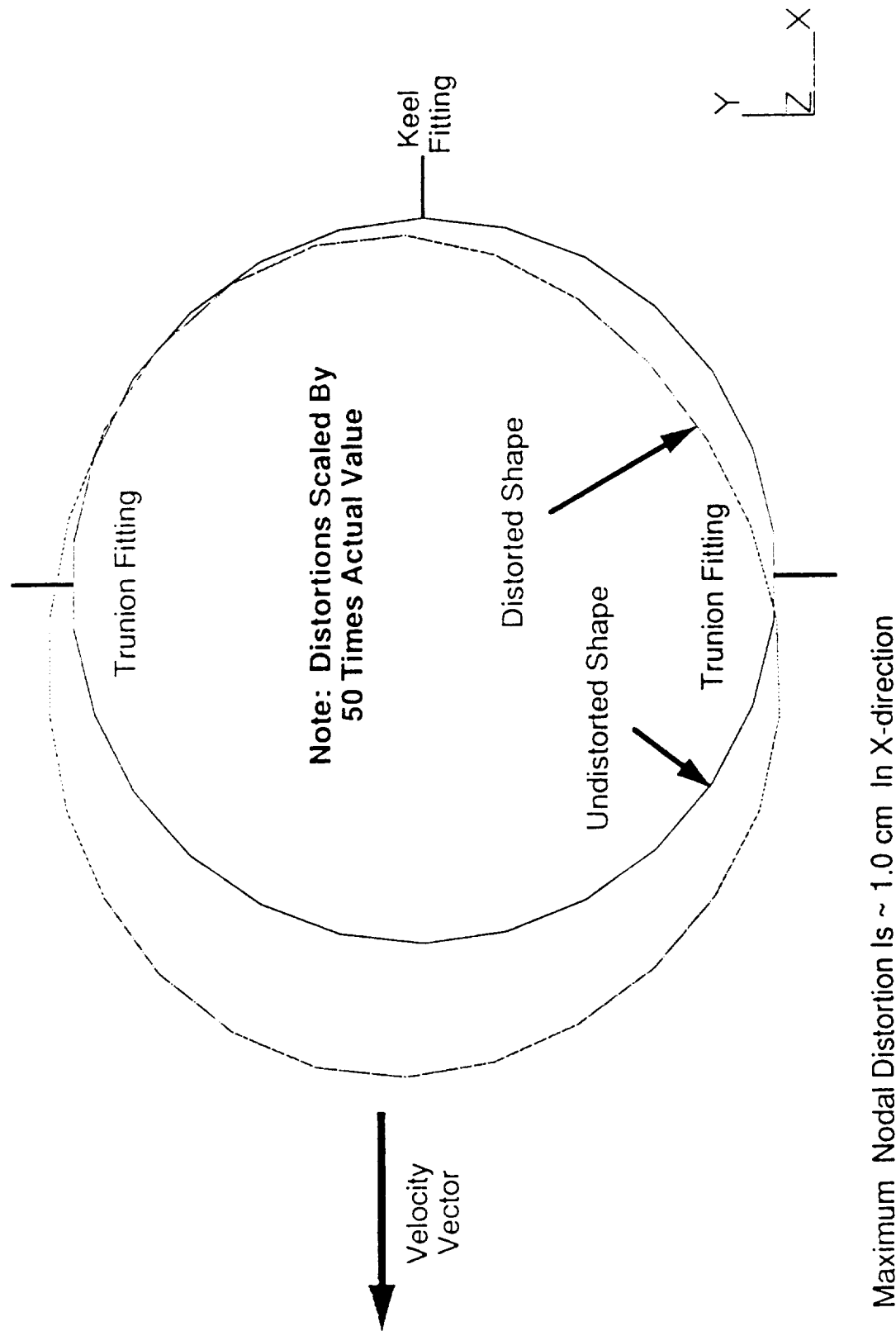
Temperature Profile Assembly Complete Configuration



Nodal Distortions (GG)

The worst case end ring nodal distortions for both configurations were in the X direction. The curves shown in this and the following chart reveal that the end-ring distortion is in the X-Y plane, which best illustrates the X-direction distortions. As illustrated in this first chart depicting the **Gravity Gradient** configuration, the worst case distortion was found in the X direction where the differential displacement between opposing nodes was 1.0 cm.

Typical Distorted Isogrid End Ring Gravity Gradient Configuration

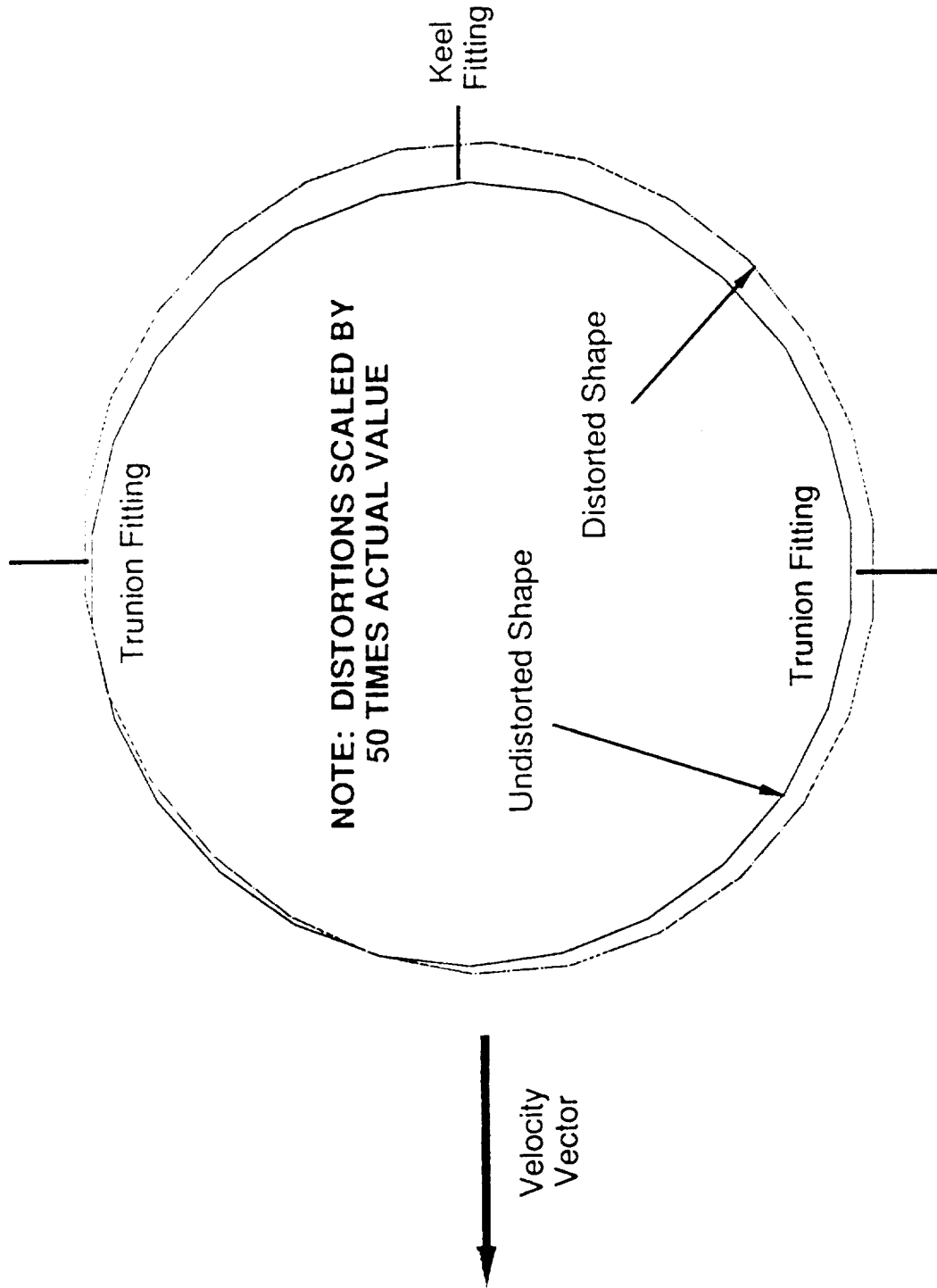


Nodal Distortions (AC)

In the **Assembly Complete** configuration depicted in this chart, the greatest distortion was in the X direction just as it was for the **Gravity Gradient** configuration, but was only 0.5 cm.



Typical Distorted Isogrid End Ring Assembly Complete Configuration



Maximum Nodal Distortion Is ~ 0.5 cm In X-direction

Conclusions

This preliminary thermal analysis indicates that the isogrid truss has a maximum thermal distortion in the end ring of approximately 1.0 cm. This distortion is not considered excessive and should allow soft-docking to occur in a very few orbits after rendezvous. To obtain the thermal profile, it was conservatively assumed that the model would initially be isothermal at 0°C (32°F) and that the starting time would correlate to an isogrid structure deployed from the orbiter payload bay. This results in a time of approximately 15 hours to reach the steady-state temperature profile, which should allow hard-docking to be performed during the second day on orbit. It is anticipated that once the soft-docked condition has been achieved, thermal coupling between the mating surfaces of the two sections will accelerate the change toward steady-state conditions.

The calculated maximum temperatures of 112°C (234°F) and maximum temperature gradient of 38°C (67°F) are higher than desired. However, as further analysis can verify, the temperatures can be substantially reduced by optimizing the material surface properties, such as decreasing the α/ϵ ratio. In addition, any further analysis should be more detailed so as to include the thermal mass and shadowing effects of the internally mounted subsystems.



Thermal Analysis Conclusions

- The calculated maximum thermal distortion in the isogrid structure end ring is not anticipated to preclude soft-docking under possible deployment time frames.
- The time to reach steady-state orbital temperature profile is compatible with hard-docking during second day on orbit.
- The calculated maximum temperatures and maximum gradients of the structure can be substantially decreased by optimizing the radiative properties (i.e., decreased α/ϵ).
- Any further analysis should include the thermal mass and added shadowing of internal systems.

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Integrated Assembly

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Manifesting Assumptions

Manifesting was performed to see how many flights it would take to build the integrated space station and to assess its functionality at each stage of the build up. PDRD target weights were assumed for all manifesting factors in order to maintain a direct comparison with the baseline assembly sequence. On flights involving the integrated truss portions of the transverse boom (designated as "truss" flights), a fifteen percent managers reserve was added as compared to the baseline sequence's five percent to account for uncertainties associated with the new packaging philosophy. Universal pallet and debris protection weights were not deleted from cargo element weights thus providing some additional margin for design growth since the hybrid isogrid structure will act as secondary support structure (universal pallet) and debris protection. An additional weight reserve of twenty percent was placed on the basic integrated structure to account for design uncertainties. The weight conservatism was implemented knowing that actual weight estimates for assembly cargo elements are significantly higher than PDRD target weights. This built in conservatism should make the integrated assembly sequence less sensitive to weight growth as compared to the baseline assembly sequence

Manifesting Assumptions

- Cargo element weights ground ruled as PDRD target weights.
- All comparisons and assumptions based on December 1989 baseline assembly sequence.
- Manager's reserve was increased to 15% to account for packaging and hardware modification uncertainties on truss structure flights.
- Universal pallet and debris protection weights were not deleted from cargo element weights resulting in additional potential weight reserve.
- An additional weight reserve of 20% was placed on the basic integrated structure to account for design uncertainties.

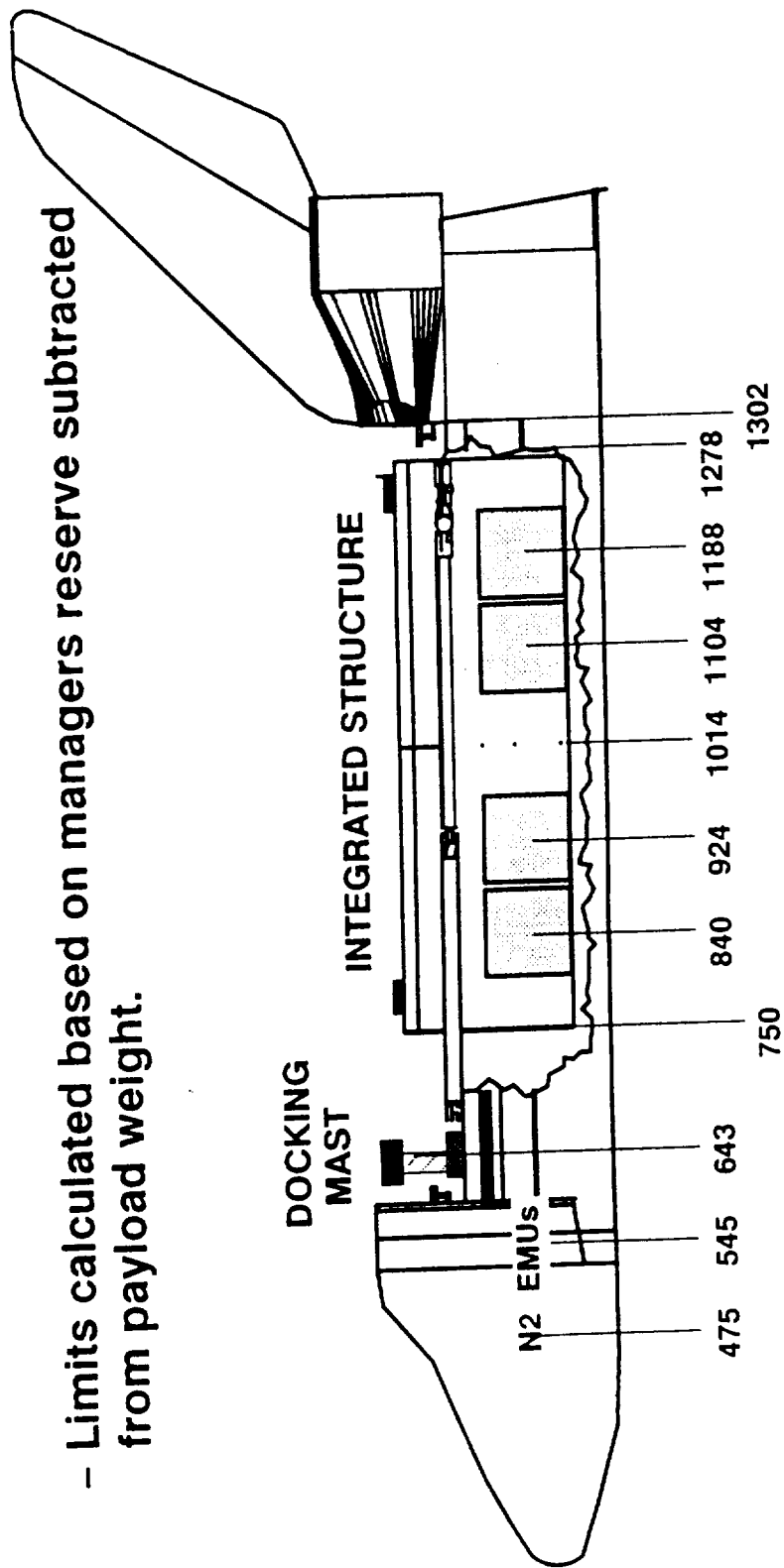
Although PDRD target weights were used in the manifest, there should be sufficient weight margin available to accommodate current weight estimates.

Locations and Assumptions for C.G. Calculations

Center of Gravity (C.G.) calculations were done in accordance with shuttle specifications that were the same as used for the baseline assembly sequence. The 44' structural section was assumed to be located with its end at the 1278 inch position in the orbiter payload bay. This allows two feet of clearance from the end of the structure to the aft bulkhead. The aft bulkhead camera was assumed not to be a problem since the structural section was only 13.3' in diameter. Since the SPDS was not used in the baseline assembly sequence its use was not assumed for the integrated assembly sequence although it could provide an additional 12 inches of C.G. margin. All C.G. calculations were based on actual payload weight and did not add in managers reserve.

Locations and Assumptions for C.G. Calculations

- C.G. limits based on Kohrs memo, NSTS-JSC TD-88-035.
- Use of SPDS not factored into calculations, reserved to increase future margins.
- Limits calculated based on managers reserve subtracted from payload weight.



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C.G. LOCATIONS

Integrated Assembly Sequence Features

The primary feature of the integrated assembly sequence relates to the great reduction in EVA and on orbit integration required to assemble the station. The ability to reduce these factors also eliminates the need for some support equipment such as the Assembly Work Platform (AWP). A direct benefit is realized on the first assembly flight since payload space and weight that is normally required for the support equipment is made available for station system elements. As a result, everything required for an active spacecraft can be brought up on the first assembly flight.

The assembly sequence assumes that 44' structural elements are used for constructing the transverse boom. Only appendages such as RCS thrusters, the Mobile Transporter (MT), the Mobile Servicing Center (MSC), PV arrays, radiators and antennas are attached external to the structural sections. The RCS fuel tanks were assumed to be in removable container sections. A module pattern consisting of six identical "common" modules was assumed in this sequence as a place holder for the station's pressurized volume with the primary focus being to complete the transverse boom from alpha joint to alpha joint before any modules were brought up. This focus could be adjusted depending on the priorities involved with early utilization of station.

Integrated Assembly Sequence Features

- "Active" first assembly flight.
- Maximizes interior packaging by using system containers.
 - Only RCS thrusters, MT/MSC, PV arrays, radiators and antennas external.
 - Fuel tanks are in removable containers.
- Uses 44 foot length hybrid Isogrid structural section.

EVA Tasks for the Integrated Assembly Sequence

Although most of the station systems and elements are pre-integrated on the ground in the 44' structural section, there are still some components such as antennas and radiators that must either deploy from or be attached to the structure. Deployable mechanisms or robotic assembly can be used to erect these appendages but for the purpose of this study EVA with RMS assistance was assumed for connection and check out of external appendages. EVA with RMS assistance was also assumed to be required for all structural and utility connections between each 44' structural element.

EVA Tasks for the Integrated Assembly Sequence

- EVA is assumed for all structural and utility connections between two 44 foot integrated elements.
- Additional EVA is assumed for connection and check out of external attached components such as antennas and solar arrays.

Integrated Configuration

The integrated configuration is assembled using eight NSTS launches for the transverse boom with the remaining assembly flights used for the pressurized modules. Four pre-integrated sections make up the portion of the transverse boom between the alpha joints (54 meters) and one pre-integrated section is used for each of the four PV power units. Proper separation (17 meters) is maintained between the solar arrays to prevent shadowing.

Integrated Assembly Sequence Summary

Eighteen NSTS flights are needed to assemble the integrated Space Station equivalent of Freedom. The first six flights bring up all but two sections of the transverse boom. These flights are designated as "TR#." The U.S. modules are then brought up (module flights are designated by "MD#") along with a combination flight, MT1, that brings up the airlock, the mobile transporter and the MSC. The last two PV power units are then delivered followed by the international modules.

Integrated Assembly Sequence Summary

FLT

- FEL 1 TR1 - Stbd TCS Equipment, two RCS tank containers, RCS thruster arms, antenna assembly, GN&C subcontainer, EPS subcontainer, temporary power unit, utilities and structure.
- 2 TR2 - IEA, solar arrays, beta gimbals, radiator, alpha joint, utilities and structure.
- 3 TR3 - CMGs (6), Stbd TCS panels and condensers, upper APAE, PMAD container, FMAD container, module interface, utilities and structure.
- 4 TR4 - Module support truss, N2O2 repressure tanks, port TCS panels and condenser, FTS with shelter, MMD with SPDM, upper APAE, module interface, utilities and structure.
- 5 TR5 - Port TCS equipment, two RCS tank containers, RCS thruster arms, antenna assembly, DMS/antenna subcontainer, EPS subcontainer, lower APAE, utilities and structure.
- 6 TR6 - IEA, solar arrays, beta gimbals, radiator, alpha joint, utilities and structure.

MTC

- 7 MD1 - U.S. Lab Module (17 racks), Pressurized Docking Module
- 8 MT1 - Airlock, Mobile Transporter, MSC phase 1, Cupola
- 9 MD2 - U.S. CHCS Module (18 racks)
- 10 MD3 - U.S. Lab Module (17 racks), Pressurized Docking Module
- 11 MD4 - U.S. Galley Module (18 racks)
- 12 MD5 - U.S. Hab Module (18 racks)
- 13 MD6 - U.S. Hab Module (15 racks), Cupola

PMC

- L1 - Logistics Module
- 14 TR7 - IEA, solar arrays, beta gimbals, radiator, utilities and structure.
- 15 TR8 - IEA, solar arrays, beta gimbals, radiator, utilities and structure.
- 16 MD7 - JEM Module
- 17 MD8 - Columbus Module

AC 18 MD9 - JEM ELM PS, JEM ELM ES, Exposed Facility #1 & #2

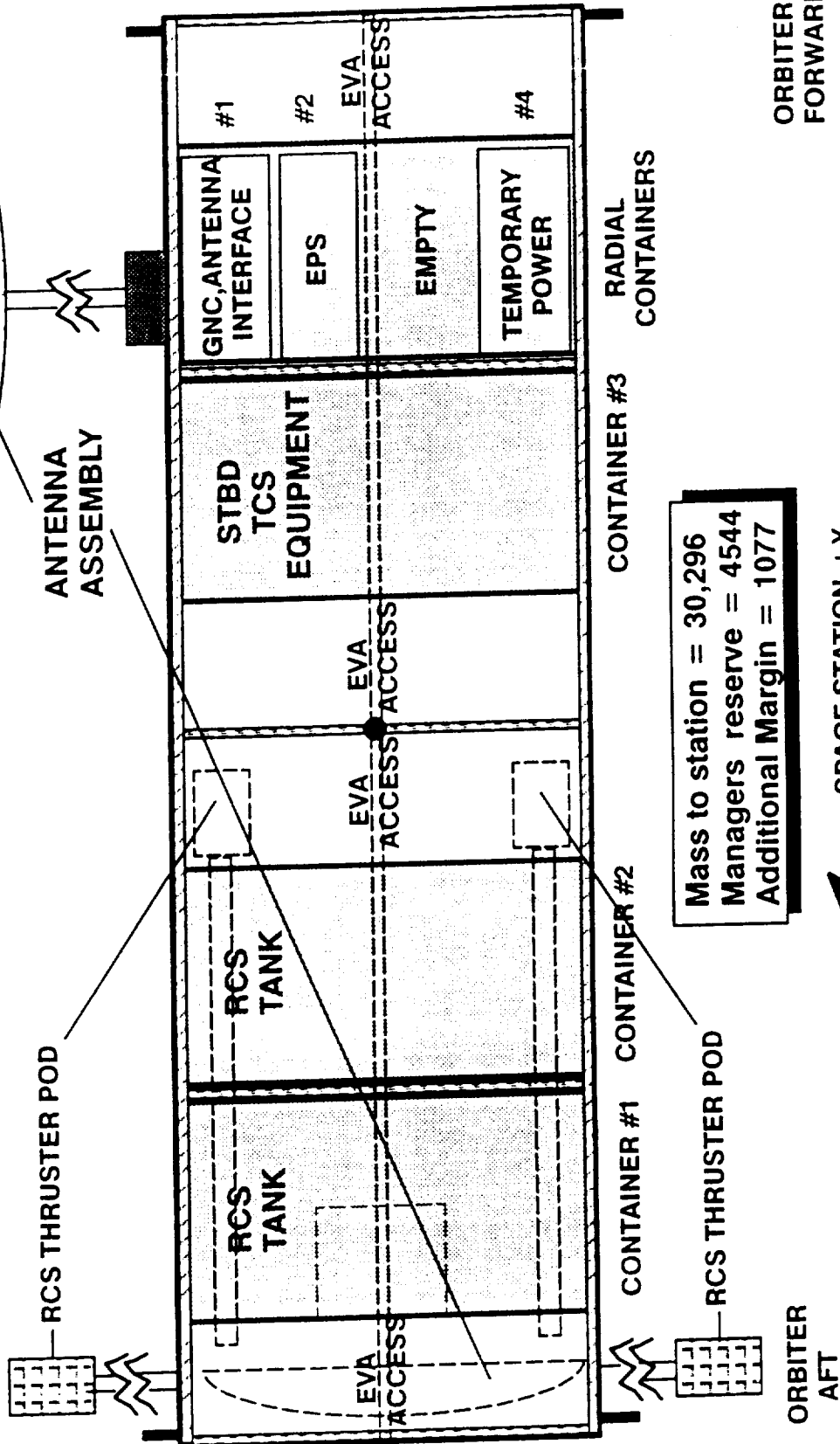
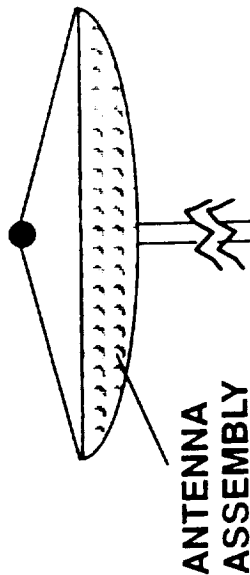
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TR1 Packaging

The first assembly flight brings up the elements that are located just inside the starboard alpha joint. All elements required to enable a minimally active/reboostable spacecraft are included on this flight. Hydrazine fuel tanks loaded with a total of 9000 pounds of fuel are located at one end of the integrated structure in removable container sections. The starboard TC'S equipment (including the starboard radiator beta joint) is located in container section three. Radial containers at the other end of the structure contain systems for communications, GN&C, power conditioning and power storage. Packaged internally are two thruster pods with extension arms and the antenna assembly. The exterior of the integrated structure is covered with a sufficient amount of solar cells to power the spacecraft once the structure is deployed. This configuration differs in some ways from the detailed structural analysis discussed earlier, but total weight and functionality are essentially the same.

Pre-Integrated Structure Packaging

TR-1



Mass to station = 30,296
Managers reserve = 4544
Additional Margin = 1077

→ SPACE STATION + Y

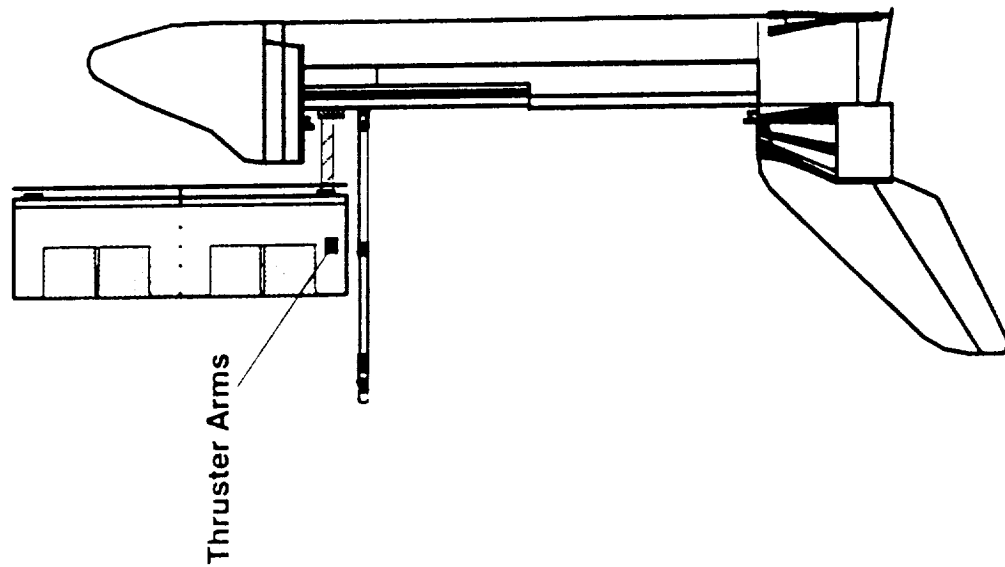
ORBITER FORWARD

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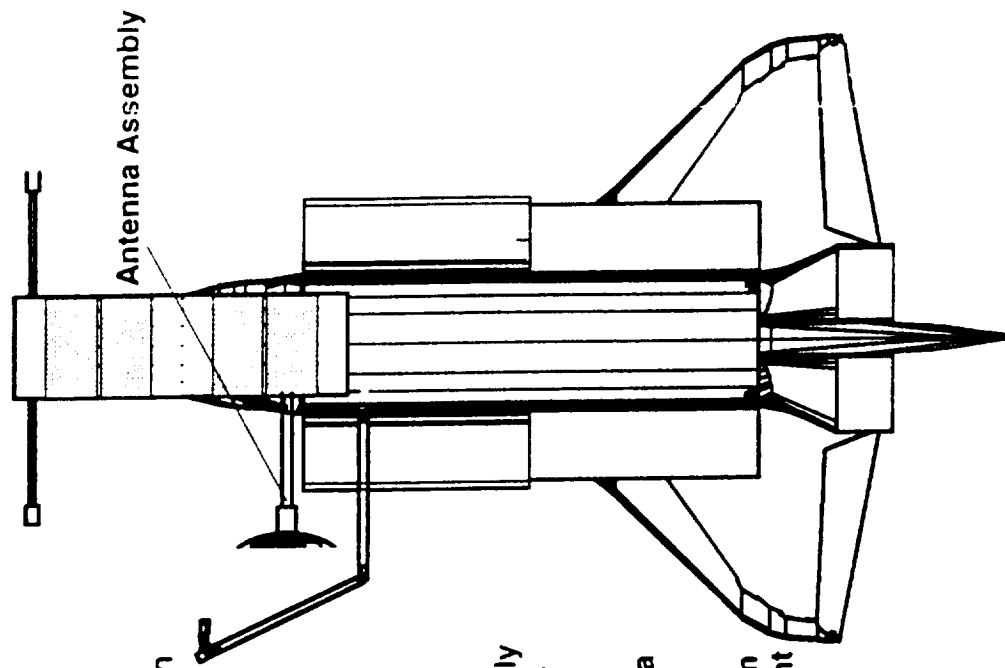
Truss Flight One Operations

The general sequence is shown for the assembly operations. No detailed study of EVA vs robotics has been attempted.

Truss Flight One Operations



STEPS 1 AND 2



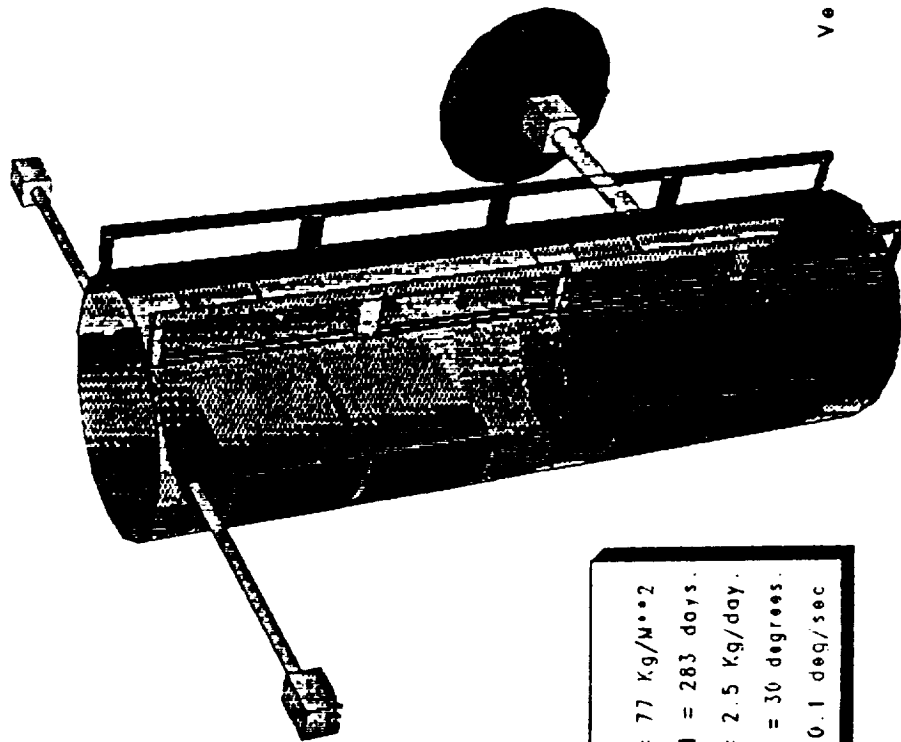
STEPS 3 TO 7

- 1) Remove TR1 structure from bay with RMS and berth to docking mast.
- 2) Remove thruster arms from structure with the RMS and attach to near end.
- 3) Rotate TR1 and berth at opposite end.
- 4) Remove antenna assembly from structure with the RMS and attach to near end.
- 5) Deploy booms on antenna support structure.
- 6) Remove transmitters from tray 3 in structure and mount on antenna assembly.
- 7) Check out systems and separate.

Active First Element Launch

A flight characteristics analysis was performed on the first element launch configuration. The station has all the necessary functionality at this point to be an active spacecraft. The flight mode is gravity gradient stable with antennas and thruster arms aligned along the velocity vector and the longitudinal axis of the structure aligned along nadir. Stability simulations showed this configuration to oscillate at most ± 45 degrees per axis with no RCS attitude control. Using RCS thrusters to hold the configuration to within a maximum deviation of 30 degrees required 2.5 kilograms of fuel a day at 190 nmi assuming a design atmosphere of $A_p = 400$ and a flux of 230. The average ballistic coefficient was 77 kg/m^2 which would give the station an orbit lifetime of 282 days if the reboost thrusters were to fail. There is sufficient reboost fuel on board to maintain altitude for many years should the orbiter be grounded for some reason.

Active First Element Launch



Mass = 13,930 Kg
 Ballistic coefficient = $77 \text{ Kg/M}^{0.2}$
 Lifetime with no reboost = 283 days
 Attitude control fuel = 2.5 Kg/day
 Maximum attitude deviation = 30 degrees
 Maximum angular rate = 0.1 deg/sec

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TR1 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the first assembly flight are listed. The overall C.G. location for the combined payload is 13.6 inches within allowable limits. There is 1077 pounds of unused STS lift capability and 4544 pounds of managers reserve available. The numbers used in this list are based on PDRD target weights and secondary structural weight estimates.

Later in the study, a more detailed analysis was done on this flight with actual system weights and structural weights derived from finite element analysis. The resulting detailed mass breakdown and center of gravity calculations are presented in the following four charts.

Integrated Assembly Sequence Manifest

FLIGHT 1
TR-1
STS
ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
STBD TCS EQUIPMENT	3018			CON#3	924
RCS PODS (2) WITH ARMS	2000	200		TUBE	1104
RCS TANK (WITH 4500# OF FUEL)	6500			CON#1	1188
RCS TANK (WITH 4500# OF FUEL)	6500			CON#2	1104
ANTENNA ASSEMBLY	608	60		TUBE	1254
GN&C,DMS/ANTENNA INTERFACE	399	100		RC#1	840
EPS SYSTEMS	811	100		RC#2	840
SOLAR CELLS/BATTERIES	1000	100		RC#4	840
STRUCTURE	8260		1100		1014
UTILITIES	1200				1014
	30296	560	1100		
HARDWARE	30296				
15% RESERVE	4544				
FSE	560				
ATTACH FITTINGS	1100				
STRUCTURAL DOCKING MAST	1550				
EVA RESERVE	2873				
SUBTOTAL	40923		CG LOCATION		1023.1
MARGIN	1077		CG MARGIN		13.6
STS CAPABILITY TO 190 NMI	42000		ALLOWABLE CG LIMIT		1009.5

LARC SSFO

Mass Breakdown Flight TR1

The mass data used for subsystems is from the Distributed Systems Deliverable listing date 05/04/90, and is the center requested PDRD weight rather than the target weight. In cases where a breakdown to smaller ORUs has been made, data from the subsystem PDR package was used. The summary mass breakdown shows a total mass to orbit of 38460 lbs. Assuming 42000 lbs load capacity for a 190 nmi orbit, this results in a margin of 3540 lbs.

Detailed mass breakdown is shown following the chart entitled "Center of Gravity Flight TR1".



Mass Breakdown Flight TRI

COMPONENT OF MASS	MASS	FSE	CG
ISOGRID TUBE STRUCTURE	4928		1015.8
PROPULSION SYSTEM	15380	200	1146.4
THERMAL CONTROL SYSTEM	3315		920.8
COMM. AND TRACKING SYSTEM	2144	160	848.7
(incl. DMS, and EPS elements)			
GUIDANCE NAVIGATION AND CONTROL	241		1003.0
TEMPORARY POWER SYSTEM	1120		849.0
UTILITIES	1200		1014.0
TOTALS	28328	360	1055.6

FLIGHT 1 MASS TOTALS

Hardware	28328
15% Reserve	4249
FSE	360
Attach Fittings	1100
Structural Docking Mast	1550
EVA Reserve	2873

FLIGHT TOTAL

38460

MARGIN

3540

STS Capability to 190 NMI

42000

Center of Gravity Flight TR1

The center of gravity summary shows a margin of 13.5 inches from the STS forward limit of 1005 inches. This corresponds to the total mass of 32338 used for the center of gravity calculation. It should be noted that the 15% reserve and part of the EVA reserve are not included in the total mass for calculation of the center of gravity.

Center of Gravity Flight TRI

Summary

	Mass	CG
Hardware + FSE	28688	1055.6
Attach Fittings	1100	1014.0
Structural Docking Mast	1550	643.0
EVA Res (part)	900	545.0
EVA Res (part)	100	475.0
TOTAL MASS for CG	32338	
CG LOCATION (see notes)		1018.4
CG MARGIN		13.5
STS CG LIMIT		1005.0

NOTES:

* 15% reserve: not in CG calc.

** EVA Reserve:

EMU 3x300#

Nitrogen

Crew 2x500# (not in CG calc.)

+1 day mission (not in CG calc.)

Incl.	not incl.
900	4249
100	
	1000
	873

Detailed Mass Breakdown and Center of Gravity Table

This table provides a detailed tabulation of the preceding summary charts.

Detailed Mass Breakdown and Center of Gravity Table

SPACE STATION INTEGRATED TRUSS ASSEMBLY CG TABLE

Code: P = Preintegrated		I = Internally mounted		S = Stowed for launch		E = Externally mounted during assembly		
Flight Element	Code	MASS	PSE	ATTACH	CG	PSE	ATTACH	CG
ISOCRID TUBE STRUCTURE								
Isogrid (left)	P	2768		see below	1014			
Isogrid segments (incl. in 3 containers)								
Longerons (trunnion) (2)	P	208			1014			
Longerons (heel) (1)	P	382			1014			
Longerons (forward)	P	80			1014			
Longerons (container) (6)	P	543			1014			
Ring (end & container)	P	294			1014			
Ring (center) (3)	P	13			946			
EVA Access Stiffener (1)	P	440			1035			
Trunnions (5)	P	200			1014			
Connecting Hardware	P	4928			1015.8			
Total Tube Structure Mass								
OTHER STRUCTURE								
Total Other Structure		0						
TOTAL STRUCTURE		4928			1015.8			
PROPULSION SYSTEM								
PCS Container #1	P, I	580			1185			
Structure								
Isogrid	P, I	n/a			n/a			
Perimeter	P, I	210			1185			
Tank Support (Total)	P, I	100			1218			
Tank support (left)	P, I	50			1154			
Trunnions	P, I	330			1109			
Lines, Sensors, Valves etc.	P, I	337			1185			
Microencapsulated Protection	P, I	835			1185			
Electrical Harnesses	P, I	525			1185			
MDMs	P, I	158			1200			
DC-DC lineA Conv. (PCA)	P, I	45			1200			
DRY Mass Container #1		3070			1100.9			
PURG. Container #1	P, I	4255			1185			
Total Mass PCS Container #1		7325			1183.3			
OTHER SYSTEMS								
PCS Container #2	P, I	3070			1104			
DRY Mass Container #2		4255			1185			
PURG. Container #2	P, I	4255			1185			
Total Mass Container #2		7325			1104.1			
PCS Thruster Assy #1	S, E	144			1328			
Thruster Assembly								
Lines etc. (incl. in container)	S, E	25			1220			
Thruster Pod Structure	S, E	65			1171			
Room	S, E	120			1144			
Lines + extra Elect Harness	S, E	120			1144			
Flight Support Structure		100						
Total Mass Thruster Pod #1		365			1172.2			
PCS Thruster Assy #2	S, E	365			1172.2			
Thruster Assy #2								
Lines etc. (incl. in container)	S, E	25			1220			
Thruster Pod Structure	S, E	65			1171			
Room	S, E	120			1144			
Lines + extra Elect Harness	S, E	120			1144			
Flight Support Structure		100						
Total Mass Thruster Pod #2		365			1172.2			
TOTAL MASS PCS ELEMENTS		15380			1145.4			
THERMAL CONTROL SYSTEM								
Structure								
Isogrid	P, I	n/a			n/a			
Perimeter	P, I	210			1185			
Tank Support (Total)	P, I	100			1218			
Tank support (left)	P, I	50			1154			
Trunnions	P, I	330			1109			
Lines, Sensors, Valves etc.	P, I	337			1185			
Microencapsulated Protection	P, I	835			1185			
Electrical Harnesses	P, I	525			1185			
MDMs	P, I	158			1200			
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TOTAL MASS PCS ELEMENTS		15380			1145.4			
THERMAL CONTROL SYSTEM								
Structure								
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Electrical Harnesses	P, I	525			1185			
MDMs	P, I	158</						

Detailed Mass Breakdown and Center of Gravity Table
(Continued)

This table provides a detailed tabulation of the preceding summary charts.

Detailed Mass Breakdown and Center of Gravity Table (Continued)

SPACE STATION INTEGRATED TRUSS ASSEMBLY CG TABLE CONT'D

Flight Element	Code	MASS	FSE	ATTACH	CG	Flight Element	Code	MASS	FSE	ATTACH	CG
COMM. AND TRACKING SYSTEM											
ANTENNA ASSEMBLY											
S-Band Ant Assy(2)	S.R.	40			886	Rack Structure	P.I	60			818
(thru 1 attachment)						Upper H00	P.I	131			851
Ku-Band Para Ant Assy(1)	S.R.	131	100		792	RFC Module 10A (14)	P.I	162			818
Flight Support Structure	S.R.	200			886	RFC Module 10A (23)	P.I	213			818
Upper Ant Support(1)	S.R.				881	SPDA(1)	P.I	45			851
(incl joints & Fu T-R bones)											
Upper UHF Omni Ant(1)	S.R.	1			860	RFS Main Rack 2		871			861.8
GPS Room 6 Attachments	S.R.	40			886						
Total Mass Antenna Assembly		472	100		860.1						
RACK 1 (CAT 0B1e)											
Rack Structure	P.I	60			849	DMS SYSTEM RACK 2					
ACS Baseband Sig Fncr (2)P.1	P.I	80			864	Data Lines and Conns.	P.I	34			818
SIG TIPS Transponder	P.I	76			864	Upper H00	P.I	131			851
SGS Antenna Controller(2)P.1	P.I	72			816	DMS Main Rack 2		172			850.0
Total Mass Rack 1		288			851.4						
RACK 3 (Antenna mounted ORU's)											
Rack Structure	P.I		60		816	TOT. MASS CAT "PALEY FUNCTIONS"		2385	160		861.1
ACS T Re w/Antennas	S.R.	98			853						
SGS Ku-Band T-Re	S.R.	134			824	TEMPORARY POWER SYSTEM (1500W)					
Ext TV Camera Assy	S.R.	81			851	RACK 4					
Upper MHD Protection	S.R.	22			824	Rack Structure	P.I	60			849
Total Mass Rack 3		341	60		839.2	Power System	P.I	1000			849
						Incl elect, batt, PV blanket	P.I				
						Rack and Fittings	P.I	60			849
						TOTAL MASS TEMP. POW. SYST.		1120			849.0
GULC SYSTEM											
Mounted on Jangleid						UTILITIES					
Star Tracker (3)	P.I	65			1003	TOTAL MASS FOR 44'	P.I	1200			1014
Upper Nav Base	P.I	15			1003						
Inertial Sensor Assy (3)	P.I	130			1003	FLIGHT TOTAL		28328	160		1005.6
Structure	P.I	31			1003						
Total Mass Nav. Base, Assy		241			1003.0						

LaRC SSFO

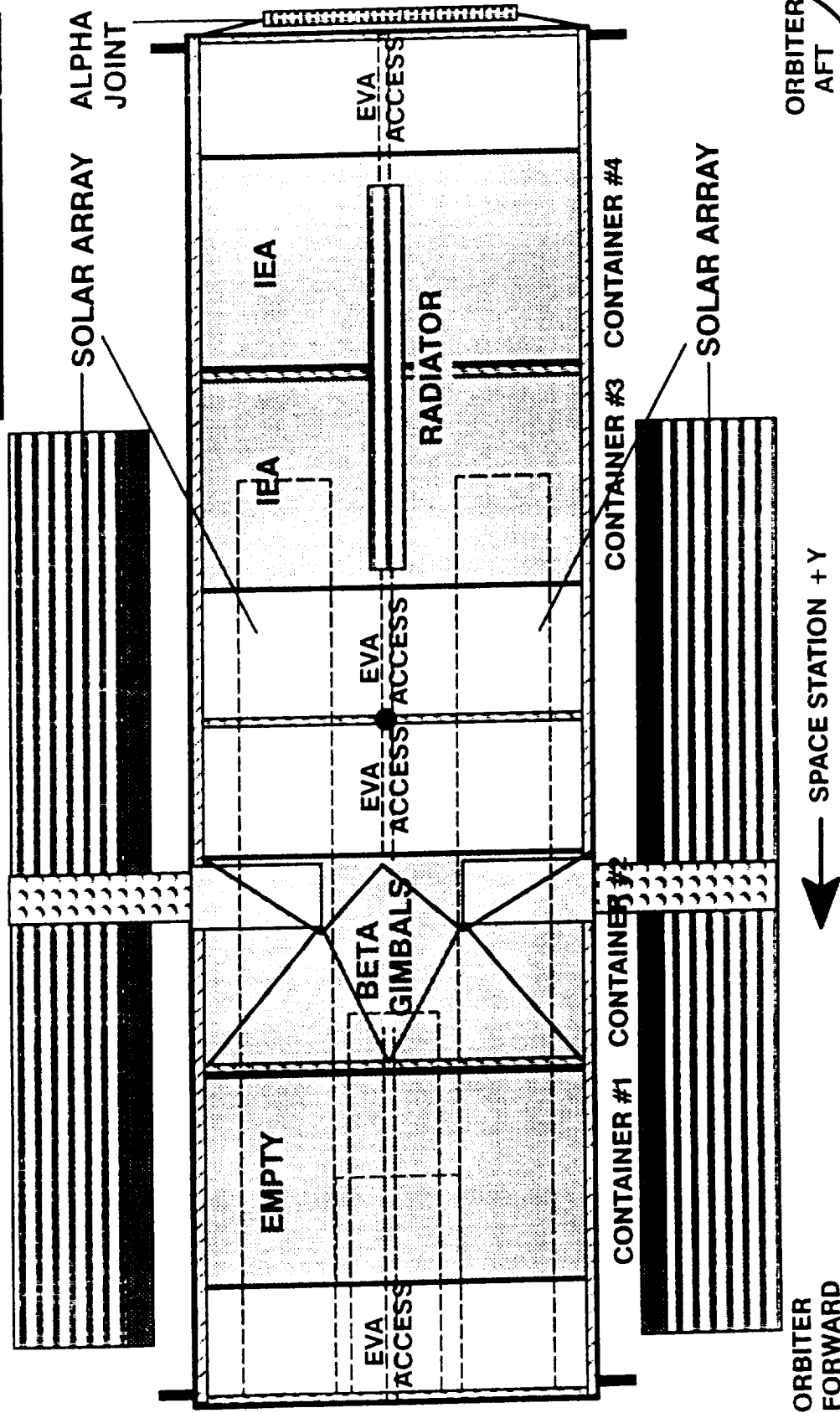
TR2 Packaging

The second assembly flight brings up the power system elements that are located just outside the starboard alpha joint. All elements required to produce 18.75 KW of power are included on this flight. The Integrated Equipment Assembly (IEA) is packaged in two container sections at one end of the integrated structure. The PV array beta gimbals are located in container section two. Packaged internally are two PV arrays and the deployable radiator. An alpha joint is located at the IEA end of the integrated structure.

Pre-Integrated Structure Packaging

TR-2

Mass to station = 27,572
Managers reserve = 4136
Additional Margin = 4270

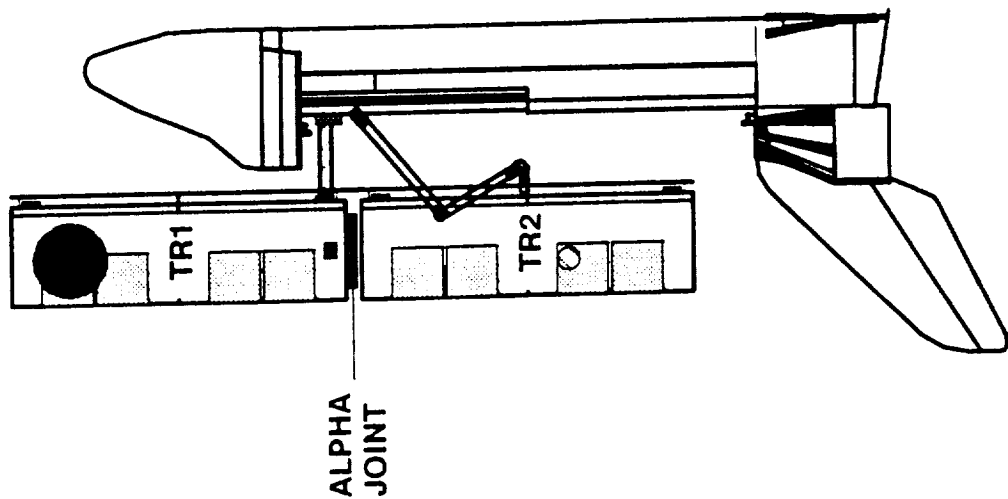


LaRC SSFO

TR2 Operations

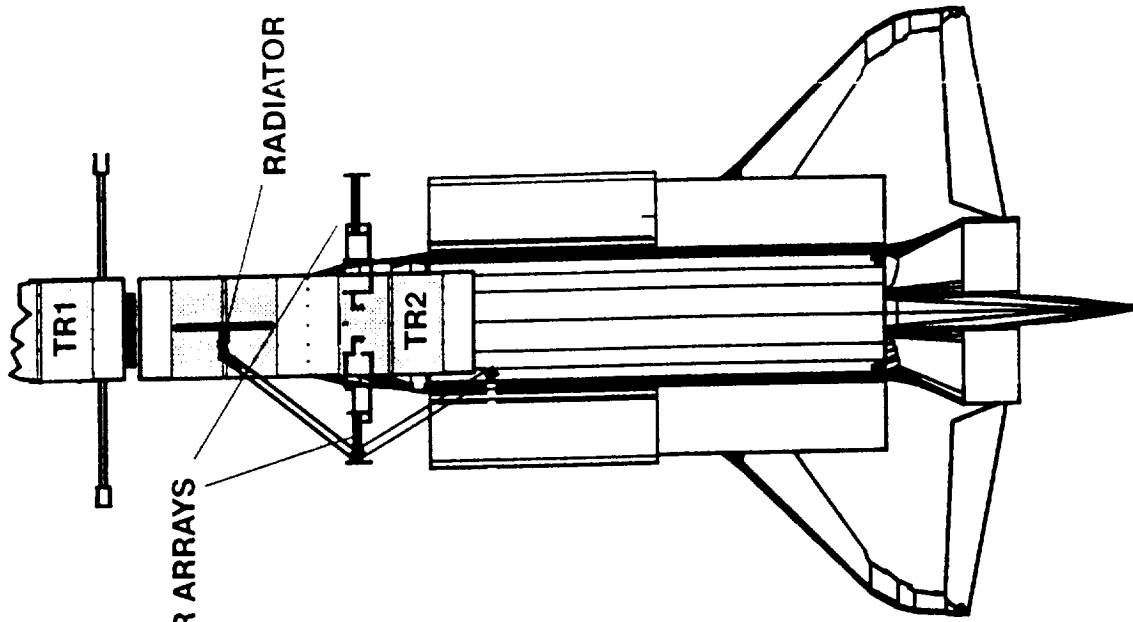
The operations involved in deploying and assembling the second integrated structural element of the space station result in an addition of 10 KW of power while the arrays operate in a feathered mode. The orbiter must first attach to the TR1 station element. The TR2 integrated structure is then removed from the orbiter cargo bay with the RMS and attached to TR1. The orbiter then detaches from TR1 and attaches to TR2. From this position the RMS removes and attaches internally stored appendages with EVA assistance. After all assembly and check out is complete, the orbiter detaches from the structure but remains in close proximity until all systems are verified operational. A malfunction would require the orbiter to berth to the structure and facilitate repairs.

Truss Flight Two Operations



STEPS 1 TO 4

- 1) Berth to TR1.
- 2) Remove TR2 from cargo bay and rotate.
- 3) Release alpha joint mechanism.
- 4) Berth TR2 to TR1. EVA secure TR1 to alpha joint.
- 5) Release from TR1 then berth to end of TR2
- 6) Remove radiator and solar arrays from structure and place in cargo bay.
- 7) Attach radiator to IEA manifold and deploy.
- 8) Attach solar arrays to beta joints.
- 9) Check out systems, separate and deploy solar arrays.

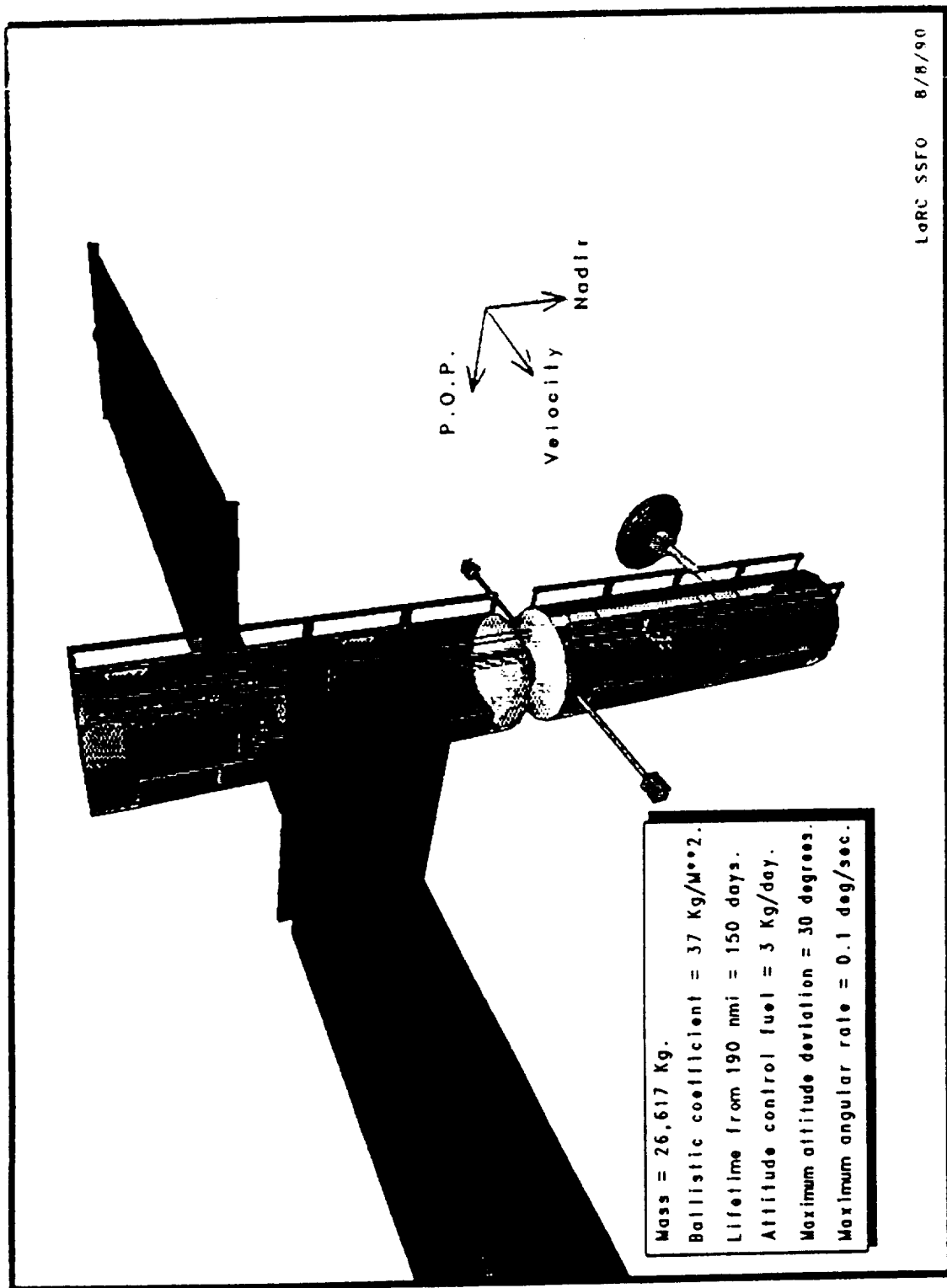


STEPS 5 TO 9

Second Assembly Flight Configuration

A flight characteristics analysis was performed on the second assembly flight configuration. The flight mode is gravity gradient stable with the deployed solar arrays, antennas and thruster arms aligned along the velocity vector and the longitudinal axis of the structure aligned along nadir. Stability simulations showed this configuration to yaw 360 degrees once every 5 orbits with no RCS attitude control. Using RCS thrusters to hold the configuration to within a maximum deviation of 30 degrees required 3 kilograms of fuel per day at 190 nmi assuming a design atmosphere of $A_p = 400$ and a flux of 230. The average ballistic coefficient was 37 kg/m^2 which would give the station an orbit lifetime of 150 days from 190 nmi if the reboost thrusters were to fail. There is sufficient reboost fuel on board to maintain altitude for many years should the orbiter be grounded for some reason.

Second Assembly Flight Configuration



TR2 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the second assembly flight are listed. The overall C.G. location for the combined payload is 10.6 inches within allowable limits. There is 4270 pounds of unused STS lift capability and 4135 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 2

TR-2

STS

ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
IEA	12144			CON#3&4	1146
SOLAR ARRAYS	3636	363		TUBE	882
BETA GIMBALS	882			CON#2	954
RADIATOR (DEPLOYABLE)	1104	136		TUBE	840
ALPHA JOINT	946			TUBE END	1278
STRUCTURE	8260		1100		1014
UTILITIES	600				1014
	27572	499		1100	
HARDWARE	27572				
15% RESERVE	4136				
FSE	499				
ATTACH FITTINGS	1100				
EVA RESERVE	2873				
DOCKING FIXTURE	1550				
SUBTOTAL	37730			CG LOCATION	1014.1
MARGIN	4270			CG MARGIN	10.6
STS CAPABILITY TO 190 NMI	42000			ALLOWABLE CG LIMIT	1003.6

LaRC SSFO

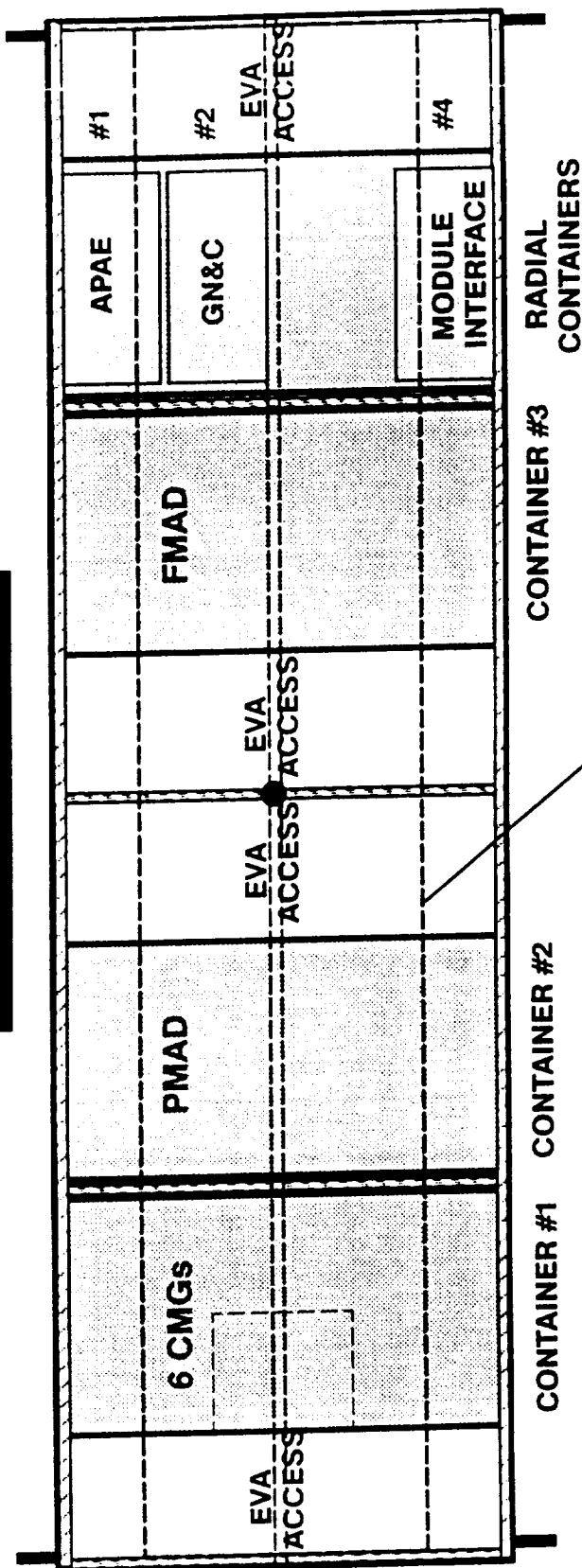
TR3 Packaging

The third truss section flight brings up the CMGs, PMAD, FMAD, one APAE and a pressurized module interface. The CMGs are in container #1, the PMAD equipment is in container #2, the FMAD equipment is in container #3 and the radial containers house the attached payload and pressurized module interfaces along with some GN&C electronics. Packaged internally are the starboard TCS radiator panels and condenser that will be attached to the beta joint on TR1.

Pre-Integrated Structure Packaging

TR-3

Mass to station = 29,338
Managers reserve = 4401
Additional Margin = 2011



STBD TCS RADIATOR & CONDENSER
PACKAGED INSIDE STRUCTURE

ORBITER
AFT

← SPACE STATION + Y

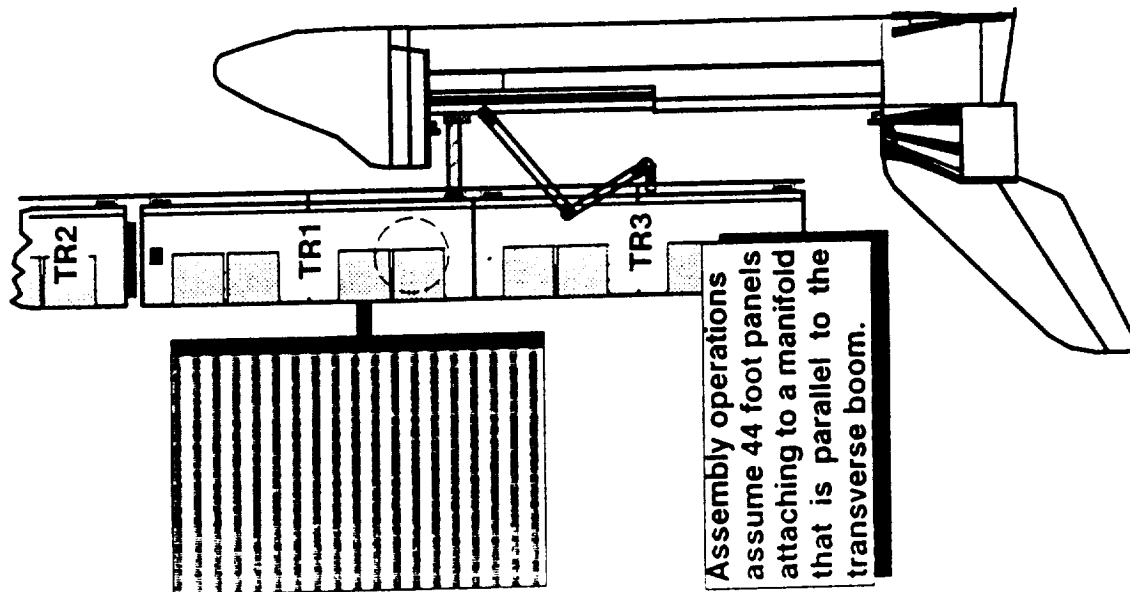
ORBITER
FORWARD

LaRC SSFO

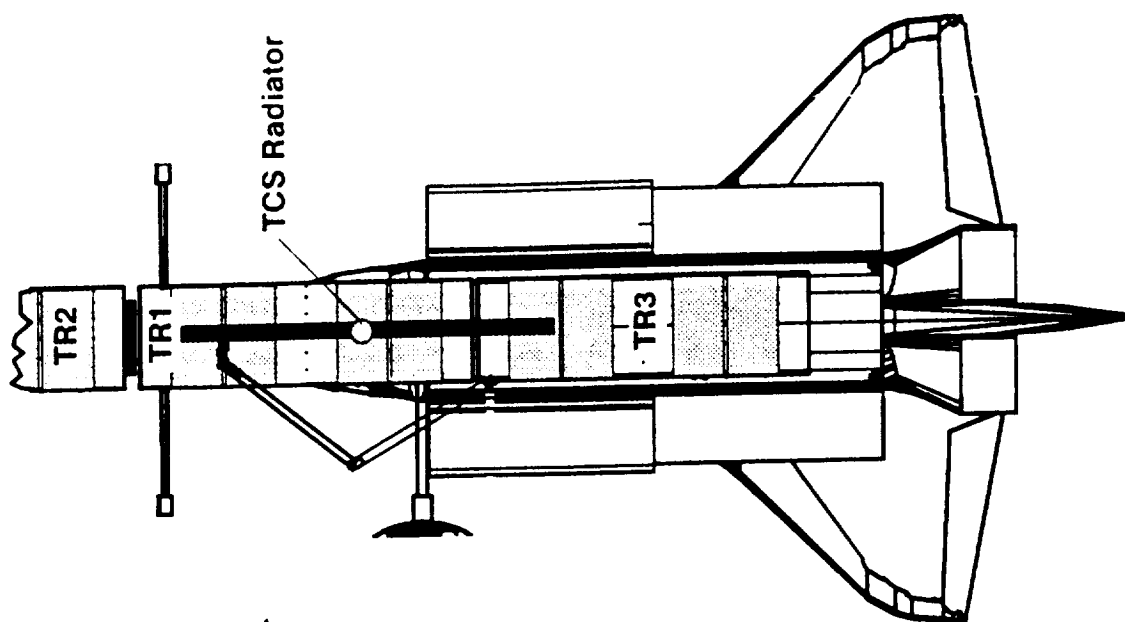
TR3 Operations

The operations involved in deploying and assembling the third integrated structural element of the space station are listed. The orbiter must first attach to the TR1 station element. The TR3 integrated structure is then removed from the orbiter cargo bay with the RMS and EVA secured to TR1. The orbiter then detaches from TR1 and attaches to TR3. From this position the radiator panels are removed and placed in the cargo bay. The orbiter then re-attaches to TR1 and the RMS assembles/attaches the radiator to the beta joint on TR1 with EVA assistance. After all assembly and check out is complete, the orbiter detaches from the structure but remains in close proximity until all systems are verified to be complete. A malfunction would require the orbiter to berth to the structure and facilitate repairs.

Truss Flight Three Operations



- 1) Berth to TR1.
- 2) Remove TR3 from cargo bay and rotate.
- 3) Berth TR3 to TR1. EVA secure TR1 to TR3
- 4) Release from TR1 then berth to end of TR3.
- 5) Remove TCS radiator and condenser from TR3 and place in cargo bay.
- 6) Re-berth to end of TR1.
- 7) Use RMS to install starboard TCS radiator rotating beta joint 180 degrees half way through construction.
- 8) Check out systems and separate.



STEPS 4 & 5 NOT SHOWN

TR3 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the third truss section flight are listed. The overall C.G. location for the combined payload is 0.5 inches within allowable limits. There is 2011 pounds of unused STS lift capability and 4401 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 3

TR-3

STS

ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
UPPER APAE	600	100		RC#1	840
MODULE INTERFACE	600	100		RC#4	840
STBD TCS PANELS & CONDENSER	4271	427		TUBE	1014
CMG'S (6)	5130			CON#1	1188
GN&C	777	100		RC#2	840
PMAD	5069			CON#2	1104
FMAD(WET)	2831			CON#3	924
STRUCTURE	8260		1100		1014
UTILITIES	1200				1014
BALLAST	600				1280
	29338	727	1100		
HARDWARE	29338				
15% RESERVE	4401				
FSE	727				
ATTACH FITTINGS	1100				
EVA RESERVE	2873				
DOCKING FIXTURE	1550				
SUBTOTAL	39989			CG LOCATION	1008.4
MARGIN	2011			CG MARGIN	0.5
STS CAPABILITY TO 190 NMI	42000			ALLOWABLE CG LIMIT	1007.9

LaRC SSFO

Title

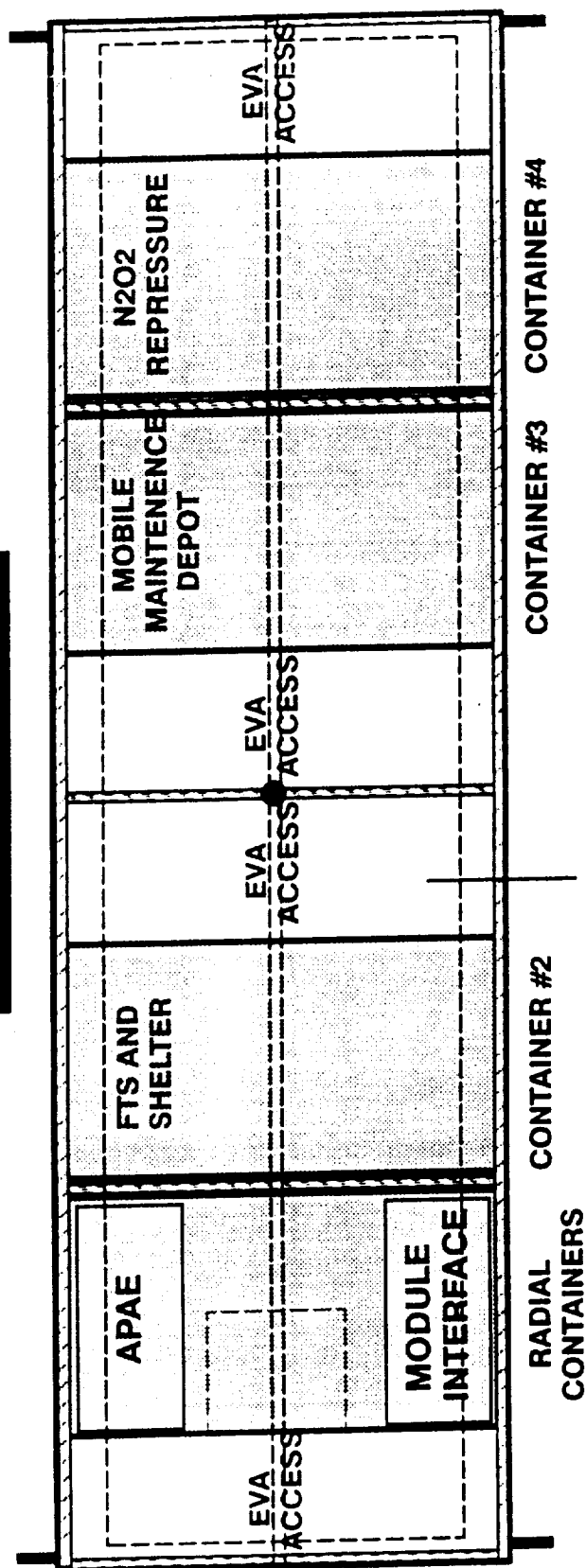
TR4 Packaging

The fourth truss section flight brings up the N₂ O₂ repressurization tanks, Mobile Maintenance Depot (MMD), FTS and shelter, an APAE and a pressurized module interface. The FTS and shelter are in container #2, the MMD is in container #3, the repressurization tanks are in container #4 and the radial containers house the attached payload and pressurized module interfaces. Packaged internally are the port TCS radiator panels and condenser that will be attached to the beta joint on the following flight.

Pre-Integrated Structure Packaging

TR-4

Mass to station = 30,206
 Managers reserve = 4531
 Additional Margin = 999



PORT TCS RADIATOR & CONDENSER,
 MODULE SUPPORT TRUSS PACKAGED
 INSIDE STRUCTURE.

ORBITER
 FORWARD

← SPACE STATION + Y

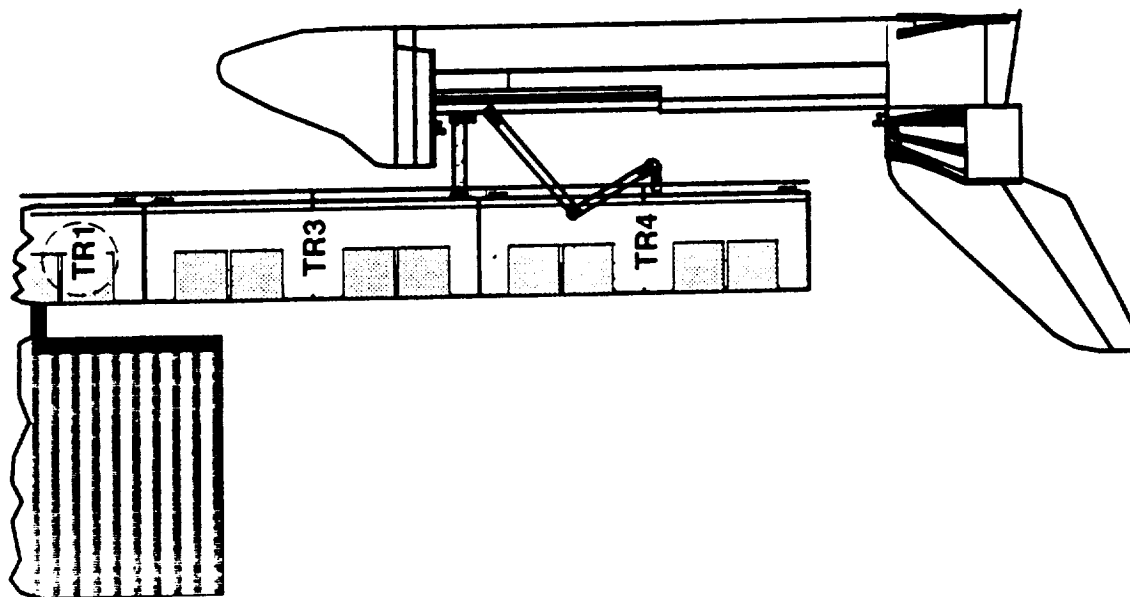
ORBITER
 AFT

LaRC SSFO

TR4 Operations

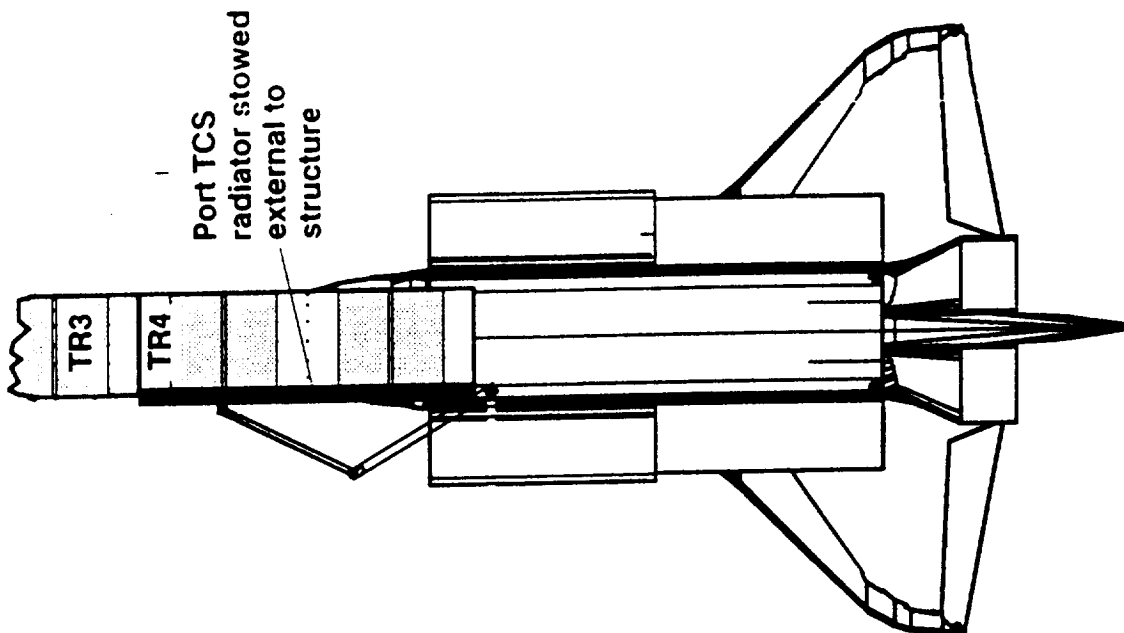
The operations involved in deploying and assembling the fourth integrated structural element of the space station are listed. The orbiter must first attach to the TR3 station element. The TR4 integrated structure is then removed from the orbiter cargo bay with the RMS and EVA secured to TR3. The orbiter then detaches from TR3 and attaches to TR4. From this position the RMS removes the radiator panels and stows them on TR4. After all assembly and check out is complete, the orbiter detaches from the structure but remains in close proximity until all systems are verified to be operational. A malfunction would require the orbiter to berth to the structure and facilitate repairs.

Truss Flight Four Operations



STEPS 1 TO 3

- 1) Berth to TR3.
- 2) Remove TR4 from cargo bay and rotate.
- 3) Berth TR4 to TR3. EVA secure TR4 to TR3.
- 4) Release from TR3 then berth to end of TR4.
- 5) Remove TCS radiator and condenser from TR4 and store on exterior of TR4.
- 6) Check out systems and separate.



STEPS 4 TO 6

TRUSS4ops

TR4 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the fourth truss section flight are listed. The overall C.G. location for the combined payload is 14 inches within allowable limits. There is 999 pounds of unused STS lift capability and 4531 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 4

TR-4

STS

ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
MODULE SUPPORT TRUSS	531	114		TUBE	1014
N2O2 REPRESSURIZATION TANKS	8400			CON#4	1188
PORT TCS PANELS & CONDENSER	4271	427		TUBE	1014
FTS/SHELTER	2232			CON#2	924
MMD WITH SPD	4112			CON#3	1104
MODULE INTERFACE	600	100		RC#4	840
UPPER APAE	600	100		RC#1	840
STRUCTURE	8260		1100		1014
UTILITIES	1200				1014
	30206	741	1100		

HARDWARE

15% RESERVE

FSE

ATTACH FITTINGS

EVA RESERVE

PRESS. DOCKING MECH.

	41001	CG LOCATION	1023.7
	999	CG MARGIN	14.0

SUBTOTAL
MARGIN

STS CAPABILITY TO 190 NMI

42000	ALLOWABLE CG LIMIT	1009.6
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LaRC SSFO

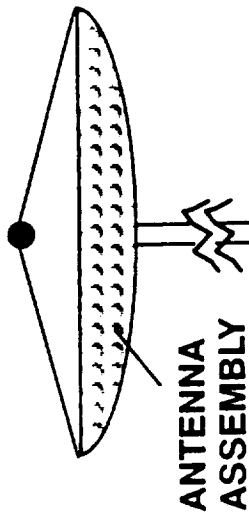
1111

TR5 Packaging

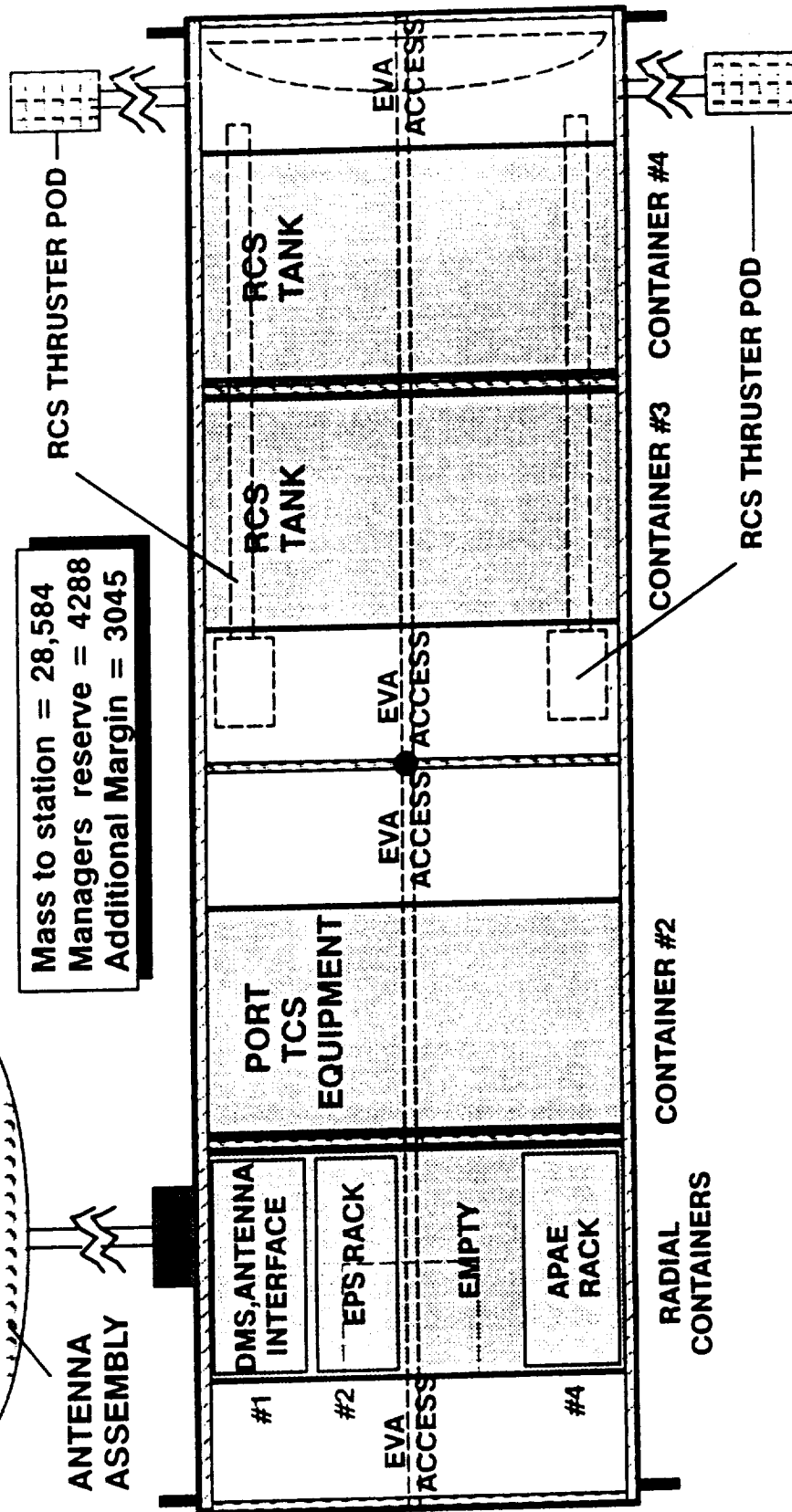
The fifth truss structure flight is essentially a mirror image of TR1 without the independent power system. Hydrazine fuel tanks loaded with a total of 9000 pounds of fuel are located at one end of the integrated structure in removable container sections. The port TCS equipment (including the port radiator beta joint) is located in container section two. Radial containers at the other end of the structure contain systems for communications and power conditioning. Packaged internally are two thruster pods with extension arms and the antenna assembly. This is identical to TR2.

Pre-Integrated Structure Packaging

TR-5



Mass to station = 28,584
Managers reserve = 4288
Additional Margin = 3045



ORBITER FORWARD

SPACE STATION + Y

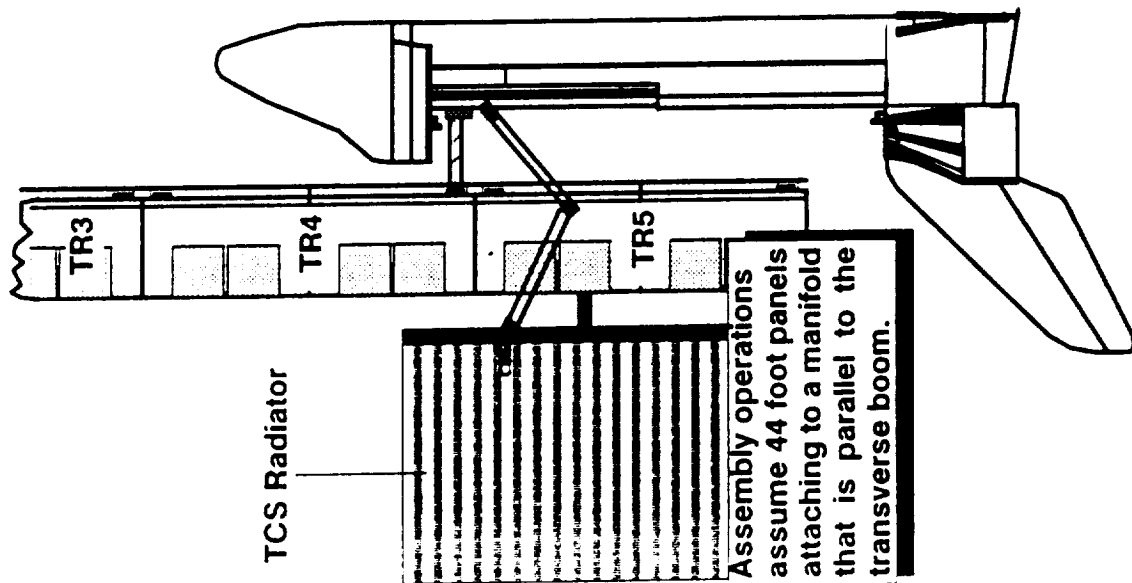
ORBITER AFT

LaRC SSFO

TR5 Operations

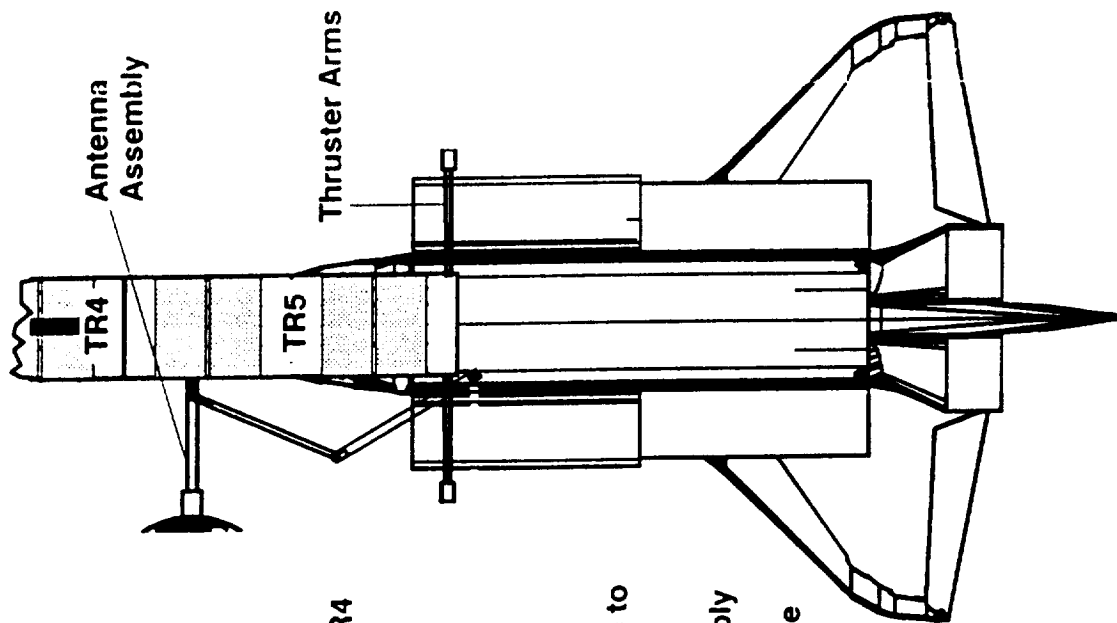
The operations involved in deploying and assembling the fifth integrated structural element of the space station are listed. The orbiter must first attach to the TR4 station element. The TR5 integrated structure is then removed from the orbiter cargo bay with the RMS and EVA secured to TR4. From this position the RMS removes the radiator panels stowed on TR4 and assembles them on TR5. The orbiter then attaches to the end of TR5, where the RMS removes and attaches the antenna assembly and thruster arms. After all assembly and check out is complete, the orbiter detaches from the structure but remains in close proximity until all systems are verified to be operational. A malfunction would require the orbiter to berth to the structure and facilitate repairs.

Truss Flight Five Operations



STEPS 1 TO 5

- 1) Berth to TR4.
- 2) Remove TR5 from cargo bay and rotate.
- 3) Berth TR5 to TR4. EVA secure TR5 to TR4
- 4) Remove stowed port TCS radiator and condenser from TR4 exterior and place in cargo bay.
- 5) Use RMS to install port TCS radiator rotating beta joint 180 degrees half way through construction.
- 6) Release from TR4 then berth to end of TR5.
- 7) Remove the antenna assembly from TR5 using RMS then EVA erect the antennas in the shuttle cargo bay. Attach assembly to TR5 with RMS.
- 8) Remove and install thruster arms to end of TR5.
- 9) Check out systems and separate.



STEPS 6 TO 9

TR5 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the fifth truss section flight are listed. The overall C.G. location for the combined payload is 26.2 inches within allowable limits. There is 3045 pounds of unused STS lift capability and 4288 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 5

TR-5

STS

ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
PORT TCS EQUIPMENT(WET)	1706			CON#2	924
RCS PODS (2) WITH ARMS	2000	200		TUBE	1146
RCS TANK (WITH 5000# OF FUEL)	6500			CON#3	1104
RCS TANK (WITH 5000# OF FUEL)	6500			CON#4	1188
ANTENNA ASSEMBLY	608	60		TUBE	1254
DMS ANTENNA INTERFACE	399	100		RC#1	840
EPS SYSTEMS	811	100		RC#2	840
LOWER APAE	600	100		RC#4	840
STRUCTURE	8260		1100		1014
UTILITIES	1200				1014
	28584	560	1100		
HARDWARE	28584				
15% RESERVE	4288				
FSE	560				
ATTACH FITTINGS	1100				
STRUCTURAL DOCKING MAST	1550				
EVA RESERVE	2873				
SUBTOTAL	38955			CG LOCATION	1032.1
MARGIN	3045			CG MARGIN	26.2
STS CAPABILITY TO 190 NMI	42000			ALLOWABLE CG LIMIT	1006.0

LaRC SSFO

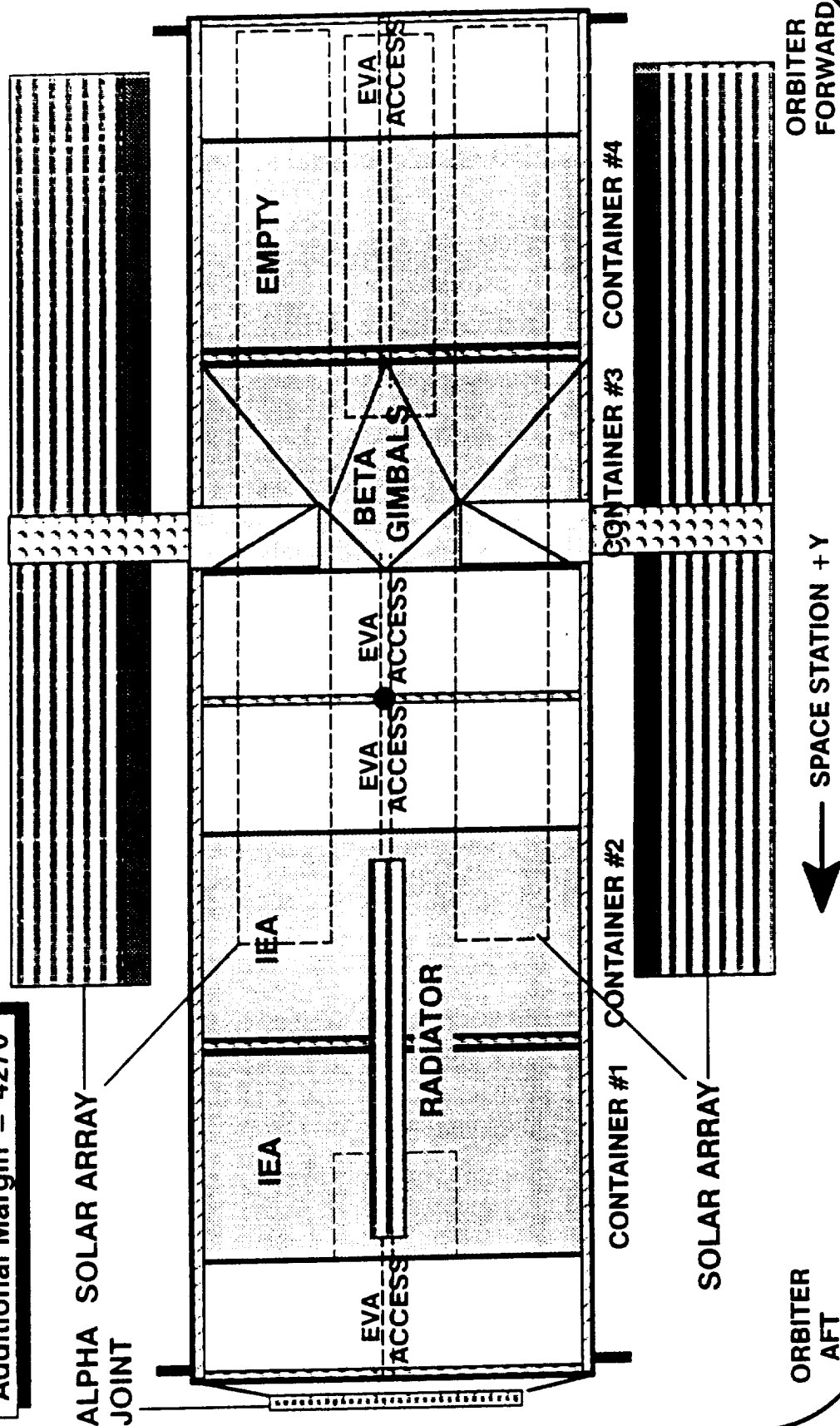
TR6 Packaging

The sixth truss structure flight brings up the power system elements that are located just outside the port alpha joint. All elements required to produce 18.75 KW of power are included on this flight. The Integrated Equipment Assembly (IEA) is packaged in two container sections at one end of the integrated structure. The PV array beta gimbals are located in container section three. Packaged internally are two PV arrays and the deployable radiator. An alpha joint is located at the IEA end of the integrated structure.

Pre-Integrated Structure Packaging

TR-6

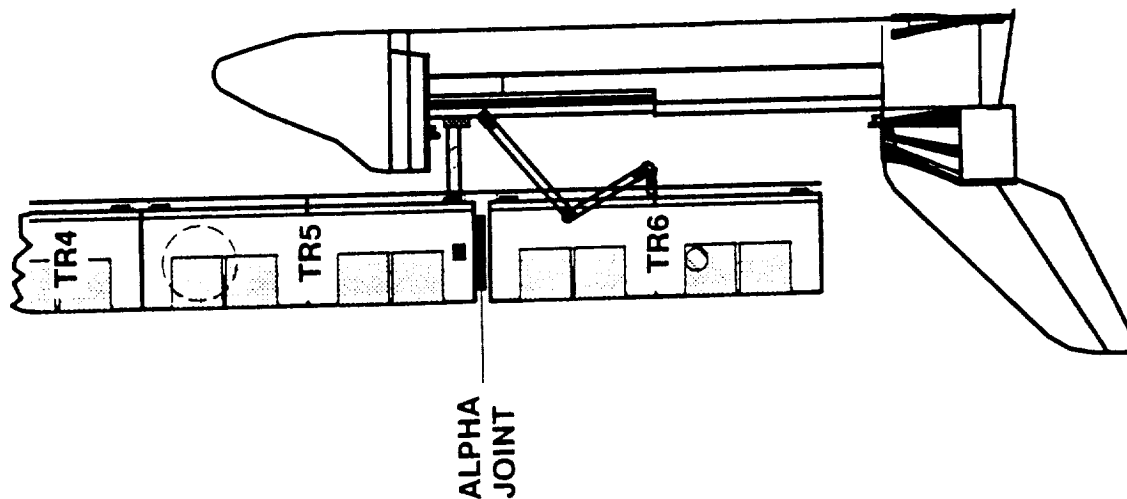
Mass to station = 27,572
Managers reserve = 4136
Additional Margin = 4270



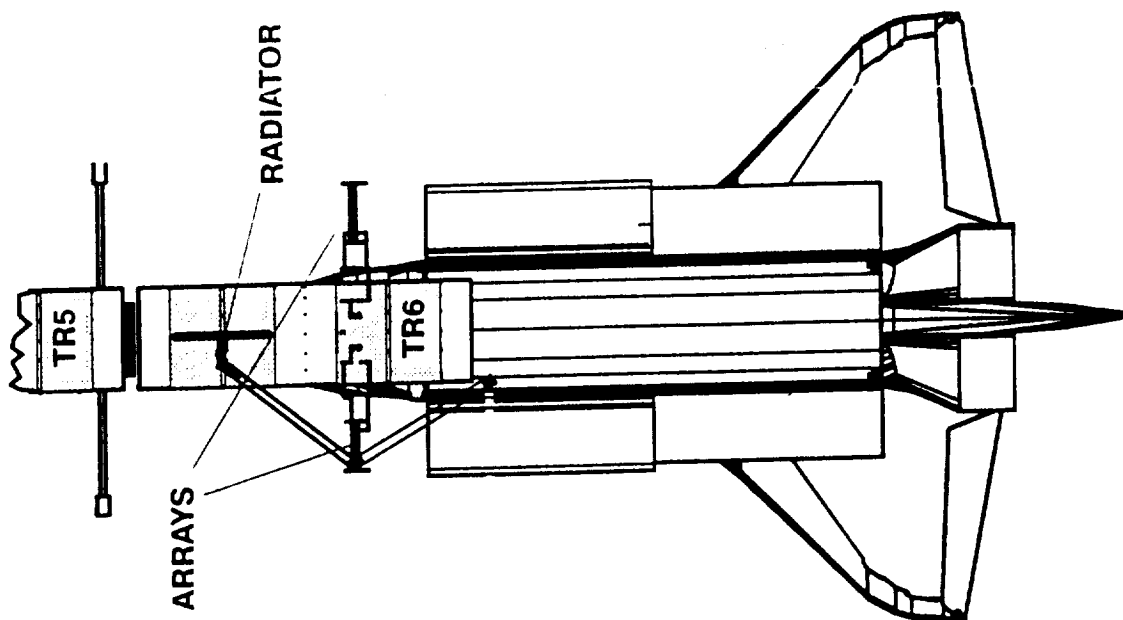
TR6 Operations

The operations involved in deploying and assembling the sixth integrated structural element of the space station result in a total power capability of 37.5 KW while flying in a LVLH sun tracking mode. The orbiter must first attach to the TR5 station element. The TR6 integrated structure is then removed from the orbiter cargo bay with the RMS and EVA secured to TR5. The orbiter then detaches from TR5 and attaches to TR6. From this position the RMS removes and attaches internally stored appendages with EVA assistance. After all assembly and check out is complete, the orbiter detaches from the structure but remains in close proximity until all systems are verified operational. A malfunction would require the orbiter to berth to the structure and facilitate repairs.

Truss Flight Six Operations



STEPS 1 TO 4



STEPS 5 TO 9

- 1) Berth to TR5.
- 2) Remove TR6 from cargo bay and rotate.
- 3) Release alpha joint mechanism.
- 4) Berth TR6 to TR5. EVA secure TR5 to alpha joint.
- 5) Release from TR5 then berth to end of TR6
- 6) Remove radiator and solar arrays from structure and place in cargo bay.
- 7) Attach radiator to IEA manifold and deploy.
- 8) Attach solar arrays to beta joints.
- 9) Check out systems, separate and deploy solar arrays.

TR6 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the sixth truss section flight are listed. The overall C.G. location for the combined payload is 10.6 inches within allowable limits. There is 4270 pounds of unused STS lift capability and 4136 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 6

TR-6

STS

ELEMENT

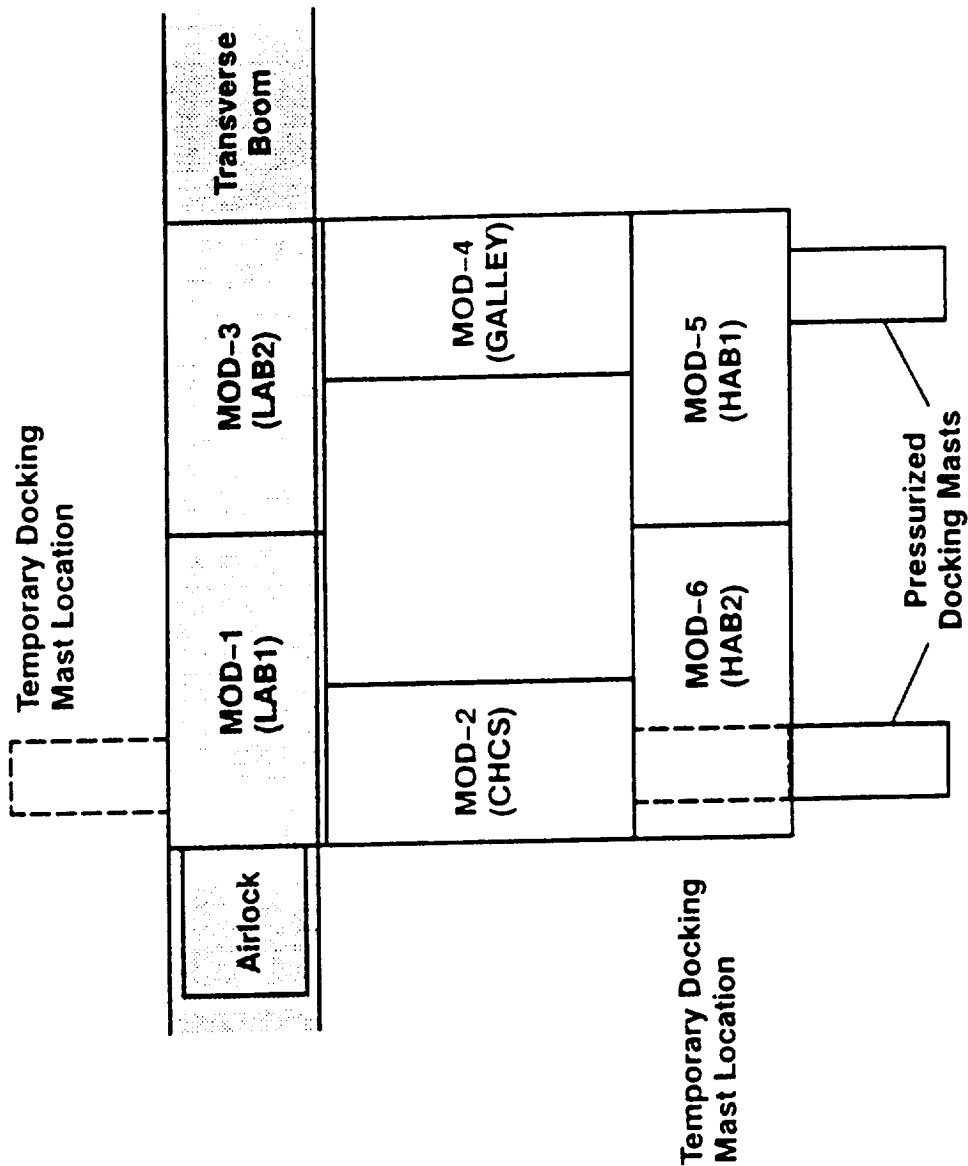
	MASS	FSE	ATTACH	LOCATION	CG
IEA	12144			CON#1&2	1146
SOLAR ARRAYS	3636	363		TUBE	882
BETA GIMBALS	882			CON#3	954
RADIATOR (DEPLOYABLE)	1104	136		TUBE	840
ALPHA JOINT	946			TUBE END	1278
STRUCTURE	8260		1100		1014
UTILITIES	600				1014
	27572	499	1100		
HARDWARE	27572				
15% RESERVE	4136				
FSE	499				
ATTACH FITTINGS	1100				
EVA RESERVE	2873				
DOCKING FIXTURE	1550				
SUBTOTAL	37730			CG LOCATION	1014.1
MARGIN	4270			CG MARGIN	10.6
STS CAPABILITY TO 190 NMI	42000			ALLOWABLE CG LIMIT	1003.6

Module Pattern Assembly

Once the transverse boom has been completed from starboard to port alpha joints, the module pattern is constructed. The first module brought up is a laboratory module located towards starboard directly under the transverse boom.. A pressurized docking module is manifested along with the lab and is temporarily placed on the aft side of the lab module in the -X direction. The following assembly flight brings up the airlock, mobile transporter, MSC, and a cupola which is stored on the transverse boom. The next flight brings up the CHCS module followed by a flight that brings up the second lab module and another pressurized docking adapter. The galley and both habitation modules are then brought up along with the second cupola on subsequent flights. The pressurized docking modules and cupolas are then placed in their final positions.



Module Pattern Assembly



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cell: graphic

MOD1 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the first module flight are listed. The overall C.G. location for the combined payload is 40.5 inches within allowable limits. There is 134 pounds of unused STS lift capability and 1677 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 7
MOD-1
STS
ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
U.S. MODULE 1 (LAB 17 RACKS)	30916	250	1100		1110
PRESSURIZED DOCKING MODULE	2343		880		878
FLUIDS	277				1110
	33536	250	1980		
HARDWARE	33536				
5% RESERVE	1677				
FSE	250				
ATTACH FITTINGS	1980				
EVA RESERVE	2873				
DOCKING FIXTURE	1550				
SUBTOTAL	41866		CG LOCATION		1056.6
MARGIN	134		CG MARGIN		40.5
STS CAPABILITY TO 190 NMI	42000		ALLOWABLE CG LIMIT		1016.2

Module/Truss (MT) Manifest

The assembly elements, weights, associated FSE and C.G. locations for a combination module pattern (airlock, cupola) / truss structure (mobile transporter, MSC) flight are listed. The overall C.G. location for the combined payload is 0.2 inches within allowable limits. There is 768 pounds of unused STS lift capability and 1547 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 8
MT-1
STS
ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
AIRLOCK	12339	250	1100		1178
MSC PHASE 1	7176		660		1000
MOBILE TRANSPORTER	5399		880		880
CUPOLA	3317	700	660		776
BALLAST	2700				1280
	30932	950	3300		

HARDWARE
5% RESERVE
FSE
ATTACH FITTINGS
MSC WORKSTATION
EVA RESERVE
DOCKING FIXTURE

30932					
1547					
950					570
3300					
80					
2873					642.7
1550					

SUBTOTAL
MARGIN

41232	CG LOCATION	1015.5
768	CG MARGIN	0.2

STS CAPABILITY TO 190 NMI

42000	ALLOWABLE CG LIMIT	1015.3
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MOD 2 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the second module flight are listed. The overall C.G. location for the combined payload is 41.6 inches within allowable limits. There are 54 pounds of unused STS lift capability and 1677 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 9
MOD-2
STS
ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
U.S. MODULE 2 (HAB 17 RACKS)	30916	250	1100		1110
PRESSURIZED DOCKING MODULE	2343		880		878
FLUIDS	277				1110
	33536	250	1980		
HARDWARE	33536				
5% RESERVE	1677				
FSE	250				
ATTACH FITTINGS	1980				
MSC WORKSTATION	80				
EVA RESERVE	2873				
DOCKING FIXTURE	1550				
SUBTOTAL	41946		CG LOCATION		1057.8
MARGIN	54		CG MARGIN		41.6
STS CAPABILITY TO 190 NMI	42000		ALLOWABLE CG LIMIT		1016.3

MOD 3 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the third module flight are listed. The overall C.G. location for the combined payload is 63.1 inches within allowable limits. There are 2773 pounds of unused STS lift capability and 1589 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 10
MOD-3
STS
ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
U.S. MODULE 3 (GALLEY 18 RACKS)	31508	250	1100		1110
FLUIDS	277				1110
	31785	250	1100		
HARDWARE					
5% RESERVE	31785				
FSE	1589				
ATTACH FITTINGS	250				
MSC WORKSTATION	1100				
EVA RESERVE	80				
DOCKING FIXTURE	2873				
	1550				
SUBTOTAL	39227		CG LOCATION		1074.9
MARGIN	2773		CG MARGIN		63.1
STS CAPABILITY TO 190 NMI	42000		ALLOWABLE CG LIMIT		1011.8

MOD 4 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the fourth module flight are listed. The overall C.G. location for the combined payload is 60.8 inches within allowable limits. There are 2773 pounds of unused STS lift capability and 1589 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 11
MOD-4
STS
ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
US MODULE 4 (CHCS 18 RACKS)	31508	250	1100		1110
FLUIDS	277				1110
	31785	250	1100		
HARDWARE	31785				
5% RESERVE	1589				
FSE	250				
ATTACH FITTINGS	1100				
MSC WORKSTATION	80				
EVA RESERVE	2873				
DOCKING FIXTURE	1550				
SUBTOTAL	39227		CG LOCATION		1074.9
MARGIN	2773		CG MARGIN		60.8
STS CAPABILITY TO 190 NMI	42000		ALLOWABLE CG LIMIT		1014.2

MOD 5 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the fifth module flight are listed. The overall C.G. location for the combined payload is 63.1 inches within allowable limits. There is 2773 pounds of unused STS lift capability and 1589 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 12

MOD-5

STS

ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
U.S. MODULE 5 (HAB 18 RACKS)	31508	250	1100		1110
FLUIDS	277				1110

	31785	250	1100
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HARDWARE

5% RESERVE

FSE

ATTACH FITTINGS

MSC WORKSTATION

EVA RESERVE

DOCKING FIXTURE

31785

1589

250

1100

80

2873

1550

SUBTOTAL

MARGIN

39227	CG LOCATION	1074.9
2773	CG MARGIN	63.1

STS CAPABILITY TO 190 NMI

42000	ALLOWABLE CG LIMIT	1011.8
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title

MOD 6 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the sixth module flight are listed. The overall C.G. location for the combined payload is 32.7 inches within allowable limits. There are 106 pounds of unused STS lift capability and 1652 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 13

MOD-6

STS

ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
U.S. MODULE 6 (LAB 15 RACKS)	29436	250	1100		1110
CUPOLA	3317	700	660		878
FLUIDS	277				1110
	33030	950	1760		
HARDWARE	33030				
5% RESERVE	1652				
FSE	950				
ATTACH FITTINGS	1760				
MSC WORKSTATION	80				
EVA RESERVE	2873				
DOCKING FIXTURE	1550				
SUBTOTAL	41895		CG LOCATION		1049.0
MARGIN	106		CG MARGIN		32.7
STS CAPABILITY TO 190 NMI	42000		ALLOWABLE CG LIMIT		1016.2

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Logistics Manifest

The assembly elements, weights, associated FSE and C.G. locations for a sample logistics flight are listed. The logistics brought up at this time will be driven by actual outfitting requirements in the hab and lab modules. There is sufficient room in the module flights for the required PMC logistics if full user utilization of the modules at PMC is not assumed. This may eliminate the need for a dedicated logistics flight at this point in the assembly sequence.

Integrated Assembly Sequence Manifest

L-1 STS ELEMENT	MASS	FSE	ATTACH	LOCATION	CG
PRESSURIZED LOGISTICS MODULE	20616		1100		1125.5
UNPRESSURIZED LOG. CARRIER	13284		1100		906.9
	33900	0	2200		
HARDWARE	33900				
MANAGER'S RESERVE	1477				
FSE	0				
ATTACH FITTINGS	2200				
EVA RESERVE	2873				
DOCKING FIXTURE	1550				
SUBTOTAL	42000		CG LOCATION		1009.6
MARGIN	0		CG MARGIN		-7.1
STS CAPABILITY TO 190 NMI	42000		ALLOWABLE CG LIMIT		1016.7

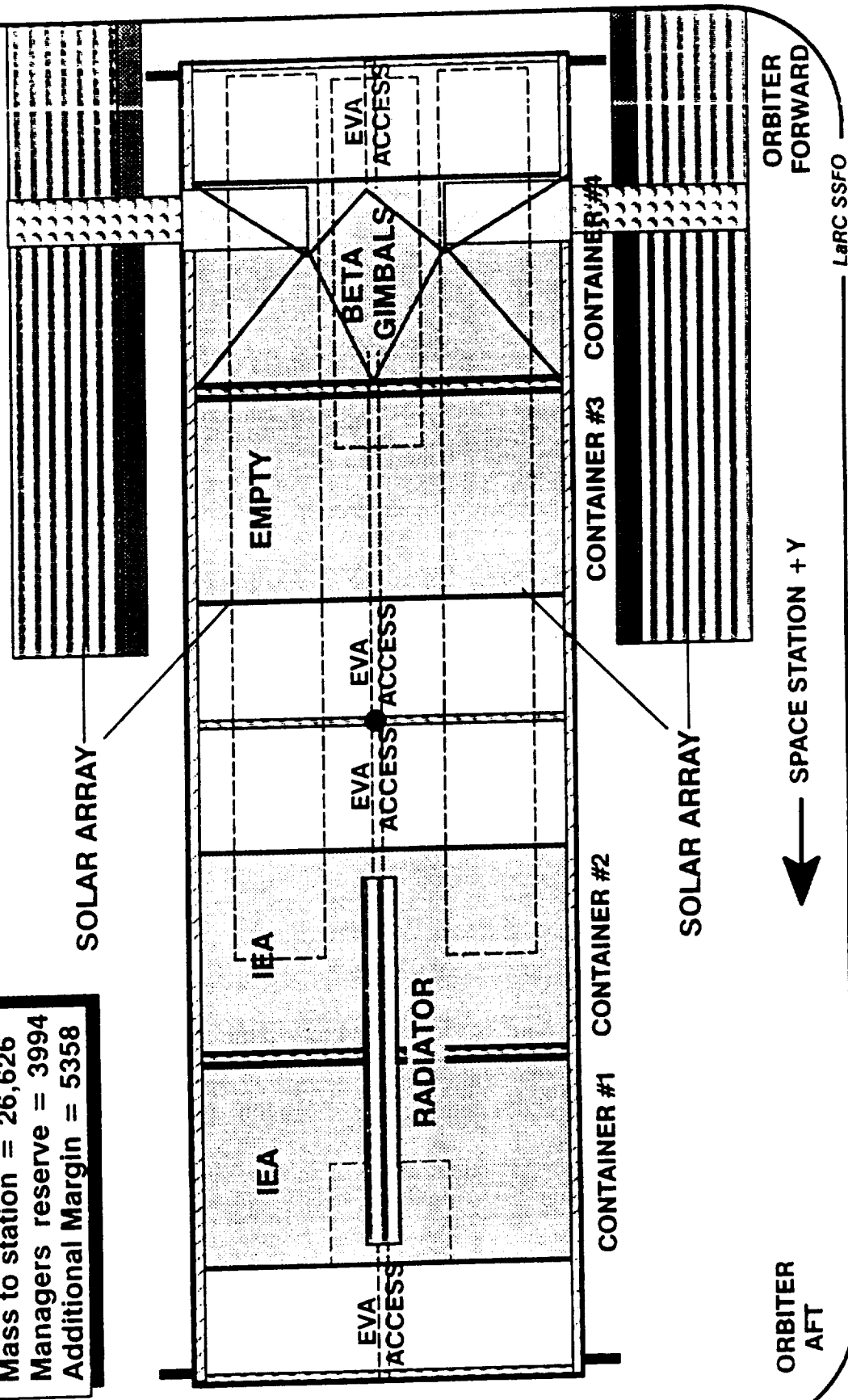
TR7 Packaging

The seventh truss structure flight brings up the outer port power system elements. All elements required to produce 18.75 KW of power are included on this flight. The Integrated Equipment Assembly (IEA) is packaged in two container sections at one end of the integrated structure. The PV array beta gimbals are located in container section four. Packaged internally are two PV arrays and the deployable radiator. .

Pre-Integrated Structure Packaging

TR-7

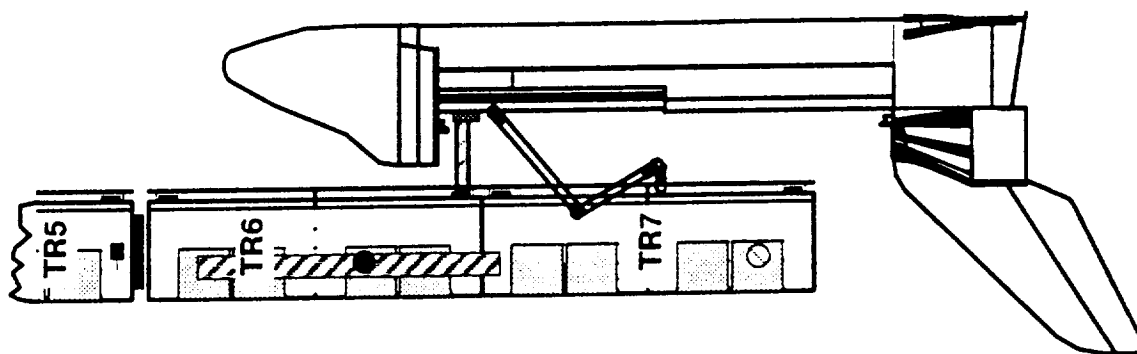
Mass to station = 26,626
Managers reserve = 3994
Additional Margin = 5358



TR7 Operations

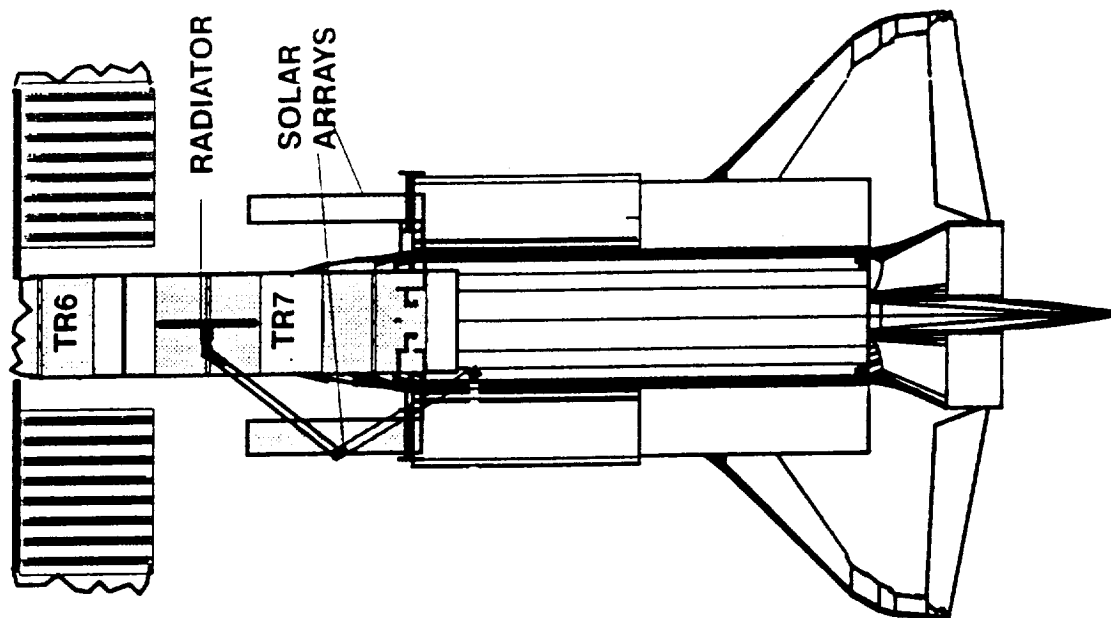
The operations involved in deploying and assembling the seventh integrated structural element of the space station can be approached from two directions. The first approach would involve using the station MT and MSC to translate the new section of integrated truss out to where it will be attached. The second approach involves flying the station in a gravity gradient mode and attaching the orbiter to the TR6 station element. The TR7 integrated structure is then removed from the orbiter cargo bay with the RMS and attached to TR6. The orbiter then detaches from TR6 and attaches to TR7. From this position the RMS removes and attaches internally stored appendages with EVA assistance.

Truss Flight Seven Operations



STEPS 1 TO 3

- 1) Berth to TR6.
- 2) Remove TR7 from cargo bay and rotate.
- 3) Berth TR7 to TR6. EVA secure TR7 to TR6.
- 4) Release from TR6 then berth to end of TR7
- 5) Remove radiator and solar arrays from structure and place in cargo bay.
- 6) Attach radiator to IEA manifold and deploy.
- 7) Attach solar arrays to beta joints.
- 8) Check out systems, separate and deploy solar arrays.



STEPS 4 TO 8

TR7 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the seventh truss section flight are listed. The overall C.G. location for the combined payload is 0.6 inches within allowable limits. There is 5358 pounds of unused STS lift capability and 3994 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 14
TR-7
STS
ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
IEA	12144			CON#1&2	1146
SOLAR ARRAYS	3636	363		TUBE	882
BETA GIMBALS	882			CON#4	810
RADIATOR (DEPLOYABLE)	1104	136		TUBE	840
STRUCTURE	8260		1100		1014
UTILITIES	600				1014
	26626	499		1100	
HARDWARE	26626				
15% RESERVE	3994				
FSE	499				
ATTACH FITTINGS	1100				
EVA RESERVE	2873				
DOCKING FIXTURE	1550				
SUBTOTAL	36642			CG LOCATION	1001.9
MARGIN	5358			CG MARGIN	0.6
STS CAPABILITY TO 190 NMI	42000			ALLOWABLE CG LIMIT	1001.3

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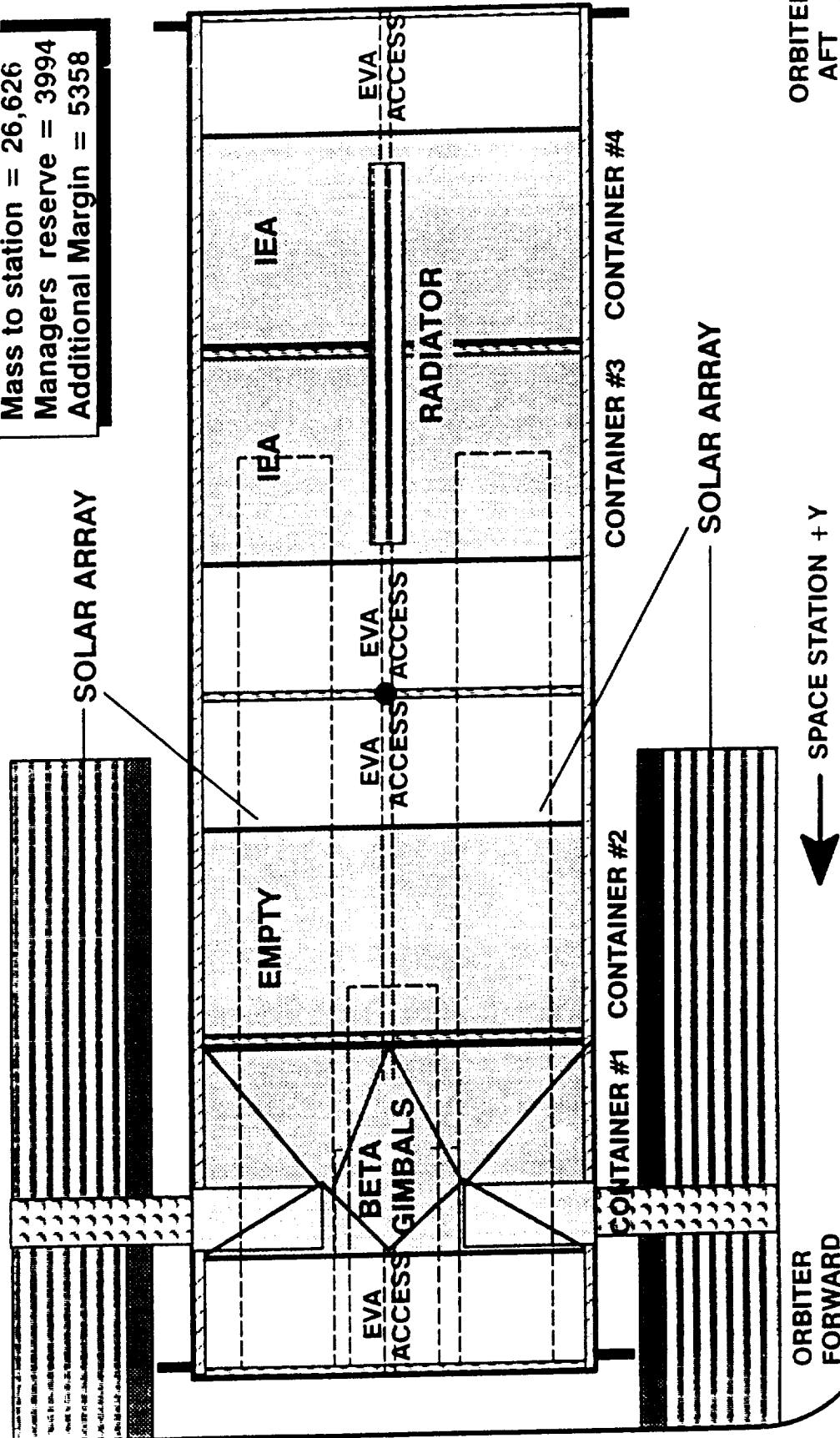
TR8 Packaging

The eighth truss structure flight brings up the outer starboard power system elements. All elements required to produce 18.75 KW of power are included on this flight. The Integrated Equipment Assembly (IEA) is packaged in two container sections at one end of the integrated structure. The PV array beta gimbals are located in container section one. Packaged internally are two PV arrays and the deployable radiator.

Pre-Integrated Structure Packaging

TR-8

Mass to station = 26,626
Managers reserve = 3994
Additional Margin = 5358



ORBITER
AFT

← SPACE STATION + Y

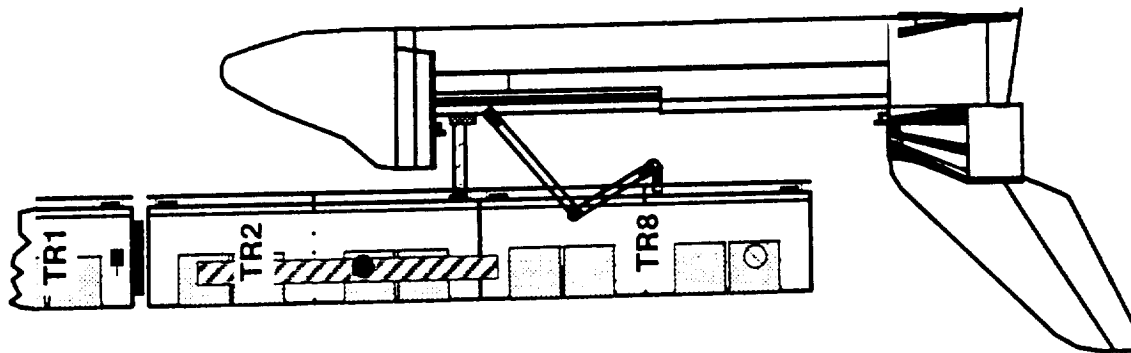
ORBITER
FORWARD

LaRC SSFO

TR8 Operations

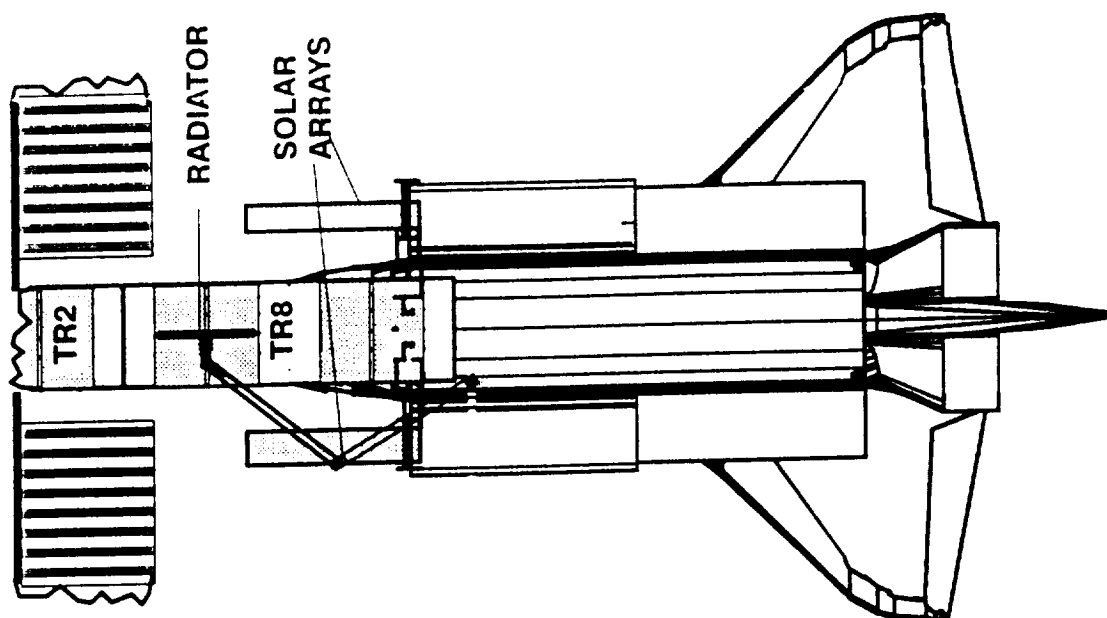
The operations involved in deploying and assembling the eighth integrated structural element of the space station can be approached from two directions. The first approach would involve using the station MT and MSC to translate the new section of integrated truss out to where it will be attached. The second approach involves flying the station in a gravity gradient mode and attaching the orbiter to the TR2 station element. The TR8 integrated structure is then removed from the orbiter cargo bay with the RMS and attached to TR2. The orbiter then detaches from TR2 and attaches to TR8. From this position the RMS removes and attaches internally stored appendages with EVA assistance.

Truss Flight Eight Operations



STEPS 1 TO 3

- 1) Berth to TR2.
- 2) Remove TR8 from cargo bay and rotate.
- 3) Berth TR8 to TR2. EVA secure TR8 to TR2.
- 4) Release from TR2 then berth to end of TR8
- 5) Remove radiator and solar arrays from structure and place in cargo bay.
- 6) Attach radiator to IEA manifold and deploy.
- 7) Attach solar arrays to beta joints.
- 8) Check out systems, separate and deploy solar arrays.



STEPS 4 TO 8

TR8 Manifest

The assembly elements, weights, associated FSE and C.G. locations for the eighth truss section flight are listed. The overall C.G. location for the combined payload is 0.6 inches within allowable limits. There is 5358 pounds of unused STS lift capability and 3994 pounds of managers reserve available.



NASA

FREEDOM

Integrated Assembly Sequence Manifest

FLIGHT 15

TR-8

STS

ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
IEA	12144			CON#3&4	1146
SOLAR ARRAYS	3636	363		TUBE	882
BETA GIMBALS	882			CON#1	810
RADIATOR (DEPLOYABLE)	1104	136		TUBE	840
STRUCTURE	8260		1100		1014
UTILITIES	600				1014

26626 499 1100

HARDWARE

15% RESERVE

FSE

ATTACH FITTINGS

EVA RESERVE

DOCKING FIXTURE

SUBTOTAL

MARGIN

36642	CG LOCATION	1001.9
5358	CG MARGIN	0.6

STS CAPABILITY TO 190 NMI

42000	ALLOWABLE CG LIMIT	1001.3
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LaRC SSFO

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MOD 7 Manifest

The assembly elements, weights, associated PSE and C.G. locations for the seventh module flight are listed. The overall C.G. location for the combined payload is 3.1 inches within allowable limits. All STS lift capability is used but 1716 pounds of managers reserve is available.

Integrated Assembly Sequence Manifest

FLIGHT 16
MOD-7
STS
ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
JEM MODULE	33240	435	1100		1042.1
DDCU'S & HT	1086				1234.9
	34326	435	1100		
HARDWARE	34326				
5% RESERVE	1716				
FSE	435				
ATTACH FITTINGS	1100				
MSC WORKSTATION	80				
EVA RESERVE	2873				
DOCKING FIXTURE	1550				
	42080		CG LOCATION		1019.5
SUBTOTAL	-80		CG MARGIN		3.1
MARGIN			ALLOWABLE CG LIMIT		1016.4
STS CAPABILITY TO 190 NMI	42000				

MOD 8 Manifest

The assembly elements, weights, associated PSE and C.G. locations for the eighth module flight are listed. The overall C.G. location for the combined payload is 3.1 inches within allowable limits. All STS lift capability is used but 1716 pounds of managers reserve is available.

Integrated Assembly Sequence Manifest

FLIGHT 17

MOD-8

STS

ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
ESA MODULE	33240	435	1100		1042
DDCU'S & HT	1086				1239.5
	34326	435	1100		
HARDWARE	34326				
5% RESERVE	1716				
FSE	435				
ATTACH FITTINGS	1100				
MSC WORKSTATION	80				
EVA RESERVE	2873				
DOCKING FIXTURE	1550				
SUBTOTAL	42080		CG LOCATION		1019.5
MARGIN	-80		CG MARGIN		3.1
STS CAPABILITY TO 190 NMI	42000		ALLOWABLE CG LIMIT		1016.4

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MOD 9 Manifest

The assembly elements, weights, associated PSE and C.G. locations for the ninth module flight are listed. The overall C.G. location for the combined payload is 2.1 inches within allowable limits. There are 11611 pounds of unused STS lift capability and 1034 pounds of managers reserve available.

Integrated Assembly Sequence Manifest

FLIGHT 18

MOD-9

STS

ELEMENT

	MASS	FSE	ATTACH	LOCATION	CG
JEM ELM PS	10194		1100		1186.7
JEM ELM ES	1686		880		1049.9
EXPOSED FACILITY #1	4989		1100		916.4
EXPOSED FACILITY #2	3803		1100		814.1
	20672	0	4180		
HARDWARE	20672				
5% RESERVE	1034				
FSE	0				
ATTACH FITTINGS	4180				
MSC WORKSTATION	80				
EVA RESERVE	2873				
DOCKING FIXTURE	1550				
SUBTOTAL	30389		CG LOCATION		994.4
MARGIN	11611		CG MARGIN		2.1
STS CAPABILITY TO 190 NMI	42000		ALLOWABLE CG LIMIT		992.3

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Assembly Sequence Weight Comparison

A weight comparison between the baseline space station assembly sequence and the integrated space station assembly sequence is given. The weight given for the transverse boom structure for the baseline includes all the truss work and station interface adapters for a total of 11,700 pounds. The equivalent transverse boom structure for the integrated station is made up of eight 44' hybrid isogrid sections yielding a weight of 66,000 pounds. The total spacecraft weight for the baseline station including all systems, structure and modules is 490,200 pounds. The equivalent weight for the integrated station is 537,600 pounds with the increase in weight coming from the additional structural weight of the transverse boom. Total Flight Support Equipment (FSE) and attach fittings for the baseline assembly sequence totals 107,050 pounds over the 18 assembly flights. This includes four outfitting flights using 10,000 pound logistics modules as module rack carriers. The integrated assembly sequence requires 37,900 pounds of FSE/attach fittings for the equivalent on orbit functionality. The ratio of on orbit station mass to FSE/attach fittings for the baseline sequence is 4.5 while the corresponding ratio for the integrated sequence is 14.1 indicating a gain in efficiency in manifesting and packaging. Total weight to orbit for the 18 assembly flights is 597,250 for the baseline sequence and 575,500 for the integrated sequence with the difference in weight corresponding to extra weight margin for the integrated sequence.

Assembly Sequence Weight Comparison

	<u>BASELINE</u>	<u>INTEGRATED ASSEMBLY</u>
Transverse Boom Structure	11,700	66,000
Total Spacecraft	490,200	537,600
FSE / Attach Fittings	107,050	37,900
Total Weight to Orbit (excludes EVA reserve, manager reserve, docking module & FTS workstation)	<u>597,250</u>	<u>575,500</u>

A 70,000 pound reduction in flight support equipment and attach fittings enables more weight to be allocated to on orbit station weight thus increasing the efficiency of the assembly sequence.

All totals and weights based on 18 module/truss assembly flights. No logistics flights are included. Weights are in pounds.

Assembly Sequence Margin Comparison

A comparison of Center of Gravity (C.G.), weight, reserve, EVA and volume margins between the baseline and integrated assembly sequences was made. Both sequences had positive C.G. margins but on average the integrated sequence had a larger C.G. margin. The weight margin (unused STS lift capability) on the baseline sequence is negative on two flights with a total 18 flight margin of 36,026 pounds. The integrated sequence has no negative margins allowing a total 18 flight margin of 47,460 pounds. The baseline sequence consistently used a five percent managers reserve on each flight resulting in an 18 flight total of 26,359 pounds. The integrated sequence used a fifteen percent reserve on truss flights and a five percent reserve on module flights resulting in an 18 flight total of 49,810 pounds. The baseline sequence has several flights where EVA and volume limits are exceeded while the integrated sequence always stays within EVA and volume margins by virtue of being pre-integrated in a fixed volume.

Assembly Sequence Margin Comparison

Flight Number	C.G. Margin (in)		Weight Margin		Mngrs Reserve		EVA Margin		Volume Margin	
	B	I	B	I	B	I	B	I	B	I
1	8	14	1731	1077	1482	4544	-	+	+	+
2	2	11	2189	4270	878	4136	-	+	-	+
3	8	1	3160	2011	1335	4401	-	+	-	+
4	8	14	399	999	1480	4531	+	+	-	+
5	8	26	956	3045	1113	4288	-	+	-	+
6	8	11	250	4270	1371	4136	+	+	-	+
7	2	41	999	134	1665	1677	+	+	+	+
8	40	1	5508	768	1492	1547	+	+	-	+
9	2	42	2291	54	1556	1677	+	+	+	+
10	2	63	-1403	2773	1779	1589	+	+	+	+
11	2	61	-915	2773	1625	1589	+	+	-	+
12	2	63	702	2773	1595	1589	+	+	-	+
13	2	33	0	106	1685	1652	-	+	+	+
14	2	1	0	5358	1716	3994	+	+	+	+
15	2	1	0	5358	1716	3994	+	+	+	+
16	2	3	11691	0	1034	1716	+	+	+	+
17	8	3	3182	0	1446	1716	-	+	-	+
18	8	2	5286	11691	1391	1034	-	+	-	+
Totals			36,026	47,460	26,359	49,810				

B = Baseline, I = Integrated Assembly, Weights in pounds.

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Potential Available Margin for Weight Growth

The preliminary nature of this study dictated that conservative estimates be used in planning and manifesting the assembly sequence. There is potentially over 125,000 pounds of weight margin built into the assembly sequence to accommodate weight growth due to design maturity and overlooked hardware. 47,460 pounds of this margin is available via unused orbiter lift capability. Another 49,810 pounds was set aside as "managers reserve" in the manifests. The manifest used an 8260 pound weight for the isogrid structure when in fact the actual estimate was just under 6000 pounds resulting in 18,336 pounds of isogrid structure margin over eight assembly flights. The weight estimates for the integrated subsystems did not exclude structure such as universal pallets designed to absorb orbiter loads. Since the isogrid structure will be used to carry the orbiter loads, about 12,000 pounds of secondary structure can be deleted from the subsystem weights.

Potential Available Margin for Weight Growth

Flight Margin	=	47,460
Managers Reserve	=	49,810
Structure Margin	=	18,336
Universal Pallets	=	12,000
Total Potential Margin	=	<u>127,606</u>

Assembly Sequence Comparison

Additional comparisons of the two sequences are given. Both sequences have the same number of flights to MTC and AC. As was stated earlier, the 14 flights it takes to achieve PMC for the integrated sequence could be reduced by one flight if the additional module rack volume is initially utilized for logistics instead of payloads. The baseline requires one less "truss" flight and one more "module" flight to AC as compared to the integrated sequence for a total of 18 flights. The length of the transverse boom is reduced by about 21 meters for the integrated station and would require an additional "truss" flight to get closer to the baseline dimension. The integrated sequence has 104 module racks on orbit by PMC where the baseline sequence has just 80 modules racks at AC. These extra racks can be used to eliminate the first logistics flight as described earlier. Both sequences achieve 37.5 KW capability at flight 6 while 75 KW is achieved at flight 14 for the baseline and flight 15 for the integrated sequence.

Assembly Sequence Comparison

	<u>BASELINE</u>	<u>INTEGRATED ASSEMBLY</u>
Flights to MTC	7	7
Flights to PMC	13	14
Flights to AC	18	18
"Truss" Flights	7.5	8.5
"Module" Flights	10.5	9.5
"Alpha to Alpha"	75 m	54 m
U.S. Racks at AC	80	104
37.5 kW Power	6	6
75 kW Power	14	15

Assembly Sequence Summary

The primary purpose of looking at the design and assembly of a pre-integrated space station was to reduce the amount of on orbit integration and EVA as compared to current baseline space station concept. The number of assembly flights and weight of the station were of secondary importance but it appears that the integrated approach can maintain the baseline number of flights to assembly complete while improving EVA, weight, volume and C.G. margins. The large reduction in FSE and attach fittings yield extra weight margin that can be used for future system weight growth. The integrated approach allows an active spacecraft after the first assembly flight while the baseline design does not go active till the third assembly flight.

Assembly Sequence Summary

- The integrated approach can maintain the baseline number of flights to assembly complete while improving EVA, weight and C.G. margins.
- The integrated approach reduces the sensitivity of the assembly sequence to weight variations.

Growth Issues

Several issues associated with growing the integrated space station have been identified. The ability of the alpha joint to handle the extra weight associated with the integrated structure and growth power systems must be evaluated. The interfaces between the isogrid structure and growth structure must be developed. Growing the radiators in the +X direction is complicated by the pre-integrated nature of the beta joint and possible interference with the growth module pattern.. Addition of new utilities and where they will go is another growth issue that needs to be addressed. Some equipment initially located on the transverse boom (such as the C&T system) will be required to be moved to the upper boom. The relocation of these pre-integrated systems requires further study.

Growth Issues

- SARJ structural and power load limitations
- Isogrid / 5M Erectable Truss structural interfaces
- Restriction of forward TCS radiator growth in 6 module +/-Y option
- Augmentation of subsystem lines on orbit vs. AC growth scars
- Distribution of utilities to growth modules
- Relocation of C&T pallet to upper keel

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Summary and Recommendations

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Summary and Recommendations

The pre-integrated isogrid structural concept that was evaluated appears to be technically feasible. Although heavier than erectable truss, the isogrid structure is sized to withstand launch loads fully integrated, thus eliminating or reducing on-orbit integration and EVA requirements. However, additional detailed studies in the areas of structural design and configurations (including non-isogrid structures), assembly, and on-orbit operations must be conducted prior to a finalization of technical results and recommendations.

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16. Abstract An in-space construction (erectable) approach to assembling Freedom is planned but the increasing complexity of the station's design along with a decrease in shuttle capability over the past several years has led to an assembly sequence that requires more resources (EVA, lift, volume, etc.) than the shuttle can provide given a fixed number of flights. One way to address these issues is to adopt a "pre-integrated" approach to assembling Freedom. A pre-integrated approach combines station primary structure and distributed systems into discrete sections that are assembled and checked out on the ground. The section is then launched as a single structural entity on the shuttle and attached to the orbiting station with a minimum of EVA. This report discusses the feasibility of a pre-integrated approach to assembling Freedom. The structural configuration, packaging and shuttle integration of discrete pre-integrated elements for Freedom assembly are discussed. It is shown that the pre-integrated approach to assembly reduces EVA and increases shuttle margin with respect to mass, volume and center of gravity limits when compared to the baseline Freedom assembly sequence.					
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